



# B.TECH ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING REGULATION – 2021 CHOICE BASED CREDIT SYSTEM I - VIII SEMESTERS CURRICULA AND SYLLABI



You Choose, We Do It **St. JOSEPH'S COLLEGE OF ENGINEERING** (An Autonomous Institution) **St. Joseph's Group of Institutions** Jeppiaar Educational Trust OMR, Chennai - 119.





## B.TECH ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING REGULATION - 2021 CHOICE BASED CREDIT SYSTEM I TO VIII SEMESTERS CURRICULAM AND COMPARISION

## **PROGRAM EDUCATIONAL OBJECTIVES (PEOs)**

**PEO-1:** To demonstrate technical skills, competency in fundamentals of Mathematics, Programming and Artificial Intelligence in modelling, designing and conducting of experiments to provide solutions for industry's complex technological problems.

**PEO-2:** To enrich graduates with creativity that applies the concepts of Machine Learning to create, build and deploy solutions for various business problems

**PEO-3:** To build graduates with potential and ability to engage in continuous professional development and life-long learning.

**PEO-4:** To train graduates to work in multi-disciplinary teams with superior work ethics and build innovative solutions to serve the needs of the society.

**PEO-5:** To enable graduates to research, design and implement AI/ML products and services with effective Communication and Entrepreneurial Skills.

## PROGRAM OUTCOMES POs:

#### Engineering Graduates will be able to:

- **1. Engineering knowledge:** Apply the knowledge of mathematics, science, engineering fundamentals and an engineering specialization to the solution of complex engineering problems.
- **2. Problem analysis:** Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- 3. Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate

consideration for the public health and safety, and the cultural, societal, and environmental considerations.

- 4. Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- **5. Modern tool usage:** Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.
- 6. The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- **7. Environment and sustainability:** Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- **8. Ethics:** Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- **9.** Individual and team work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- **10. Communication:** Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
- **11. Project management and finance:** Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
- **12. Life-long learning:** Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

## Programme Specific Outcomes (PSO)

**PSO-1:** Graduates should be able to acquire and apply practical competency with engineering knowledge in the field of artificial intelligence for efficient design of intelligent systems of varying complexity.

**PSO-2:** Graduates should be able to contribute constructive ideas and innovative Machine learning solutions for multi-disciplinary problems

**PSO-3:** Graduates should be able to build systems by applying AI/ML methods, techniques and tools for solving engineering problems.

## MAPPING OF PROGRAMME EDUCATIONAL OBJECTIVES WITH PROGRAMME OUTCOMES

AbroadrelationbetweentheProgrammeobjectiveandtheoutcomesisgiveninthefollowingtable

PROGRAMME EDUCATIONAL					PRC	GRA	MME	OUT		IES		
OBJECTIVES	Α	В	С	D	Е	F	G	Н	I	J	к	L
1	3	2										
2	3	2	1	1								1
3			3									3
4			2		1	2	2	1				
5				3		1		1	1	2	2	1

## MAPPING OF PROGRAM SPECIFIC OBJECTIVES WITH PROGRAMME OUTCOMES

Abroad relation between the Program Specific Objectives and the outcomes is given in the following table

PROGRAM SPECIFIC						ROGRAI OUTCON						
OBJECTIVES	Α	В	С	D	E	F	G	н	I	J	κ	L
1	3											
2		2	3			1						
3	1		2	1	2		1		1	1	1	

Contribution 1: Reasonable

2: Significant

3: Strong

YEAR	SEM	COURSE TITLE		F	PRO	GR	AM	OU	тсо	OME	ES (	PO	s)		F	PSO	s
			1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
		Communicative English								1	1	1		1	1	1	1
		Engineering Mathematics - I	1	1	1						1				1	1	1
		Engineering Physics	1	1	1										1	1	1
		Engineering Chemistry	1	1	1										1	1	1
	I	Problem Solving and Python Programming	1	1	1										1	~	1
		Engineering Graphics	1	1	1		1			1	1	1		1	1	1	1
		Python Programming Laboratory	1	1	1		1			1	1	1		1	1	1	1
		Physics and Chemistry Laboratory	1	1	1					1	1	1			1	1	1
I		Professional English								1	~	1		1	1	1	1
		Linear Algebra	1	✓	1						1				1	1	1
		Physics for Information Science	1	1	1										1	1	1
		Environmental Science and Engineering	1	1	1				1	1	1	1		1	1	1	1
	II	Basic Electrical, Electronics and Measurement Engineering	~	~	1										1	~	1
		Programming in C	1	1	1					1	1	1		1	1	1	1
		Engineering Practice Laboratory	1	1	1	1	1	1		~	1	-		1	~	1	~
		Programming in C Laboratory	1	1	1					1	1	1		1	1	1	1

(EAR	SEM	COURSE TITLE		F	PRO	GR	AM	OU	TCO	OME	ES (	PO	s)		F	PSO	s
			1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
		Probability and Bayesian Inference	1	1	1	~					1	1		1	1	1	~
		Data Structures	1	1	1	1	1	1							1	1	-
		Introduction to Artificial Intelligence	1	1	1	1	1					1	1	1	1	1	~
		Data Foundation	1	1	1	1	1					1	1	1	1	1	1
		Object Oriented Software Engineering (Lab Integrated)	1	1	1		1			1	~	1		1	1	1	-
		Optimization for Machine Learning	1	1	1	1					1	1		1	1	1	-
		Data Structures Laboratory using Python	1	1	1	1					1	1	~	1	1	1	-
11		Artificial Intelligence Laboratory	1	1	1	1	1			1	1	1		1	1	~	•
		Professional Skills Laboratory		<		1					1	1			1	1	•
		Discrete Mathematics and Graph Theory	1	1	1	1								1	1	1	•
		Design and Analysis of Algorithms	~	1	1	1	1				~		~	1	1	1	~
		Operating Systems	1	1	1	~	1					1	<	~	1	~	~
	IV	Database Design and Management (Lab Integrated)	1	1	1	1	1					1	1	1	1	1	-
		Foundations to Machine Learning	1	1	1	1	1	~	~			1	~	~	~	~	•
		Statistics for Machine Learning	1	1	1	1	1					1	1	1	1	1	•
		Operating Systems Laboratory	1	1	1	1	1					1	1	1	1	1	1
		Machine Learning Laboratory	1	1	1	1	1			1		-	1	1	1	1	-

	SEM	COURSE TITLE		F	PRO	GR	AM	OU	тсс	OME	ES (	POs	5)		F	°SO	s
	SEINI	COORSE IIILE	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
		Reinforcement Learning	1	✓	1	✓	1				✓	1	1	1	✓	1	•
		Advanced Artificial Intelligence Systems	~	1	~	~	1				1	1	1	1	1	1	•
		Nature Inspired Computing Techniques	1	1	1	~								1	1	1	•
	V	Web programming(Lab Integrated)	1	~	~		1				~		~	1	~	1	•
		Applied Reinforcement Laboratory	1	1	~	1	1			~	~	1		1	~	1	,
		Advanced Artificial Intelligence Laboratory	1	~	~	~	1			~	~	1		1	~	1	,
		Deep Learning	1	1	1	<						✓	<	1	✓	1	•
		Autonomous Mobile Robot		✓								✓	✓	1	✓	1	
		Probabilistic Graphical Models	1	1	1	✓	1					1	1	1	✓	1	
	VI	Big Data Analytics	1	1	1	~	1	1	<				~	1	1	1	
		Deep Learning Laboratory	1	✓	1	<	1	1			1	1	1	1	1	1	
		Socially relevant Project	1	1	1	1	1	1	1	1	1	1	1	1	1	1	
		Statistical Natural Language Processing	~	1	1	~	1			~				1	1	1	
		Formal Languages and Automata Theory	1	1	~	~	1			~		1	1	1	~	1	
	VII	Image Processing and Vision Techniques	1	~	~	~								1	>	1	
IV		Machine Intelligence for Network Sciences	1	1	1	<	1							1	~	1	
		Natural Language Processing Laboratory	~	~	~	~	1			~	~	~		1	~	~	
		Capstone Project-Phase1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	ſ
	VIII	Capstone Project-Phase2	~	1	1	~	1	~	~	1	1	1	1	1	1	~	

## MAPPING OF PROFESSIONAL ELECTIVES

YEAR	SEM	COURSE TITLE			RO	GRA	M		тсс						F	SO	-
	02		1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
		Advanced Databases	1	<b>\</b>	✓		✓					1	1	~		~	
		Semantic Web	✓	✓	✓	~	✓					1	1	1	✓	✓	1
	v	Advanced Data Structures	1	1	✓	1	1	1							1	✓	1
		Logic Programming	1	1	<	1	✓			1				1	1	1	1
		Application Of Machine Learning In Industries	1	1	~	~	1			1				1	1	1	1
111		Green Computing	1	~	1						1			1	1	~	1
		Game Programming	1	~	~	~								<ul> <li>Image: A start of the start of</li></ul>	1	~	1
	VI	Game Theory	1	1	1	✓								1	1	~	1
		Parallel And Distributed Computing	1	1	1	~	1			1	1	1	1	1	1	1	1
		Case Based Reasoning	1	1	✓	1							1	1	1	1	1
		AI for Clinical Information System	1	1	1	1	1					1	1	1	1	1	1
		AI In Healthcare	1	1	<	1	1					1	1	<	1	<	1
		Data Mining And Predictive Modelling	1	~	~	~	1		1			1	1	1	~	1	1
		Virtualization Techniques	1	1	1	1	1					1	1	1	✓	1	1
	VII	Augmented & Virtual Reality	1	1	✓	~					1	1	1	1	1	✓	✓
	vii	Genetic Algorithm	1	1	1	1	✓			1		1	1	1	1	1	1
		Speech Processing	1	1	1					1	1	1			1	✓	1
		Advanced Optimization Techniques		1	1	~									1	1	1
		Intelligent Transport Systems	1	1	1	1					1	1	1	1	1	✓	1
IV		Advanced Bio-Inspired Artificial Intelligence Techniques	1	>	~	>									>	1	1
		Video Analytics	1	1	✓	✓	✓			✓	1	1	1	✓	1	✓	✓
		Block chain Architecture Design	1	1	<b>√</b>	1					1	1			✓	✓	✓
		Microsoft Bots Framework	✓	1	✓	<b>√</b>								✓	1	✓	✓
		Business Intelligence	1	1	<b>√</b>	<b>√</b>						1	1	1	✓	✓	✓
	VIII	Supply Chain Management		1	✓	-									✓	<b>√</b>	✓
	V 111	Internet of Everything	1	1	<b>√</b>	1	✓					1	1	1	✓	<b>√</b>	✓
		Human Robot Interaction	1	1	<b>√</b>	1	<b>√</b>			✓				1	✓	✓	✓
		Agile Software Development	1	1	1	<b>√</b>						1	1	1	1	1	1
		Brain Computer Interface	1	1	✓	1								1	✓	✓	1
		Cognitive Systems	1	1	1	1	1					1	1	1	1	✓	1

## SEMESTER – I

S.No	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
		THEO	RY					
1	HS1101	Communicative English (Common for all branches of B.E. /B. Tech Programmes)	HSMC	3	3	0	0	3
2	MA1102	Engineering Mathematics – I (Common for all branches of B.E. /B. Tech Programmes)	BSC	4	4	0	0	4
3	PH1103	Engineering Physics (Common for all branches of B.E. /B. Tech Programmes)	BSC	3	3	0	0	3
4	CY1104	Engineering Chemistry (Common for all branches of B.E. /B. Tech Programmes)	BSC	3	3	0	0	3
5	GE1105	Problem Solving and Python Programming (Common for all branches of B.E. /B. Tech Programmes)	ESC	4	3	1	0	3
6	GE1106	Engineering Graphics (Common for all branches of B.E. /B. Tech Programmes)	ESC	5	1	0	4	4
		PRACTIC	CALS					
7	GE1107	Python Programming Laboratory <b>(Common for all branches of B.E. /B. Tech Programmes)</b>	ESC	4	0	0	4	2
8	BS1108	Physics and Chemistry Laboratory (Common for all branches of B.E. /B. Tech Programmes)	BSC	4	0	0	4	2
		Total		30	17	1	12	24

## SEMESTER – II

S.N o	COURSE CODE	COURSE TITLE	CATEGOR Y	CONTACT PERIODS	L	т	Ρ	С
		THEOF	RY					
1	HS1201	Professional English (Common for all branches of B.E. /B. Tech Programmes)	HSMC	3	3	0	0	3
2	MA1251	Linear Algebra (Common to AI-DS)	BSC	4	4	0	0	4
3	PH1252	Physics for Information Science (Common to CSE, AI-DS & IT )	BSC	3	3	0	0	3
4	GE1204	Environmental Science and Engineering (Common for all branches of B.E. /B. Tech Programmes)	HSMC	3	3	0	0	3
5	BE1251	Basic Electrical Electronics and Measurement Engineering (Common to CSE, AI-DS & IT )	ESC	3	3	0	0	3
6	CS1206	Programming C (Common to CSE, AI-DS & IT )	PCC	4	3	1	0	3
		PRACTIC	ALS					
7	GE1207	Engineering Practices Laboratory (Common for all branches of B.E. /B. Tech Programmes)	ESC	4	0	0	4	2
8	CS1208	Programming in C Laboratory (Common to CSE, AI-DS & IT )	PCC	4	0	0	4	2
		Total		28	19	1	8	23

#### SEMESTER - III

S.No	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
		ТН	EORY					
1	MA1354	Probability and Bayesian Inference	BSC	4	4	0	0	4
2	CS1302	Data Structures (Common to CSE, AI-DS & IT )	PCC	4	3	1	0	3
3	DS1303	Introduction to Artificial Intelligence ( Common to AI-DS )	PCC	3	3	0	0	3
4	ML1301	Data Foundation	PCC	3	3	0	0	3
5	ML1302	Object Oriented Software Engineering (Lab Integrated)	PCC	5	3	0	2	4
6	ML 1303	Optimization for Machine Learning	PCC	3	3	0	0	3
		PRA	CTICAL			-		
7	DS1307	Data Structures Laboratory using Python ( Common to AI-DS )	PCC	4	0	0	4	2
8	DS1308	Artificial Intelligence Laboratory ( Common to AI-DS )	PCC	4	0	0	4	2
9	HS1310	Professional Skills Laboratory ( Common to IT )	HSMC	2	0	0	2	1
		Total		32	19	1	12	25

## SEMESTER - IV

SI. No	COURS E CODE	COURSE TITLE	CATEGOR Y	CONTAC T PERIODS	L	т	Ρ	с
		THEC	DRY					
1	MA1454	Discrete Mathematics and Graph Theory	BSC	4	4	0	0	4
2	CS1401	Design and Analysis of Algorithm (Common to CSE, Al-DS & IT )	PCC	3	3	0	0	3
3	CS1402	Operating Systems (Common to CSE, AI-DS & IT )	PCC	3	3	0	0	3
4	CS1403	Database Design and Management (Lab Integrated) (Common to CSE, AI-DS & IT)	PCC	5	3	0	2	4
5	ML1401	Foundations of Machine Learning (Common to AI-DS & IT )	PCC	3	3	0	0	3
6	ML1402	Statistics for Machine Learning	PCC	3	3	0	0	3
		PRACI	<b>FICAL</b>					
7	CS1407	Operating Systems Laboratory (Common to CSE & IT)	PCC	4	0	0	4	2
8	ML1408	Machine Learning Laboratory (Common to AI-DS & IT)	PCC	4	0	0	4	2
		Total		29	19	0	10	24

SEMESTER - \	/
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SI. No.	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
		THE	EORY					
1	ML1501	Reinforcement Learning	PCC	4	3	1	0	3
2	DS1502	Advanced Artificial Intelligence Systems (Common to AI-DS)	PCC	4	3	1	0	3
3	ML1502	Nature Inspired Computing Techniques	PCC	4	3	1	0	3
4	ML1503	Web programming (Lab Integrated)	PCC	5	3	0	2	4
5		Open Elective-I	OEC	3	3	0	0	3
6		Professional Elective - I	PEC	3	3	0	0	3
		PRAC	CTICAL					
7	ML1507	Applied Reinforcement Laboratory	PCC	4	0	0	4	2
8	DS1508	Advanced Artificial Intelligence Laboratory (Common to AI-DS)	PCC	4	0	0	4	2
		31	18	3	10	23		
10	O         Value Added Course         Audit Course			Two	Neek	S		1

## SEMESTER – VI

SI. No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Р	с
		THEC	DRY					
1	ML1601	Deep Learning	PCC	4	3	1	0	3
2	ML1602	Autonomous Mobile Robot	PCC	4	3	1	0	3
3	ML1603	Probabilistic Graphical Models	PCC	4	3	1	0	3
4	ML1604	Big Data Analytics	PCC	4	3	1	0	3
5		Open Elective-II	OEC	3	3	0	0	3
6		Professional Elective-II	PEC	3	3	0	0	3
		PRACT	ICAL					
7	ML1607	Deep Learning Laboratory	PCC	4	0	0	4	2
8	ML1608	Socially relevant Project	EEC	4	0	0	4	2
	Total			31	18	3	10	22
9		Audit Course (Optional)	AC					

#### SEMESTER - VII

SI. No.	COURS E CODE	COURSE TITLE	CATEGOR Y	CONTACT PERIODS	L	т	Ρ	с
		THE	ORY					
1	ML1701	Statistical Natural Language Processing	PCC	4	3	1	0	3
2	ML1702	Formal Languages and Automata Theory	PCC	4	4	0	0	4
3	ML1703	Image Processing and Vision Techniques	PCC	4	3	1	0	3
4	ML1704	Machine Intelligence for Network Sciences	PCC	4	3	1	0	3
5		Professional Elective-III	PEC	3	3	0	0	3
6		Professional Elective-IV	PEC	3	3	0	0	3
		PRACT	ICALS					
7	ML1707	Natural Language Processing Laboratory	PCC	4	0	0	4	2
8	ML1708	Capstone Project-Phase1	EEC	4	0	0	4	2
	Total			30	18	4	8	23

## SEMESTER - VIII

SI. No.	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
THEORY								
1		Professional Elective-V	PEC	3	3	0	0	3
2		Professional Elective-VI	PEC	3	3	0	0	3
		PRA	CTICALS					
3	ML1807	Capstone Project-Phase2	EEC	20	0	0	20	10
	Total				6	0	20	16

**Total Credits: 180** 

## HUMANITICS SCIENCE AND MANAGEMENT COURSES (HSMC)

S.No	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	HS1101	Communicative English	HSMC	3	3	0	0	3
2	HS1201	Professional English	HSMC	3	3	0	0	3
3	GE1204	Environmental Science and Engineering	HSMC	3	3	0	0	3
4	HS1310	Professional Skills Laboratory	HSMC	2	0	0	2	1

## **BASIC SCIENCE COURSES (BSC)**

S.No	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
1	MA1102	Engineering Mathematics - I	BSC	4	4	0	0	4
2	PH1103	Engineering Physics	BSC	3	3	0	0	3
3	CY1104	Engineering Chemistry	BSC	3	3	0	0	3
4	BS1108	Physics and Chemistry Laboratory	BSC	4	0	0	4	2
5	MA1251	Linear Algebra	BSC	4	4	0	0	4
6	PH1252	Physics for Information Science	BSC	3	3	0	0	3
7	MA1354	Probability and Bayesian Inference	BSC	4	4	0	0	4
8	MA1454	Discrete Mathematics and Graph Theory	BSC	4	4	0	0	4

## ENGINEERING SCIENCE COURSES (ESC)

S.No	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	GE1105	Problem Solving and Python Programming	ESC	4	3	1	0	3
2	GE1106	Engineering Graphics	ESC	5	1	0	4	4
3	GE1107	Python Programming Laboratory	ESC	4	0	0	4	2
4	BE1205	Basic Electrical and Electronics Engineering	ESC	3	3	0	0	3
5	GE1207	Engineering Practice Lab	ESC	4	0	0	4	2

## PROFESSIONAL CORE COURSES (PCC)

S.No	COURS E CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Р	с
1	CS1206	Programming in C	PCC	4	3	1	0	3
2	CS1208	Programming in C Lab	PCC	4	0	0	4	2
3	CS1302	Data Structures	PCC	4	3	1	0	3
4	DS1303	Introduction to Artificial Intelligence	PCC	3	3	0	0	3
5	ML1301	Data Foundation	PCC	3	3	0	0	3
6	ML1302	Object Oriented Software Engineering (Lab Integrated)	PCC	5	3	0	2	4
7	ML 1303	Optimization for Machine Learning	PCC	3	3	0	0	3
8	DS1307	Data Structures Laboratory using Python	PCC	4	0	0	4	2
9	DS1308	Artificial Intelligence Laboratory	PCC	4	0	0	4	2
10	CS1401	Design and Analysis of Algorithms	PCC	3	3	0	0	3
11	CS1402	Operating Systems	PCC	3	3	0	0	3
12	CS1403	Database Design and Management (Lab Integrated)	PCC	5	3	0	2	4
13	ML1401	Foundations to Machine Learning	PCC	3	3	0	0	3
14	ML1402	Statistics for Machine Learning	PCC	3	3	0	0	3
15	CS1407	Operating Systems Laboratory	PCC	4	0	0	4	2
16	DS1408	Machine Learning Laboratory	PCC	4	0	0	4	2
17	ML1501	Reinforcement Learning	PCC	4	3	1	0	3
18	DS1502	Advanced Artificial Intelligence Systems	PCC	4	3	1	0	3
19	ML1502	Nature Inspired Computing Techniques	PCC	4	3	1	0	3
20	ML1503	Web programming(Lab Integrated)	PCC	5	3	0	2	4
21	ML1507	Applied Reinforcement Laboratory	PCC	4	0	0	4	2

22	DS1508	Advanced Artificial Intelligence Laboratory	PCC	4	0	0	4	2
23	ML1601	Deep Learning	PCC	4	3	1	0	3
24	ML1602	Autonomous Mobile Robot	PCC	4	3	1	0	3
25	ML1603	Probabilistic Graphical Models	PCC	4	3	1	0	3
26	ML1604	Big Data Analytics	PCC	4	3	1	0	3
27	ML1607	Deep Learning Laboratory	PCC	4	0	0	4	2
28	IT1701	Statistical Natural Language Processing	PCC	4	3	1	0	3
29	ML1701	Formal Languages and Automata Theory	PCC	4	4	0	0	4
30	ML1702	Content Based Image And Video Retrieval	PCC	4	3	1	0	3
31	ML1703	Machine Intelligence for Network Sciences	PCC	4	3	1	0	3
32	ML1707	Natural Language Processing Laboratory	PCC	4	0	0	4	2

## PROFESSIONAL ELECTIVE COURSES (PEC) PROFESSIONAL ELECTIVE – I (V)

SI. No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	ML1511	Advanced Databases	PEC	3	3	0	0	3
2	ML1512	Semantic Web	PEC	3	3	0	0	3
3	ML1513	Advanced Data Structures	PEC	3	3	0	0	3
4	ML1514	Logic Programming	PEC	3	3	0	0	3
5	ML1515	Application Of Machine Learning In Industries	PEC	3	3	0	0	3

## PROFESSIONAL ELECTIVE - II (SEMESTER VI)

S.No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	с
1	ML1611	Green Computing	PEC	3	3	0	0	3
2	ML1612	Game Programming	PEC	3	3	0	0	3
3	ML1613	Game Theory	PEC	3	3	0	0	3
4	ML1614	Parallel And Distributed Computing	PEC	3	3	0	0	3
5	ML1615	Case Based Reasoning	PEC	3	3	0	0	3

## PROFESSIONAL ELECTIVE - III (SEMESTER VII)

SI. No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	ML1711	AI for Clinical Information System	PEC	3	3	0	0	3
2	ML1712	AI In Healthcare	PEC	3	3	0	0	3
3	ML1713	Data Mining And Predictive Modelling	PEC	3	3	0	0	3
4	CS1712	Virtualization Techniques	PEC	3	3	0	0	3
5	IT1715	Augmented & Virtual Reality	PEC	3	3	0	0	3

## PROFESSIONAL ELECTIVE - IV (SEMESTER VII)

SI. No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	ML1721	Genetic Algorithm	PEC	3	3	0	0	3
2	ML1722	Speech Processing	PEC	3	3	0	0	3
3	ML1723	Advanced Optimization Techniques	PEC	3	3	0	0	3
4	ML1724	Intelligent Transport Systems	PEC	3	3	0	0	3
5	ML1725	Advanced Bio-Inspired Artificial Intelligence Techniques	PEC	3	3	0	0	3

## PROFESSIONAL ELECTIVE - V (SEMESTER VIII)

S.No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Р	с
1	ML1811	Video Analytics	PEC	3	3	0	0	3
2	ML1812	Block chain Architecture Design	PEC	3	3	0	0	3
3	ML1813	Microsoft Bots Framework	PEC	3	3	0	0	3
4	ML1814	Business Intelligence	PEC	3	3	0	0	3
5	MG1815	Supply Chain Management	PEC	3	3	0	0	3

## PROFESSIONAL ELECTIVE - VI (SEMESTER VIII)

S.No.	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	Т	Ρ	с
1	ML1821	Internet of Everything	PEC	3	3	0	0	3
2	ML1822	Human Robot Interaction	PEC	3	3	0	0	3
3	ML1823	Agile Software Development	PEC	3	3	0	0	3
4	ML1824	Brain Computer Interface	PEC	3	3	0	0	3
5	DS1821	Cognitive Systems	PEC	3	3	0	0	3

#### OPEN ELECTIVE COURSES - I & II

S.No	COURSE CODE	COURSE TITLE	CATEGORY	CONTACT PERIODS	L	т	Ρ	С
1	OBT101	Industrial Biotechnology	OEC	3	3	0	0	3
2	OBT104	Biosensors	OEC	3	3	0	0	3
3	OBT105	Introduction To Nanoscience And Nanotechnology	OEC	3	3	0	0	3
4	OCE102	Introduction To Geographic Information System	OEC	3	3	0	0	3
5	OCH101	Hospital Management	OEC	3	3	0	0	3
6	OEC103	Basics of Embedded Systems and IoT	OEC	3	3	0	0	3
7	OEE101	Basic Circuit Theory	OEC	3	3	0	0	3
8	OEE103	Introduction To Renewable Energy Systems	OEC	3	3	0	0	3
9	OEI102	Robotics	OEC	3	3	0	0	3
10	OMB101	Total Quality Management	OEC	3	3	0	0	3
11	OME104	Industrial Safety Engineering	OEC	3	3	0	0	3

## EMPLOYABILITY ENHANCEMENT COURSES (EEC)

S.No	COURS E CODE	COURSE TITLE	CATEGOR Y	CONTACT PERIODS	L	т	Ρ	С
1	ML1608	Socially relevant Project	EEC	4	0	0	4	2
2	ML1708	Capstone Project-Phase1	EEC	4	0	0	4	2
3	ML1807	Capstone Project-Phase2	EEC	20	0	0	20	10

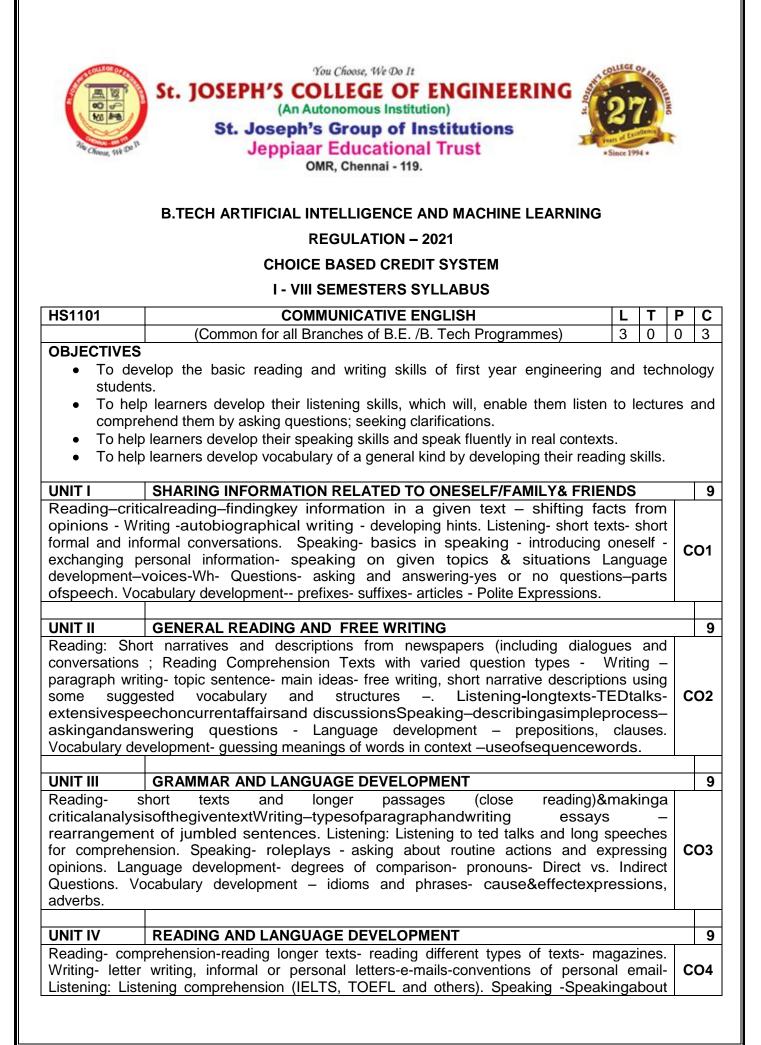
## AUDIT COURSES (AC)

SI. No.	Course Code	Subject Name	Category	Contact Periods	L	т	Ρ	С
1	AD1001	Constitution of India	AC	2	2	0	0	0
2	AD1002	Value Education	AC	2	2	0	0	0
3	AD1003	Pedagogy Studies	AC	2	2	0	0	0
4	AD1004	Stress Management by Yoga	AC	2	2	0	0	0
5	AD1005	Personality Development Through Life EnlightenmentSkills	AC	2	2	0	0	0
6	AD1006	Unnat Bharat Abhiyan	AC	2	2	0	0	0
7	AD1007	Essence of Indian Knowledge Tradition	AC	2	2	0	0	0
8	AD1008	Sanga Tamil Literature Appreciation	AC	2	2	0	0	0

\* Registration for any of these courses is optional to students

## **CREDIT SUMMARY**

	I	II	III	IV	v	VI	VII	VIII	Total	PERCENTAGE OF CREDIT
HSMC	3	6	1						10	5.56
BSC	12	7	4	4					27	15.00
ESC	9	5							14	7.77
PCC		5	20	20	17	14	15		91	50.55
PEC					3	3	6	6	18	10.00
OEC					3	3			6	3.33
EEC						2	2	10	14	7.78
Total	24	23	25	24	23	22	23	16	180	100



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5. 6. Upon CO1 CO2 CO3 CO4 CO5 COs COs	Comfc Camb Dutt P John I Univer SE OU comple Speak approp Write vocab Read Listen Identif PO 1 -	PO 2 PO 2 PO 2 PO 2 PO 2 PO 2 -	emy, e Inivers mai a bod et ess: 2 <b>ES</b> f the /, con vely a ange, nt gen nd co s and <b>PO</b> 3 -	et al. sity Pr nd Ra al : E 2020. fident unicat and c organ res of mprel formu M PRC 4 -	Speal ress, f ijeeva 3e Gr se, st ive st ohere izing texts hend f ilate of APPI OGRA	king E Camb In Ge amm amprel rategi ently their i adop differe questi NG O	Effectionidge eta Ba ar Re ts will hensik ideas oting v ent sp ons for DF CO JTCO	vely: : Rep asic C ady: I be a oly, ar lawles logica various oken or pro- os WIT MES PO	Devel rint 20 comm The L ble to nd cor ssly a ally on s reac disco ductiv <b>FH PC</b> 9	oping 011 unicati Iltimate mmuni avoidin a topi ling str urses/e e inqui Ds ANI 0 10 3	on Skil e Guid cate w g grar c. ategie excerp ry D PSO 11 -	Ils, Fou e to E ith one nmatic <u>s.</u> <u>s</u>	or many al errors fferent a PROGI OUTC PSO1 2	Books: 2 rammar, y listener s, using ccents ccents	2013 Oxford rs using a wide ECIFIC PSOs) PSO3 2
5. 6. Upon CO1 CO2 CO3 CO4 CO5 CO5 CO5	Comfc Camb Dutt P John I Univer SE OU comple Speak approp Write vocab Read Listen, Identif PO 1 - - -	ridge L ridge L Kiran Eastwo sity Pr TCOM etion o clearly oriate c cohesi ulary ra differer /view a y topic	emy, o Inivers mai a bod et ess: 2 <b>ES</b> f the /, con vely a ange, nt gen nd co s and <b>PO</b> 3 -	et al. sity Pr nd Ra al : E 2020. fident unicat and c organ res of mprel formu M PRC PO 4 - 2	Speal ress, f ijeeva 3e Gr se, st ly, col ive st ohere izing texts hend f ilate c APPI OGRA	king E Camb In Ge amm amprel rategi ently their i adop differe questi NG O	Effectionidge eta Ba ar Re ts will hensik ideas oting v ent sp ons for DF CO JTCO	vely: : Rep asic C ady: I be a oly, ar lawles logica various oken or pro- os WIT MES PO	Devel rint 20 comm The L ble to nd cor ssly a ally on s reac disco ductiv <b>FH PC</b> 9	oping 011 unicati Iltimate woidin a topi ling str urses/e e inqui Ds ANI 0 10 3 3	on Skil e Guid cate w g grar c. ategie excerp ry D PSO 11 -	Ils, Fou e to E ith one nmatic <u>s.</u> <u>s</u>	e or many al errors fferent a PROGI OUTC PSO1 2 2	Books: 2 rammar, y listener s, using ccents ccents	2013 Oxford s using a wide ECIFIC PSOs) PSO3 2 2

MA1102	ENGINEERING MATHEMATICS –I L T	Ρ	С
	(COMMON FOR ALL BRANCHES OF B.E. /B. TECH 4 0	0	4
OBJECTIVES	PROGRAMMES)		
The go	al of this course is to achieve conceptual understanding and to retain the best tra	ditio	ons
<ul> <li>The sy</li> </ul>	tional calculus. Ilabus is designed to provide the basic tools of calculus mainly for the purp	ose	; 0
	ng the engineering problems mathematically and obtaining solutions. algebra is one of the powerful tools to handle practical problems arising in the t ering	fielc	d c
This is	a foundation course of single variable and multivariable calculus plays an importaunderstanding of science, engineering, economics and computer science, among		
UNIT I	MATRICES		12
Eigenvalues a	nd Eigenvectors of a real matrix – Characteristic equation – Properties of		
•	nd Eigenvectors – Cayley-Hamilton theorem – Diagonalization of matrices –		
-	a quadratic form to canonical form by orthogonal transformation – Nature of	С	:01
quadratic form			
	CALCULUS OF ONE VARIABLE		12
<u> </u>			
	tion - Continuity - Derivatives - Differentiation rules – Interval of increasing and ctions – Maxima and Minima - Intervals of concavity and convexity.	С	02
UNIT III	CALCULUS OF SEVERAL VARIABLES		12
Partial differer	ntiation – Homogeneous functions and Euler's theorem – Total derivative –		
Change of var	iables – Jacobians – Partial differentiation of implicit functions – Taylor's series		
for functions of	f two variables – Maxima and minima of functions of two variables – Lagrange's	С	:03
	etermined multipliers.		
UNIT IV	INTEGRAL CALCULUS		12
	definite integrals - Substitution rule - Techniques of Integration - Integration by		
	netric integrals, Trigonometric substitutions, Integration of rational functions by Integration of irrational functions - Improper integrals.	C	04
•			
	MULTIPLE INTEGRALS	+	12
Double integra	lals – Change of order of integration – Double integrals in polar coordinates –		
•	by plane curves – Change of variables from Cartesian to polar in double	C	:05
	e integrals – Volume of solids		
	TOTAL : 60 PE	RIO	D

#### **TEXT BOOKS**

- Grewal B.S., Higher Engineering Mathematicsl, Khanna Publishers, New Delhi, 43rd Edition, 2014.
- James Stewart, "Calculus: Early Transcendental", Cengage Learning, 7th Edition, New Delhi,2015. [For Units I & III Sections 2.2, 2.3, 2.5, 2.7(Tangents problems only), 2.8, 3.1 to 3.6, 3.11, 4.1, 4.3, 5.1(Area problems only), 5.2, 5.3, 5.4 (excluding net change theorem), 5.5, 7.2 7.4 and 7.8].

## **REFERENCE BOOKS**

- 1. Anton, H, Bivens, I and Davis, S, "Calculus", Wiley, 10th Edition, 2016.
- 2. Jain R.K. and Iyengar S.R.K., —Advanced Engineering MathematicsII, Narosa Publications, New Delhi, 3rd Edition, 2007.
- Narayanan, S. and Manicavachagom Pillai, T. K., —Calculus" Volume I and II, S. Viswanathan Publishers Pvt. Ltd., Chennai, 2007.
- 4. Srimantha Pal and Bhunia, S.C, "Engineering Mathematics" Oxford University Press, 2015.
- 5. T. Veerarajan. Engineering Mathematics I, McGraw Hill Education; First edition 2017.

#### **COURSE OUTCOMES**

#### UPON COMPLETION OF THE COURSE, STUDENTS WILL BE ABLE TO

- CO1 Have a clear idea of matrix algebra pertaining Eigen values and Eigenvectors in addition dealing with quadratic forms.
   CO2 Understand the concept of limit of a function and apply the same to deal with continuity and derivative of a given function. Apply differentiation to solve maxima and minima problems, which are related to real world problems.
   CO3 Have the idea of extension of a function of one variable to several variables. Multivariable functions of real variables are inevitable in engineering.
   CO4 Understand the concept of integration through fundamental theorem of calculus. Also acquire skills to evaluate the integrals using the techniques of substitution, partial fraction and integration by parts along with the knowledge of improper integrals.
- CO5 Do double and triple integration so that they can handle integrals of higher order which are applied in engineering field.

#### MAPPING OF COS WITH POS AND PSOS

cos				PRC	OGRA	MOL	JTCO	MES	(POS)	)				RAM SP OMES (I	
003	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	3	3	1	2	3	-	-	3	2	3	3	3	3	2
CO2	3	3	3	2	2	1	-	-	-	-	1	2	3	3	2
CO3	3	3	3	2	2	1	-	-	-	-	1	2	2	3	2
CO4	3	3	3	2	2	1	-	-	-	-	1	2	2	3	1
CO5	3	3	3	2	1	1	-	-	-	-	1	2	2	3	1

DU14402				<u>_</u>	
PH1103			P	T	C
	(Common for all branches of B.E. /B. Tech Programmes)	3	0	0	3
OBJECTIVES					
	tudents conversant with				
	properties of materials and various moduli of elasticity.				
Prince	ples of laser and fiber optics and its various technological applications.				
• Therma	al conduction in solids, heat exchangers and its applications in various de	vice	es.		
<ul> <li>Quanti</li> </ul>	um concepts to explain black body radiation, Compton effect and matter w	vave	es.		
Various	s crystal structures, Miller indices and crystal growth techniques.				
UNIT I	PROPERTIESOF MATTER				9
•	ress-strain diagram and its uses - factors affecting elastic modulus ar				
strength - tor	sional stress and deformations - twisting couple - torsion pendulum: th	eor	y an	d	
experiment - b	pending of beams - bending moment – cantilever: theory and experiment	– ur	hiforr	n C	:01
and non-unifo	orm bending: theory and experiment - Practical applications of mo	bdul	us d	of	
elasticity- I sha	aped girders - stress due to bending in beams.				
UNIT II	LASER ANDFIBER OPTICS				9
Lasers : popul	ation of energy levels, Einstein's A and B coefficients derivation – resona	ant c	avity	/,	
optical amplif	ication (qualitative) – Nd-YAG Laser-Semiconductor lasers: homojuno	ctior	n an	d	
heterojunction	- Industrial and medical applications of Laser- Fiber optics: principle, r	านm	erica	al	
aperture and	acceptance angle - types of optical fibres (material, refractive index,	mo	de)	- c	:02
losses associa	ated with optical fibers – Fabrication of Optical fiber-Double crucible met	thoc	l-fibr	е	
optic sensors:	pressure and displacement-Industrial and medical applications of opti-	ical	fibe	r-	
Endoscopy-Fil	per optic communication system.				
UNIT III	THERMAL PHYSICS				9
Transfer of he	at energy – thermal expansion of solids and liquids – expansion joints -	bim	etalli	с	
strips - therm	al conduction, convection and radiation – heat conductions in solids -	- th	erma	al	
conductivity –I	Rectilinear flow of heat- conduction through compound media (series and	par	allel		:03
Lee's disc m	ethod: theory and experiment - Radial flow of heat- thermal ins	ulati	ion		
applications: h	eat exchangers, refrigerators, oven, Induction furnace and solar water he	ater	s.		
UNIT IV	QUANTUMPHYSICS				9
Black body ra	⊥ diation – Planck's theory (derivation) – Compton effect: theory and exp	erin	nenta	al	
verification -	wave particle duality - electron diffraction - concept of wave function	n ai	nd it	s	
	icance – Schrödinger's wave equation – time independent and time d				:04
	particle in a one-dimensional rigid box – Electron microscope- t			_	- •
•	scanning tunnelling microscope-Applications of electron microscopy.				
	CRYSTAL PHYSICS				9
Single crystall	ine, polycrystalline and amorphous materials – single crystals: unit ce	ll, c	rysta		05
			-		23

systems, Bravais lattices, directions and planes in a crystal, Miller indices – inter-planar distances coordination number and packing factor for SC, BCC, FCC, HCP and diamond structures – Graphite structure-crystal imperfections: point defects, line defects – Burger vectors, stacking faults – growth of single crystals: solution and melt growth techniques-Epitaxial growth-Applications of Single crystal (Qualitative).

#### TEXT BOOKS

TOTAL: 45 PERIODS

- 1. Bhattacharya, D.K. & Poonam, T. "Engineering Physics". Oxford University Press, 2017.
- 2. Gaur, R.K. & Gupta, S.L. "Engineering Physics". Dhanpat Rai Publishers, 2012.
- 3. Pandey, B.K. & Chaturvedi, S. "Engineering Physics". Cengage Learning India, 2013.

#### **REFERENCE BOOKS**

- 1. Halliday, D., Resnick, R. & Walker, J. "Principles of Physics". Wiley, 2015.
- 2. Serway, R.A. & Jewett, J.W. "Physics for Scientists and Engineers". Cengage Learning, 2019.
- Tipler, P.A. & Mosca, G. "Physics for Scientists and Engineers with Modern Physics'. W.H.Freeman,2014.

#### **COURSE OUTCOMES**

CO3

CO4 CO5 

#### Upon completion of the course, the students will gain knowledge on

-	-				-				-		•				
	The ela	istic p	ropert	y and	stres	ss str	ain di	agran	n, det	ermina	ation o	f rigidi	ty modu	lus by to	orsional
CO1	pendulı	im and	l Your	ng's m	odulu	is by '	variou	is me	thods						
000	Principl	e of	laser,	Eins	stein's	coe	fficier	nts o	f lase	er act	ion, s	emico	nductor	laser a	nd its
CO2	applicat	plications, optical fibers and their applications in sensors and communication system. e heat transfer through solids and the determination of thermal conductivity in a bad													
000	The he	at tra	nsfer	throu	gh so	olids	and t	he d	eterm	ination	of th	ermal	conduct	ivity in	a bad
CO3	conduc	tor by l	_ee's	disc n	netho	d and	radia	l flow	of he	at.					
004	The qu	antum	conce	epts a	ind its	s use	to ex	plain	black	body I	radiatio	on, Co	mpton e	ffect and	wave
CO4	equatio	n for m	natter	wave	s, tuni	nelling	g elec	tron n	nicros	сору а	ind its	applica	ations.		
CO5	The imp	ortand	ce of v	variou	s crys	tal str	uctur	es, M	iller in	dices a	and va	rious g	rowth te	chniques	S.
				Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S			
COs	6			PR	OGR/		UTCC	MES	(POs	5)				RAM SP	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3 3 3 3 2 2 1 3 2 1 2 3 2 2													
CO2	3	3	3	2	3	2	2	1	2	2	2	1	2	2	3

CY1104	ENGINEERING CHEMISTRY	L	Ρ	Т	С
	(Common for all branches of B.E. /B. Tech Programmes)	3	0	0	3
OBJECTIVE	ES T				
To make th	e student conversant with the				
Prince	piples of water characterization and treatment for industrial purposes.				
Prince	piples and applications of surface chemistry and catalysis.				
<ul> <li>Phase</li> </ul>	e rule and various types of alloys				
<ul> <li>Vario</li> </ul>	ous types of fuels, applications and combustion				
<ul> <li>Conv</li> </ul>	ventional and non-conventional energy sources and energy storage device				
UNIT I	WATER AND ITS TREATMENT				9
-	f water – Types – Expression of hardness – Units – Estimation of har	dne	ss b	ν	
	od – Numerical problems on EDTA method – Boiler troubles (scale and				
	rittlement , boiler corrosion, priming and foaming) – Treatment of boiler fee				:01
Internal trea	tment (carbonate, phosphate, colloidal, sodium aluminate and calgon condi	ition	ing)		
	atment – Ion exchange process, Zeolite process – Desalination of brackish	wat	er b	у	
reverse Osn					
UNIT II	SURFACE CHEMISTRY AND CATALYSIS				9
	emistry : Types of adsorption – Adsorption of gases on solids – Adsorption				
	ons – Adsorption isotherms – Freundlich's adsorption isotherm – La				
	isotherm – Kinetics of uni-molecular surface reactions – Adso	rptic	on i		
•	aphy – Applications of adsorption in pollution abatement using PAC.			-	02
	Catalyst – Types of catalysis – Criteria – Contact theory – Catalytic poisc		0		
	moters – Industrial applications of catalysts – Catalytic convertor – Auto c	atar	ysis	_	
UNIT III	alysis – Michaelis-Menten equation. PHASE RULE AND ALLOYS				9
			Mot		9
	Introduction – Definition of terms with examples – One component system				
•	Reduced phase rule – Thermal analysis and cooling curves – Two co ead-silver system – Pattinson process.	лпр	onei	10	
•	oduction – Definition – Properties of alloys – Significance of alloying – Func	tion	e an	d C	03
	ying elements – Nichrome, Alnico, Stainless steel (18/8) – Heat treatment				
	alloys – Brass and bronze.	010	1001		
UNIT IV	FUELS AND COMBUSTION				9
Fuels: Intro	duction – classification of fuels – Comparison of solid, liquid, gaseous fuels	; – (	Coal	_	
	coal (proximate and ultimate) - Carbonization - Manufacture of metallurg				
	ann method) – Petroleum – Cracking – Manufacture of synthetic petrol				
	cher Tropsch Process) - Knocking - Octane number - Diesel oil - Cetane				
	sed natural gas (CNG) - Liquefied petroleum gases (LPG) - Power alc	cohc	l an	d C	04
biodiesel.					
	n of fuels: Introduction – Calorific value – Higher and lower calorific				
	calculation of calorific value - Ignition temperature - Spontaneous	s ig	nitio	n	
	<ul> <li>Explosive range – Flue gas analysis by Orsat Method.</li> </ul>				
UNIT V	NON-CONVENTIONAL ENERGY SOURCES AND STORAGE DEVIC				9
	ergy - Fission and fusion reactions - Differences - Chain reactions -				
	Classification of reactors – Light water nuclear reactor for power gen				
	ctor – Solar energy conversion – Solar cells – Wind energy – Fuel cells – H	iyar	uger	'  C	05
oxygen fuel			<b>4 h</b> i · · ·	~	
batteries –	Types of batteries - Alkaline batteries - Lead-acid, Nickel-cadmium and	u L	mu	n	
vallenes.	TOTAL	• 1	5 PF		200
TEXT BOO		*			
		_	11. 1	204	5)
1, P.C.Jain	Wonica Jain. Engineering Chemistry 17" Ed., Dhandat Rai Pub. Co., New	/ De	ini. (	201	JJ.
	Monica Jain, "Engineering Chemistry" 17 <sup>th</sup> Ed., Dhanpat Rai Pub. Co., New , S.S. Umare, "A text book of Engineering Chemistry" S.Chand & Co.Ltd., N				5).

Delł	ni, (2018	· 3).						•	•		•	•	dia (P) L Publishing	td. New g Compa	iny
	Ltd., Cł			9).											
	RENCE Sharma			na Ch	emist	rv" Ki	rishna	Prak	asan	Media	(P) I to	Mee	erut (200	1)	
		•		•		•					. ,		•	•	
<ol> <li>B. Sivasankar "Engineering Chemistry" Tata McGraw–Hill Pub.Co.Ltd, New Delhi (2008).</li> <li>Prasanta Rath, "Engineering Chemistry", Cengage Learning India (P) Ltd., Delhi, (2015).</li> </ol>															
<ol> <li>Prasanta Rath, "Engineering Chemistry, Cengage Learning India (P) Ltd., Deini, (2015).</li> <li>Shikha Agarwal, "Engineering Chemistry–Fundamentals and Applications", Cambridge University</li> </ol>															
Press, Delhi, (2015). 5 A. Pahari, B. Chauhan, "Engineering Chemistry", Eirewall Media, New Delhi, (2010)															
5. A. Pahari, B. Chauhan, "Engineering Chemistry", Firewall Media, New Delhi., (2010).															
6. A. Sheik Mideen, Engineering Chemistry, Airwalk Publications, Chennai (2018)															
	SE OU				_		_	_							
-	comple														
CO1	Able to	under	stand	impu	rities	in ind	ustria	l wate	er, boi	ler trou	ubles,	interna	I and ex	ternal tre	eatment
	method	s of pu	ırifying	g wate	er.										
CO2	Able to	unde	rstanc	d con	cepts	of a	bsorp	tion,	adsor	ption,	adsorp	otion is	sotherms	s, applica	ation of
002	adsorpti	on for	pollut	tion al	batem	nent, c	catalys	sis an	d enz	yme ki	netics.				
<u> </u>	Able to	recog	nize s	signifi	cance	e of a	lloying	g, fun	ctions	s of all	oying	eleme	nts and	types of	alloys,
CO3	uses of	alloys	phas	e rule	e, redu	uced p	bhase	and i	ts app	olicatio	ns in a	lloying	I.		
	Able to	identi	y var	ious t	ypes	of fue	els, pi	ropert	ies, u	ses ar	nd ana	lysis c	of fuels.	They sh	ould be
CO4	able to u	unders	stand	comb	ustion	of fu	els, m	ethoo	l of pr	eparat	ion of I	bio-die	sel, synt	hetic pet	rol.
	Able to	under	stand	conv	entior	nal, no	on-col	nvent	ional	enerav	sourc	es, nu	clear fis	sion and	fusion,
										0,				uses of	
ľ	batteries	-					,	,		5	,	1			
				M		NGO		s WI		)s AN[	) PSO	s			
					OGR/							-	PROG	RAM SP	ECIFIC
COs					1				•	-					
CO1	P01	PO2	PO3	PO4	<b>РО5</b> З	P06	P07	P08	P09	PO10	P011	PO12	PS01	PSO2	PSO3
CO1 CO2	3	3	3	3	3	2	3	2	2	2	2 1	2	2	2	1
CO3	3	3	3	3	3	2	2	1	2	2	2	2	2	2	2
CO4	3	3	3	2	2	3	3	2	2	3	2	2	3	1	2
	-	-	_	_	-	-	-	-	-	-	_	_	-	-	

CO5

GE1105		Ρ	С
		0	3
<ul><li>To wr</li><li>To de</li><li>To us</li></ul>	<b>S</b> ow the basics of algorithmic problem solving ite simple python programs velop python program by using control structures and functions e python predefined data structures ite file based program		
UNIT I	ALGORITHMIC PROBLEM SOLVING		g
Algorithms, b	building blocks of algorithms (statements, state, control flow, functions), notation		
(pseudo coc	le, flow chart, programming language), algorithmic problem solving, Basic		
algorithms, f	lowcharts and pseudocode for sequential, decision processing and iterative	C	01
•	trategies, Illustrative problems: find minimum in a list, insert a card in a list of	0	51
	guess an integer number in a range, Towers of Hanoi.		
	INTRODUCTION TO PYTHON		ç
Python Introd	duction, Technical Strength of Python, Python interpreter and interactive mode;		
•	o colab, pycharm and jupyter idle(s), values and types: int, float, boolean, string,		
	-in data types, variables, Literals, Constants, statements, Operators; Assignment,	С	<u>~</u>
	elational, Logical, Bitwise operators and their precedence, , expressions, tuple		JZ
	Accepting input from Console, printing statements, Simple 'Python' programs.		
	CONTROL FLOW, FUNCTIONS AND STRINGS		ç
	Boolean values and operators, conditional (if), alternative (if-else), chained		
	f-elif-else); Iteration: while, for; Loop manipulation using pass, break, continue,		
	dules and Functions, function definition and use, flow of execution, parameters		
	its; local and global scope, return values, function composition, recursion; Strings:	C	03
•			
•	immutability, string functions and methods, string module; Illustrative programs:		
•	gcd, exponentiation, sum an array of numbers, linear search, binary search.		
	LISTS, TUPLES, DICTIONARIES		ę
	ng list and list slicing, list operations, list slices, list methods, list loop, List		
	, mutability, aliasing, cloning lists, list parameters; Lists as arrays, Tuples: tuple		
•	tuple as return value, Tuple Manipulation; Dictionaries: operations and methods;	C	24
	t processing – list comprehension; Illustrative programs: selection sort, insertion		
	ort, histogram.		
	FILES, MODULES, PACKAGES		ç
	ception: Concept of Files, Text Files; File opening in various modes and closing of		
	t Operators, Reading from a file, Writing onto a file, File functions-open(), close(),		
	line(), readlines(),write(), writelines(),tell(),seek(), Command Line arguments.	C	25
Errors and	exceptions, handling exceptions, modules, packages; introduction to numpy,		
	ustrative programs: word count, copy file.		

#### **TEXT BOOKS**

- 1. Allen B. Downey, "Think Python: How to Think Like a Computer Scientist", 2nd edition, Updated for Python 3, Shroff/O'Reilly Publishers, 2016 (http://greenteapress.com/wp/thinkpython/)
- 2. Guido van Rossum and Fred L. Drake Jr, An Introduction to Python Revised and updated for Python 3.2, Network Theory Ltd., 2011.

#### **REFERENCE BOOKS**

- 1. John V Guttag, —Introduction to Computation and Programming Using Python", Revised and expanded Edition, MIT Press, 2013
- 2. Robert Sedgewick, Kevin Wayne, Robert Dondero, —Introduction to Programming in Python: An Inter-disciplinary Approach, Pearson India Education Services Pvt. Ltd., 2016.
- 3. Timothy A. Budd, Exploring Pythonll, Mc-Graw Hill Education (India) Private Ltd.,, 2015.
- 4. Kenneth A. Lambert, —Fundamentals of Python: First ProgramsII, CENGAGE Learning, 2012.
- 5. Charles Dierbach, —Introduction to Computer Science using Python: A Computational Problem-Solving Focus, Wiley India Edition, 2013.
- 6. Paul Gries, Jennifer Campbell and Jason Montojo, —Practical Programming: An Introduction.

#### **COURSE OUTCOMES**

#### Upon completion of the course, students will be able to

	CO1	Develop algorithmic solutions to simple computational problems
	CO2	Develop simple console application in python
ſ	CO3	Develop python program by applying control structure and decompose program into functions.
ſ	CO4	Represent compound data using python lists, tuples, and dictionaries.
	CO5	Read and write data from/to files in Python.

#### MAPPING OF COs WITH POS AND PSOs

COs			PROGRAM SPECIFIC OUTCOMES (PSOs)												
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	-	2	-	-	2	3	2	-	2	2	1	1
CO2	3	3	3	-	2	-	-	2	3	2	-	2	2	1	1
CO3	3	3	3	-	2	-	-	2	3	2	-	2	1	2	2
CO4	3	3	3	-	2	-	-	2	3	2	-	2	1	2	2
CO5	3	3	3	-	2	-	-	2	3	2	-	2	1	2	1

GE1106	ENGINEERING GRAPHICS		<b>T</b>	P	<u> </u>
GEIIUO	Common for all branches of B.E. /B. Tech Programmes)	L 1	<b>T</b> 0	<u>Р</u> 4	<b>C</b> 4
OBJECTIVES	Common for all branches of D.E. /D. Tech Programmes)		U	4	4
<ul> <li>To dev Engine</li> </ul>	relop in students, graphic skills for communication of concepts, ideas ering products ose them to existing national standards related to technical drawings.	an	d de	sign	ı of
	ND CONVENTIONS (Not for Examination)		DIC		1
	graphics in engineering applications – Use of drafting instruments nd specifications – Size, layout and folding of drawing sheets – Lette				
UNIT I	PLANE CURVES AND FREEHAND SKETCHING			7-	+12
of ellipse, pa construction o curves. Visualization o	rical constructions, Curves used in engineering practices: Conics – Construction and hyperbola by eccentricity method – Construction of construction of construction of square and circle – Drawing of tangents and normal to the concepts and Free Hand sketching: Visualization principles –Representional objects – Layout of views- Freehand sketching of multiple vie of objects	yclo e al tatic	id – bove on of	с	:01
UNIT II	PROJECTION OF POINTS, LINES AND PLANE SURFACE			6-	+12
Projection of s Determination	projection- principles-Principal planes-First angle projection-projection of straight lines (only First angle projections) inclined to both the principal of true lengths and true inclinations by rotating line method and traces P ygonal and circular surfaces) inclined to both the principal planes by	plar roje	nes - ction	с	02
UŃIT III	PROJECTION OF SOLIDS			5-	+12
•	imple solids like prisms, pyramids, cylinder, cone and truncated solids v to one of the principal planes by rotating object method.	vher	n the	С	03
UNIT IV	PROJECTION OF SECTIONED SOLIDS AND DEVELOPMENT OFSURFACES			5-	+12
one of the pri	above solids in simple vertical position when the cutting plane is incline ncipal planes and perpendicular to the other – obtaining true shape of of lateral surfaces of simple and sectioned solids – Prisms, pyramids of	sec	tion.		04
UNIT V	ISOMETRIC AND PERSPECTIVE PROJECTIONS			6-	+12
truncated soli simple vertica	sometric projection – isometric scale –Isometric projections of simple so ds - Prisms, pyramids, cylinders, cones- combination of two solid of I positions - Perspective projection of simple solids-Prisms, pyram sual ray method.	bjec	ts in	с	05
	TOTAL	.:4	5 PE	rio	DS
Twenty	an K.V., "A text book of Engineering Graphics", Dhanalakshmi Publis Ninth Edition 2016 Internation K. and Prabhu Raja V., "Engineering Graphics", New Age Internation		-		-
REFERENCE	BOOKS				
1. Bhatt I	I.D. and Panchal V.M., "Engineering Drawing", Charotar Publishing	; Н	ouse	, 5	3rd
Edition	, 2019.				
2. Basant	Agarwal and Agarwal C.M., "Engineering Drawing", Tata McGraw	Hill	Put	olish	ing
Compa	ny Limited, New Delhi, 2008.				

- 4. Luzzader, Warren.J. and Duff,John M., "Fundamentals of Engineering Drawing with an introduction to Interactive Comput er Graphics for Design and Production, Eastern Economy Edition, Prentice Hall of India Pvt. Ltd, New Delhi, 2005.
- 5. N S Parthasarathy and Vela Murali, "Engineering Graphics", Oxford University, Press, New Delhi, 2015.
- 6. Shah M.B., and Rana B.C., "Engineering Drawing", Pearson, 2nd Edition, 2009.

## COURSE OUTCOMES

## Upon completion of the course, students will be able to

CO1	Understand the fundamentals and standards of Engineering graphics
CO2	Perform freehand sketching of basic geometrical constructions and multiple views of objects
CO3	Understand the concept of orthographic projections of lines and plane surfaces
CO4	Draw the projections of section of solids and development of surfaces
CO5	Visualize and to project isometric and perspective sections of simple solids

#### MAPPING OF COS WITH POS AND PSOS

COs					PROGRAM SPECIFIC OUTCOMES (PSOs)										
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	2	1	2	1	1	-	-	3	3	2	3	1	1	1
CO2	3	1	2	2	1	1	-	-	3	3	2	3	1	1	1
CO3	3	1	1	3	1	1	-	-	3	3	2	3	1	1	1
CO4	3	1	1	3	1	1	-	-	3	3	2	3	1	1	1
CO5	3	1	2	3	1	1	-	-	3	3	2	3	1	1	1

SE11			P (
	(Common for all branches of B.E. /B. Te	ech Programmes) 0 0	4 2
)BJE	CTIVES		
٠	To write, test, and debug simple Python programs.		
٠	To implement Python programs with conditionals and	loops.	
٠	Use functions for structuring Python programs.		
٠	Represent compound data using Python lists, tuples,	and dictionaries.	
٠	Read and write data from/to files in Python.		
IST (	OF EXPERIMENTS		
1.	Write an algorithm, draw flowchart illustrating mail me	erge concept.	
2.	Write an algorithm , draw flowchart and write pseud	lo code for a real life or scientific o	or
	technical problems		
3.	Scientific problem solving using decision making and	looping.	co
	<ul> <li>Armstrong number, palindrome of a number, I</li> </ul>	Perfect number.	
4.	Simple programming for one dimensional and two dir	mensional arrays.	
	Transpose, addition, multiplication, scalar, de	eterminant of a matrix	
5.	Program to explore string functions and recursive fun	nctions.	
6.	Utilizing 'Functions' in Python		_
	<ul> <li>Find mean, median, mode for the given set of</li> </ul>	f numbers in a list.	
	<ul> <li>Write a function dups to find all duplicates in t</li> </ul>		
	<ul> <li>Write a function unique to find all the unique e</li> </ul>		CO
	Write function to compute gcd, lcm of two nun		
7	Demonstrate the use of Dictionaries and tuples with s		
8.			
	To sort the 'n' numbers using: Selection, Merge sort a		_
	). Find the most frequent words in a text of file using co		
	. Demonstrate Exceptions in Python.	ommand line arguments.	co
	2. Applications: Implementing GUI using turtle, pygame		_
12	Applications. Implementing GOI using turtle, pygame	TOTAL : 60 P	
	OF EQUIPMENT FOR A BATCH OF 30 STUDENTS		
•	n 3 interpreter for Windows/Linux		
	RENCE BOOKS		ر باند. ا
1.	Allen B. Downey, "Think Python: How to Think Lik	•	
~	Updated for Python 3, Shroff/O'Reilly Publishers, 201		
	Shroff "Learning Python: Powerful Object-Oriented P		
3.	, ,	lison-Wesley Protessional; Fourth	editio
	2009.		

#### 4. David M. Baezly "Python Cookbook" O'Reilly Media; Third edition (June 1, 2013)

## WEB REFERENCES

1. http://www.edx.org

#### **COURSE OUTCOMES**

data.

#### Upon completion of the course, students will be able to

CO1 Develop simple console applications through python with control structure and functions
 CO2 Use python built in data structures like lists, tuples, and dictionaries for representing compound

CO3 Read and write data from/to files in Python and applications of python.

## MAPPING OF COS WITH POS AND PSOS

COs				PRO	GRA	PROGRAM OUTCOMES (POs)													
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3				
CO1	3	3	3	-	2	-	-	2	3	2	-	2	2	-	-				
CO2	3	3	3	-	2	-	-	2	3	2	-	2	2	1	1				
CO3	3	3	3	-	2	-	-	2	3	2	-	2	2	-	1				

BS110		L	Т	Ρ	С
	(Common for all branches of B.E. /B. Tech Programmes)	0	0	4	2
	CTIVES				
ne st	udents will be trained to perform experiments to study the following.				
	The Properties ofMatter				
	The Optical properties , Characteristics of Lasers & Optical Fibre				
	<ul> <li>Electrical &amp; Thermal properties of Materials</li> </ul>				
	<ul> <li>Enable the students to enhance accuracy in experimentalmeasure</li> </ul>	ements			
	<ul> <li>To make the student to acquire practical skills in the determination parameters through volumetric analysis</li> </ul>	n of w	ater	qua	alit
	Instrumental method of analysis such as potentiometry, conductometr	y and	pHm	netry	'
IST C	OF EXPERIMENTS - PHYSICS				
	(A minimum of 5 experiments to be performed from the given list)				
1.	Determination of Young's modulus of the material of the given beam by	(	CO1		
	Non-uniform bending method.				
2.	Determination of rigidity modulus of the material of the given wire using	(	CO1		
	torsion pendulum.				
3.	Determination of wavelength of mercury spectra using Spectrometer and	(	CO2		
	grating.				
4.	Determination of dispersive power of prism using Spectrometer.	(	CO2		
5.	(a) Determination of wavelength and particle size using a laser.				
	(b) Determination of numerical aperture and acceptance angle of an	(	CO2		
	optical fibre.				
	(c) Determination of width of the groove of compact disc using laser.				
6.	Determination of Young's modulus of the material of the given beam by	(	CO1		
	uniform bending				
	method.		_		
	Determination of energy band gap of the semiconductor.		CO2		
8.	Determination of coefficient of thermal conductivity of the given bad	(	CO2		
	conductor using Lee's disc.				
	ONSTRATION EXPERIMENT		_		
1.	Determination of thickness of a thin sheet / wire – Air wedge method	(	CO1		
IST C	OF EXPERIMENTS - CHEMISTRY				
(/	A minimum of 6 experiments to be performed from the given list)				
1.	<b>J Z J J</b>		CO5	5	
	of alkalinity in water sample.				
2.	Determination of total, temporary & permanent hardness of water by EDTA method.		CO5	<b>)</b>	
3.			CO5	5	
4.	• •		CO3		
	method.				
5.			соз	}	
6.			CO3		
7.			CO4		
-	conductivity meter.				
8.	•		CO4	Ļ	
9.	• • • • • • • • • • • • • • • • • • • •		CO4		
	viscometer.				
10.	Conductometric titration of strong acid vs strong base.		CO4	ļ	
	ONSTRATION EXPERIMENTS				
			CO3	5	
1		1			
1.	(1,10- Phenanthroline / thiocyanate method).				

COU					cours	so th	o stu	donte	shou	ıld be						
CO1	Able of m	e to u nodul e to ι	nders i.	stand	the co	oncep	t abo	ut the	basio	c prop	erties				strain an n presen	
CO2	Able spee Able	e to ctrom e to u	neter ( under	grating stand	g. the o	conce	pt ab	out m	neasu		he cor				iction by acid and	-
CO3	con Able	ducto e to u	or. Inders		the pi										luctivity o	
CO4						•			•		••			ermining potention	the mooneter.	luli.
CO5	Able	e to u		stand	the co	oncep	t of de	eterm	ining	•	H value		Ū	h of a giv	ven acid	sample
									-	_	)s AN[	) PSO	S	PROC		
					- PR(	JGRA	AM OI	JTCC	MES	(POs	5)					
со	S				1 1.					<b>`</b>	-			0	UCOME	ECIFIC S
		PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	O PSO1	PSO2	
CO co <sup>,</sup>		3	<b>РО2</b> 1	2					1	•	PO10	P011 2	P012 3		1	S
	1	3	-	2	PO4	PO5 2 1	PO6 1 1	PO7	PO8	PO9		-	-	PSO1	PSO2	S PSO3
CO,	1	3	1	2	PO4 2	P05 2	PO6	<b>РО7</b> 1	РО8 1	PO9 3	2	2	3	<b>PSO1</b> 2	<b>PSO2</b> 2	<b>S</b> PSO3 2
CO <sup>2</sup>	1 2 3	3	1	2	PO4 2 1	PO5 2 1	PO6 1 1	<b>РО7</b> 1 1	P08 1 1	PO9 3 2	2 1	2 1	3 2	<b>PSO1</b> 2 2	<b>PSO2</b> 2 2	<b>S</b> PSO3 2 2

HS1201	PROFESSIONAL ENGLISH	L	Т	Ρ	С
	(Common for all branches of B.E. /B. Tech Programmes)	3	0	0	3
OBJECTIVE	······································	•	•	•	
techr • Foste • Deve • Strer	alop strategies and skills to enhance their ability to read and comprehend enology texts. For their ability to write convincing job applications and effective reports. For their speaking skills to make technical presentations, participate in ground their their listening skill which will help them comprehend lectures and sof specialization.	up c	liscu	ssic	ons
UNIT I	READING AND STUDY SKILLS				9
three or four	ening Comprehension of a discussion on a technical topic of common interparticipants (real life as well as online videos)Speaking – describing a p	roc	ess-		
graphs- Voc homophone	ctice in chunking and speed reading - Paragraphing- Writing- interpreting abulary Development: Important foreign expressions in Use, homo s, homographs - easily confused words Language Develo	ony	vms,	С	:01
impersonal p UNIT II	assive voice, numerical adjectives.           READING AND STUDY SKILLS				9
-	ening Comprehension of a discussion on a technical topic of common inter-	eres	st bv		3
three or four Reading: Pra graphs- Voc homophone	participants (real life as well as online videos)Speaking – describing a p actice in chunking and speed reading - Paragraphing- Writing- interpreting abulary Development: Important foreign expressions in Use, homo s, homographs – easily confused words Language Development- imp e, numerical adjectives.	oroc ch ony	ess- arts, rms,		:02
	TECHNICAL WRITING AND GRAMMAR				9
stress, into Reading lon Describing a Informal voo	stening to conversation–effective use of words and their sound as nation & pronunciation- Speaking – mechanics of presentations -R ger texts for detailed understanding. (GRE/IELTS practice tests); process, use of sequence words- Vocabulary Development- sequence cabulary and formal substitutes-Misspelled words. Language Development-	eac Wri wc	ding: ting- ords-		:03
UNIT IV	entences and Ellipsis.				
Listening – agreement/or reports, adve cover letter - based essay	<b>REPORT WRITING</b> Model debates & documentaries and making notes. Speaking– exp disagreement, assertiveness in expressing opinions-Reading: Te ertisements and minutes of meeting - Writing- email etiquette- job applid -Résumé preparation( via email and hard copy)- analytical essays an sVocabulary Development- finding suitable synonyms-paraphrasing- La c- clauses- if conditionals.	echi catio d is	nical on – ssue		9 :04
	GROUP DISCUSSION AND JOB APPLICATIONS				9
Listening: Ex Speaking –p novels, poeti Writing a lett	tensive Listening. (radio plays, rendering of poems, audio books and articipating in a group discussion - Reading: Extensive Reading (short ry and others )– Writing reports- minutes of a meeting- accident and ter/ sending an email to the Editor - cause and effect sentences -Voo - verbal analogies. Language Development- reported speech.	sto sur abu	ries, vey- ulary	С	:05
TEXT BOOK		. 4:		RIU	פּטי
<ol> <li>Boarc Black</li> <li>Barun</li> <li>Sudha Unive</li> </ol>	I of editors. Fluency in English A Course book for Engineering and Tech swan, Hyderabad: 2020. K Mitra, Effective Technical Communication Oxford University Press : 200 arshana.N.P and Saveetha. C. English for Technical Communicatio rsity Press: New Delhi, 2016.	6.			
REFERENCE	E BOOKS				
	n, Meenakshi and Sharma, Sangeetha- Technical Communication				

Practice. Oxford University Press: New Delhi,2014.

- 2. Kumar, Suresh. E. Engineering English. Orient Blackswan: Hyderabad, 2015
- 3. Booth-L. Diana, Project Work, Oxford University Press, Oxford: 2014.
- 4. Grussendorf, Marion, English for Presentations, Oxford University Press, Oxford: 2007
- 5. Means, L. Thomas and Elaine Langlois, English & Communication For Colleges. Cengage Learning, USA: 2007.
- 6. Caroline Meyer & Bringi dev, Communicating for Results Oxford University Press: 2021.
- 7. Aruna Koneru, Professional Speaking Skills, Oxford University Press :2015.

# COURSE OUTCOMES

### Upon completion of the course, students will be able to

- CO1 Speak clearly, confidently, comprehensibly, and communicate with one or many listeners using appropriate communicative strategies.
- CO2 Write cohesively and coherently and flawlessly avoiding grammatical errors, using a wide vocabulary range, organizing their ideas logically on a topic.

CO3 Read different genres of texts adopting various reading strategies.

CO4 Listen/view and comprehend different spoken discourses/excerpts in different accents

CO5 Identify topics and formulate questions for productive inquiry

COs				PRC	OGRA	MOU	лсо	MES	(POs)					RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	-	-	-	1	2	3	-	-	-	-	3
CO2	-	1	-	2	-	-	-	-	-	3	-	-	-	-	-
CO3	-	2	-	3	-	-	-	-	1	2	-	-	3	-	1
CO4	-	-	-	-	1	-	-	-	2	2	-	-	1	-	2
CO5	-	2	1	1	2	-	2	-	-	3	-	-	2	-	1

MA125		L	Т	Ρ	С
	(Common to AI-DS )	4	0	0	4
OBJEC	TIVES				
	To test the consistency and solve the system of linear equations				
	To find the basis and dimension of vector space				
	To obtain the matrix of linear transformation and its eigenvalues and eigenvect				
	To find orthonormal basis of inner product space and find least square approxi			- ···	
٠	To find eigenvalues of a matrix using numerical techniques and perform matrix	dec	ompo	SITI	on.
UNIT I	MATRICES AND SYSTEM OF LINEAR EQUATIONS				12
	s - Row echelon form - Rank - System of linear equations - Consistency	- G	auss	C	:01
elimina UNIT II	ion method - Gauss Jordon method. VECTOR SPACES				12
-	spaces, Subspaces, Linear combinations, Linear independence and linear dep	ende	nce		
	ind dimensions.	onat	,	C	:02
UNIT II					12
	ransformation - Rank space and null space - Rank and nullity - Dimension				
	representation of linear transformation - Eigenvalues and eigenvectors	of I	inear	C	:03
transfol UNIT IN	mation.			1	12
-	product and norms - Properties - Orthogonal, Orthonormal vectors - Gram	Sch	nmidt		
	rmalization process - Least square approximation		at	C	:04
UNIT V					12
	alue Problems: Power method, Jacobi rotation method - Singular value decom omposition.	posi	tion -	C	:05
	TOTA	L:4	5 PE	RIC	DS
TEXT E	OOKS				
2. 3.	Friedberg S.H, Insel A.J. and Spence L, Linear Algebra, Fifth edition, Pearson, Burden R. and Faires J.D. Numerical Analysis, tenth edition, Brooks/Cole, 201 Strang G, Linear algebra for everyone, Wellesley Cambridge press, 2020. ENCE BOOKS		8		
1.	Seymour Libschutz and Marc Lipson, Linear Algebra, Sixth edition, McGra ndia private limited, New Delhi, 2017.	w Hi	ll Ed	uca	tion
	yengar S.R.K. and Jain R.K., Numerical Methods, Third edition, New a publications, 2012.	age	interr	natio	ona
	Kumaresan S, Linear Algebra - A geometric approach, Prentice Hall of Ir Reprint, 2010.	ndia,	New	D	əlhi,
4. 5.	Sundarapandian V, Numerical Linear Algebra, Prentice Hall of India, New Delh Bernard Kolman and David R. Hill, Introductory Linear Algebra, Pearson I Delhi, First Reprint, 2009.			s, 1	lew
Upon c	ompletion of the course, students will be able to				
CO1	Test the consistency and solve the system of linear equations				
CO2	Find the basis and dimension of vector space				
CO3	Obtain the matrix of linear transformation and its eigenvalues and eigenvector	rs			
CO4	Find orthonormal basis of inner product space and find least square approxin	natio	n		
CO5	Determine eigen values of a matrix using numerical techniques and	per	form	m	atrix
	decomposition				
	-				

				Μ	APPI	NG O	F CO	s WI	ГН РС	)s ANI	D PSO	S			
COs			-	PRC	OGRA	MOL	JTCO	MES	(POs)		-	-		RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	3	3	2	I	-	1	1	3	3	3	3
CO2	3	3	2	3	2	2	1	-	-	-	-	2	2	2	2
CO3	3	2	2	2	2	1	1	-	-	-	-	1	2	2	2
CO4	3	3	3	2	2	2	1	I	-	-	-	1	2	2	2
CO5	3	3	3	2	2	2	1	-	-	-	-	1	2	3	3

PH1252	PHYSICS FOR INFORMATION SCIENCE	L	Ρ	Т	С
	(Common to CSE, AI-DS & IT )	3	0	0	3
OBJECTI	ES				
To make	he student				
•	To acquire knowledge on the electron transport properties				
•	To understand the essential principles of semiconductor device				
•	To have the necessary understanding in optical properties of materials.				
•	To grasp the principles of magnetic materials and its applications.				
•	To understand the basics of Nano-electronic devices.				
UNIT I	ELECTRICAL PROPERTIES OF MATERIALS				9
Classical	free electron theory - Expression for electrical conductivity - Thermal con	duc	tivity	/,	
expressio	- Wiedemann-Franz law - Success and failures - electrons in metals - Pa	rticl	e in	а	
three dim	nsional box - degenerate states - Fermi- Dirac statistics - Density of energy	/ st	ates	- C	:01
Electron i	periodic potential - Energy bands in solids - Electron effective mass - conce	ot o	f hol	е	
- Applicat	ns of low resistive and high resistive materials.				
UNIT II	SEMICONDUCTOR PHYSICS				9
Intrinsic	emiconductors - Energy band diagram - direct and indirect bar	nd	gap		
semicond	ctors - carrier concentration in intrinsic semiconductors - extrinsic semiconc	luct	ors -		
	centration in n-type & p-type semiconductors - variation of carrier concentrat				:02
temperatu	e - variation of Fermi level with temperature and impurity concentration -	- ca	rrier		,02
transport	n semiconductors - Hall effect and devices - Ohmic contacts - Schottky	dio	de -		
Semicono	cting polymers.				
UNIT III	MAGNETIC PROPERTIES OF MATERIALS				9
Magnetisr	in materials - magnetic dipole moment - magnetic permeability and suscept	otibi	lity -		
Microscop	c classification of magnetic materials : diamagnetism - paramagne	etis	m -		
ferromagr	tism - antiferromagnetism - ferrimagnetism - Curie temperature - Domain 1	The	ory -		:03
M versus	H behaviour - Hard and soft magnetic materials - examples and uses - M	lag	netic		.03
	computer data storage - Magnetic hard disc - Spintronics - GMR Senso	r (C	Siant		
Magnetor	sistance) - TMR (Tunnel Magnetoresistance)				
UNIT IV	OPTICAL PROPERTIES OF MATERIALS				9
	on of optical materials - carrier generation and recombination proce				
	emission and scattering of light in metals, insulators and semiconductors (c				<b>•</b> ••
only) - ph	to current in a P-N diode - solar cell - LED - Organic LED - p-i-n Photoc	dioc	les -		:04
Avalanche	Photodiodes -Optical data storage techniques- Holography - applications.				
UNIT V	NANO DEVICES				9
Electron of	ensity in bulk material - Size dependence of Fermi energy - Quantum confi	nen	nent	-	
Quantum	structures - Density of states in quantum well, quantum wire and quar	ntur	n da	ot	
structure	Band gap of nanomaterials - Tunneling: single electron phenomena ar	nd	singl	е	
electron t	nsistor - Quantum dot laser - Ballistic transport - Carbon nanotubes: prope	rtie	s an	d C	:05
	s - Material Processing by chemical vapour deposition and Laser ablation				
	properties and applications.				
	TOTAL	: 4	5 PE	RIC	DS
TEXT BO	KS				
	ingh, — Semiconductor Devices: Basic Principles, Wiley 2012.				
	Jeaman, Dhrubes Biswas, Semiconductor Physics and Devices (SIE), 4 <sup>th</sup> Ec	litio	n, 2	017	
	nan,S., Rajalakshmi,A., Karthie,S., Rajesh,N.P., "Physics for Electronics Eng				
	on Science", McGraw Hill Education (India) Private Limited, 2018.	, ,			
	5.0. — Principles of Electronic Materials and Devices, McGraw-Hill Education	n, 2	007.		
	- Introduction to Solid State Physics, Wiley, 2005.	, _			
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### **REFERENCE BOOKS**

- 1. Garcia, N. & Damask, A. Physics for Computer Science Students. Springer-Verlag, 2012.
- 2. Hanson, G.W. Fundamentals of Nanoelectronics, Pearson Education, 2009.
- Rogers, B., Adams, J. & Pennathur, S. —Nanotechnology: Understanding small systems, CRC press, 2014

### COURSE OUTCOMES

### Upon completion of the course, the students will be able to

CO1 Gain knowledge on classical and quantum electron theories and energy band structures.
 CO2 Acquire knowledge on basics of semiconductor physics and its applications in various devices.
 CO3 Get knowledge on magnetic properties of materials and their applications in data storage.
 CO4 Have the necessary understanding on the functioning of optical materials for Optoelectronics.
 CO5 Understand the basics of quantum structures and their applications in nano electronic devices.
 MAPPING OF COS WITH POS AND PSOS

COs								MES						RAM SP	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	1	2	1	1	1	2	1	3	2	2
CO2	3	3	1	1	3	1	1	1	2	2	2	1	2	2	3
CO3	3	3	1	1	2	2	1	1	1	1	1	2	2	2	2
CO4	3	3	3	2	2	1	1	1	2	2	1	3	3	3	3
CO5	3	3	3	2	3	1	1	1	2	1	2	3	3	3	3

054004			-	
GE1204	ENVIRONMENTAL SCIENCE AND ENGINEERING	P	<u>Т</u>	<b>C</b>
OBJECTIVES	(Common for all branches of B.E. /B. Tech Programmes) 3	0	0	3
<ul> <li>To stud</li> <li>To app envision</li> <li>To find environ</li> <li>To stud manage</li> </ul>	dy the dynamic processes and understand the features of the earth's i	olutio	ons I wa	to iste
	ENVIRONMENT, ECOSYSTEM AND BIODIVERSITY			11
Individual in Er ecosystem – F chains, food v features, struc oceans, estuar Biodiversity – Consumptive u global, nationa Threats to bio protection act a	pe and importance of environment – Need for public awareness – Romvironmental protection – Concept of an ecosystem – Structure and function Producers, consumers and decomposers – Energy flow in the ecosystem – webs and ecological pyramids – Ecological succession – Types, character ture and function of forest, grass land, desert and aquatic (ponds, lakes, r ies) ecosystem. Definition – Genetic, species and ecosystem diversity – Value of biodiver use, productive use, social, ethical, aesthetic and option values – Biodivers I and local levels – India as a mega diversity nation – Hot spots of biodiver diversity– Habitat loss, poaching of wild life, human-wildlife conflicts – W and forest conservation act – Endangered and endemic species – Conservat m-situ and ex-situ conservation of biodiversity.	of a Foo eristi ivers sity a sity a sity a	n c, c, c, t t	01
UNIT II	ENVIRONMENTAL POLLUTION			9
<ul> <li>(c) Soil polluti</li> <li>hazards – Soli</li> <li>wastes – Probl</li> <li>studies – Disas</li> </ul>	auses, effects and control measures of: (a) Air pollution (b) Water pollu on (d) Marine pollution (e) Noise pollution (f) Thermal pollution (g) Nuc d waste management: causes, effects and control measures of municipal ems of e-waste – Role of an individual in prevention of pollution – Pollution of ster management – Floods, earthquake, cyclone, tsunami and landslides – I polluted site – Urban / Rural / Industrial / Agricultural.	clear solid case		02
UNIT III	NATURAL RESOURCES			9
extraction, min and overutiliza benefits and p extracting and – Changes ca pesticide probl needs – Rene Case studies landslides, soi resources – Ee	ces: Uses and over-exploitation – Deforestation – Case studies – Tir ing, dams and their effects on forests and tribal people – Water resources – tion of surface and ground water, floods, drought, conflicts over water – Da roblems – Mineral resources: Uses and exploitation – Environmental effec using mineral resources – Case studies – Food resources: World food probl used by agriculture and overgrazing – Effects of modern agriculture: fertili ems, water logging, salinity – Case studies – Energy resources: Growing en wable and non renewable energy sources – Use of alternate energy source – Land resources: Land as a resource – Land degradation, man indu l erosion and desertification – Role of an individual in conservation of na quitable use of resources for sustainable lifestyles – Field study of local are ronmental assets – River / Forest / Grassland / Hill / Mountain.	Use ams: ts of lems zer– ergy es – uced tural	с	О3
UNIT IV	SOCIAL ISSUES AND THE ENVIRONMENT			8
conservation, r of people; its p	hable to sustainable development – Urban problems related to energy – W ain water harvesting, watershed management – Resettlement and rehabilita roblems and concerns, case studies – Role of non-governmental organizati ethics – Issues and possible solutions – Climate change – Global warming	ation on –		04

Acid rain, Ozone layer depletion –Nuclear accidents and holocaust – Case studies – Wasteland reclamation – Consumerism and waste products – Principles of Green Chemistry – Environment protection act – Air (Prevention and Control of Pollution) Act – Water (Prevention and control of Pollution) Act – Wildlife protection Act – Forest conservation Act – Enforcement machinery involved in environmental legislation– Central and state pollution control boards– National Green Tribunal – Public awareness.

### UNIT V HUMAN POPULATION AND THE ENVIRONMENT

Population growth – Variation among nations – Population explosion – Family welfare programme – Environment and human health – Human rights – Value education – HIV / AIDS – COVID 19 – Women and child welfare – Role of information technology in environment and human health – Case studies

### **TEXT BOOKS**

CO5

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- 1. Benny Joseph, 'Environmental Science and Engineering', Tata McGraw-Hill, New Delhi, (2014).
- 2. Gilbert M. Masters, 'Introduction to Environmental Engineering and Science', 2<sup>nd</sup> edition, Pearson Education, (2004). 3. Dr. A. Sheik Mideen and S.Izzat Fathima, "Environmental Science and Engineering", Airwalk Publications, Chennai, (2018). **REFERENCE BOOKS** 1. Dharmendra S. Sengar, 'Environmental law', Prentice hall of India Pvt Ltd, New Delhi, (2007). 2. Erach Bharucha, "Textbook of Environmental Studies", Universities Press (I) Pvt, Ltd, Hyderabad, (2015).3. G. Tyler Miller, Scott E. Spoolman, "Environmental Science", Cengage Learning India Pvt. Ltd, Delhi, (2014). 4. R. Rajagopalan, 'Environmental Studies - From Crisis to Cure', Oxford University Press, (2005). 5. Anubha Kaushik, C.P. Kaushik, "Perspectives in Environmental Studies", New Age International Pvt. Ltd, New Delhi, (2004). 6. Frank R. Spellman, "Handbook of Environmental Engineering", CRC Press, (2015). COURSE OUTCOMES Upon completion of the course, the students should be able CO1 To obtain knowledge about environment, ecosystems and biodiversity. CO2 To take measures to control environmental pollution. CO3 To gain knowledge about natural resources and energy sources. To find and implement scientific, technological, economic and political solutions to the CO4 environmental problems. CO5 To understand the impact of environment on human population and human health. MAPPING OF COs WITH POs AND PSOs **PROGRAM SPECIFIC PROGRAM OUTCOMES (POs)** OUCOMES COs P01 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 PSO2 PSO3 CO1 3 3 2 2 3 3 3 3 2 2 2 3 2 1 2 CO2 3 2 3 3 2 3 3 3 3 2 2 3 2 2 2 2 2 1 3 2 2 2 CO3 3 3 2 3 3 2 2 1 3 3 3 3 1 2 3 3 2 2 2 2 2 2 CO4 1

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**TOTAL : 45 PERIODS** 

BE1251	BASIC ELECTRICAL, ELECTRONICS AND MEASUREMENT ENGINEERING	L	Т	Ρ	С
	(Common to CSE, AI-DS & IT)	3	0	0	3
OBJECTIVES					
<ul> <li>To lear</li> </ul>	n the fundamental laws, network theorems and analyse the electric circu	its.			
	ly the basic principles of electrical machines and their performance.				
	ly the fundamentals of power systems.				
	n the characteristics of various electron devices and Op Amp integrated				
<ul> <li>To und</li> </ul>	erstand the principle and operation of measuring instruments and transd	ucer	S.		
UNIT I	ELECTRIC CIRCUITS ANALYSIS				9
	irchhoff's Law-Instantaneous power - Series and parallel circuit: and				
	icitive and inductive network, star delta conversion, Nodal analysis and inductive network, star delta conversion, Nodal analysis and starter in the second starter is the second starter in the second starter is the secon				~
	ork theorems: Thevenin's theorem, Norton's theorem, superposition power transfer theorem. Three phase ac supply –Instantaneous power,			C	01
power and app	· · · · · · ·	nea	Clive		
UNIT II	ELECTRICAL MACHINES				9
DC and AC R	DTATING MACHINES: Types, Construction, principle, EMF and torque e	equa	tion,		
	eed Control. Basics of Stepper Motor and Brushless DC motors. Trans			С	02
	pes and construction, working principle of Ideal transformer, EMF equa	atior	n, All		<b>U</b> -
day efficiency	calculation.				1
	FUNDAMENTALS OF POWER SYSTEM				9
-	power system. Sources of electrical energy – Non-renewable, Rer	าคพส	able-		5
	ns: Batteries-Ni-Cd, Pb -Acid and Li-ion, SOC (State of Charge), DOD (				~~
	aracteristics. Utilization of electrical power - DC and AC load applic			C	03
Electric circuit	Protection-need for earthing, fuses and circuit breakers.				
					•
UNIT IV	ELECTRON DEVICES AND INTEGRATED CIRCUITS	0 0 1 1	otor	1	9
	/I Characteristics of Diode, Zener diode, Rectifiers, Zener voltage refigurations – CE amplifier - RC and LC oscillators. Op Amps			C	04
	and its applications.	-	200		04
UNIT V	MEASURING INSTRUMENTS AND TRANSDUCERS			<b>1</b>	9
	of measurement-errors in measurement – Principle and working of				
	oving Coil meter, Moving Iron meter, Energy meter and watt meter, Cath Transducers, thermo-electric, RTD, Strain gauge, LVDT, LDR		-	С	05
piezoelectric tr		ζ,	and		
	TOTAL	.:4	5 PEI	RIO	DS
TEXT BOOKS		-			
	otharti and I.J Nagarath, Basic Electrical and Electronics Engineering, Mo	Gra	aw Hi	II,	
	Edition, 2019 ukhija and T.K. Nagsarkar, Basic Electrical and Electronic Engineering, C	Dxfo	rd 20	16	
			•, =•		
REFERENCE					
	I Seksena and Kaustuv Dasgupta, Fundaments of Electrical Engineering	l, Ca	mbrio	dge	,
2016 2 BL Th	eraja, Fundamentals of Electrical Engineering and Electronics. S.Chand	8 Cr	200	18	
	hdev, Basic of Electrical Engineering, Pearson, 2015		, 200	.0.	
2. 2				r	
4. John B		n, E	lsevie	71.	
	ird, —Electrical and Electronic Principles and Technologyll, Fourth Editio dition,2017.	n, E	lsevie	,	
sixth eo 5. Mittle,N	ird, —Electrical and Electronic Principles and Technologyll, Fourth Editio dition,2017. /littal, Basic Electrical Engineeringll, 2nd Edition, Tata McGraw-Hill Editio	n, 20	016.		
sixth eo 5. Mittle,N 6. C.L.Wa	ird, —Electrical and Electronic Principles and Technologyll, Fourth Editio dition,2017.	n, 20	016.		٩ge

	SE OUT comple		-	cours	se. sti	udent	ts will	l be a	ble to	)					
CO1	•										al circu	its and	d to ana	lyze then	n
CO2	Ability t	o und	erstar	nd the	basio	c cons	structi	on an	d ope	rating	princip	le of d	c and ac	machine	es.
CO3	Ability to power.	o unc	lersta	nd the	e elec	trical	powe	er gen	eratio	n, ene	ergy sto	orage a	and utiliz	ation of	electric
CO4		o unc	lersta	nd the	e cha	racter	istics	of va	rious	electro	onic de	evices	and Op	Amp int	egrated
CO5	Ability	to und	lersta	nd the	e princ	ciples	and c	operat	ion of	meas	uring ir	nstrum	ents and	l transdu	cers.
				Μ	APPI	NG O	F CO	s WI	ГН РС	)s ANI	D PSO	S			
<u> </u>				PR	OGR/		UTCC	MES	(POs	;)				RAM SP OMES (	
COs	PO 1	PO 2	PO 3	РО 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
C01	3	3	3	3	1	1	1	2	3	2	1	2	3	1	2
CO2	3	3	3	3	1	1	1	2	3	2	1	2	3	1	2
CO3	3	3	3	3	1	1	1	2	3	2	1	2	3	1	2
CO4	3	3	3	3	1	1	1	3	3	3	1	3	3	1	3
CO5	3	3	3	3	1	1	1	2	3	2	1	2	3	1	2

CS1206	PROGRAMMING IN C	L	Т	Ρ	С
		3	1	0	3
OBJECTIVES					
	elop C Programs using basic programming constructs				
	elop C programs using arrays, strings and functions				
	elop applications in C using pointers				
	elop applications in C using structures and union				
<ul> <li>To dev</li> </ul>	elop applications using sequential and random-access fileprocessing.				
	BASICS OF C PROGRAMMING		l		ç
	of C: History of C; Compiler Vs. Interpreter, Structure of a C Program, Libra				
	piling a C Program; Basic data types , Modifying the basic data types, Val				
	rs, Storage class specifiers; Constants: Enumeration Constants; Key ecedence and Associativity; Expressions: Order of evaluation, Type convert			С	<u>_1</u>
•	• •				
	Casts; Input/Output statements; Assignment statements, Selection state ements; Jump statements; Expression statements; Pre-processor dire				
Compilation pr		ecun	ves.		
Compliation pi					
UNIT II	ARRAYS, STRINGS AND FUNCTIONS				ć
	o Arrays: Declaration, Initialization, Single dimensional array, Two dime	ensio	onal		
	Manipulations; String operations: length, compare, concatenate, copy; Fur			C	02
General form of	of a function, Function Arguments, Built-in functions, return statement, Rec	curs	ion		
UNIT III	POINTERS				9
•	I ONTERO				
Pointers: Dec	claring and defining pointers, Pointer operators, Pointer expression;				
Pointers: Dec Assignment, F	claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe	ers a	and		
Pointers: Dec Assignment, F Arrays: Array	claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Po	ers a	and		
Pointers: Dec Assignment, F Arrays: Array	claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe	ers a	and		
Pointers: Dec Assignment, I Arrays: Array Parameter pas	claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Po ssing: Pass by value, Pass by reference.	ers a	and		03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV	claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Po ssing: Pass by value, Pass by reference.	ers a oint	and ers;	C	
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> </ul>	oint Poir	and ers; nter	C	03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> <li>s; Array of structures; Passing Structure members</li> </ul>	ers oint Poir	and ers; nter	C (	03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointer of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> <li>s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structures; Self-reference</li> </ul>	ers oint Poir	and ers; nter	C (	03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> <li>s; Array of structures; Passing Structure members</li> </ul>	ers oint Poir	and ers; nter	C (	03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> <li>s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures, Interview of structures; Self-reference</li> </ul>	ers oint Poir	and ers; nter	C (	03 <u>9</u> 04
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures, Passing entire structure to functions; Arrays in Structures; Self-reference</li> <li>FILE PROCESSING</li> </ul>	Point Point nem	and ers; nter nber ntial	C(	03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointer of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures, Passing entire structure to functions; Arrays in Structures; Self-reference</li> <li>FILE PROCESSING</li> <li>Basics: File Pointer, Opening and Closing a File; Reading and Writing Character</li> </ul>	Point Point Point Point Point Point Point Point Point Point Point Point	and ers; nter ber ntial		03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B Working with	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures; Self-reference</li> <li>FILE PROCESSING</li> <li>Basics: File Pointer, Opening and Closing a File; Reading and Writing Chasters; fputs() and fgets(); rewind(); ferror(); fread() and fwrite(); Erasin</li> </ul>	Pointer Pointe	and ers; nter ber ntial		03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B Working with Types of file p	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures;</li> <li>s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, and closing a File; Reading and Writing Chassics: File Pointer, Opening and Closing a File; Reading and Writing Chassing: fputs() and fgets(); rewind(); ferror(); fread() and fwrite(); Erasing processing: Sequential access; Random access: fprintf() and fscanf(), fsee</li> </ul>	Pointer Pointe	and ers; nter ber ntial		03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B Working with Types of file p	<ul> <li>claring and defining pointers, Pointer operators, Pointer expression;</li> <li>Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Possing: Pass by value, Pass by reference.</li> <li>STRUCTURES AND UNIONS</li> <li>cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure members, Structures to Functions: Passing structure members, Structures; Self-reference</li> <li>FILE PROCESSING</li> <li>Basics: File Pointer, Opening and Closing a File; Reading and Writing Chasters; fputs() and fgets(); rewind(); ferror(); fread() and fwrite(); Erasin</li> </ul>	Point Point Point rerer aracong fi ek()	and ers; nter hber ntial cter; and		03
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B Working with Types of file p	Claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Pointers ssing: Pass by value, Pass by reference.           STRUCTURES AND UNIONS           cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure memory allocation ; typedef statement, , Union and Enumeration           FILE PROCESSING           Basics: File Pointer, Opening and Closing a File; Reading and Writing Chastring: fputs() and fgets(); rewind(); ferror(); fread() and fwrite(); Erasin processing: Sequential access; Random access: fprintf() and fscanf(), fsee and line arguments.	Point Point Point rerer aracong fi ek()	and ers; nter hber ntial cter; and		03 9 04 9 05
Pointers: Dec Assignment, F Arrays: Array Parameter pas UNIT IV Structure: Acc and Structures to function, F structures; Dyr UNIT V File System B Working with Types of file p ftell(); Comma	Claring and defining pointers, Pointer operators, Pointer expression; Pointer Conversions, Pointer arithmetic, Pointer Comparisons; Pointe of pointers; Multiple Indirection; Pointers to function; Problems with Pointers ssing: Pass by value, Pass by reference.           STRUCTURES AND UNIONS           cessing Structure members, Structure Assignments; Nested structures; s; Array of structures; Passing Structures to Functions: Passing structure memory allocation ; typedef statement, , Union and Enumeration           FILE PROCESSING           Basics: File Pointer, Opening and Closing a File; Reading and Writing Chastring: fputs() and fgets(); rewind(); ferror(); fread() and fwrite(); Erasin processing: Sequential access; Random access: fprintf() and fscanf(), fsee and line arguments.	Point Point Point rerer aracong fi ek()	and ers; nter hber ntial cter; and		03
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## COURSE OUTCOMES

Upon	completion of the course, students will be able to
CO1	Develop simple applications in C using basic constructs.
CO2	Design and implement applications using arrays, strings and functions.
CO3	Develop and implement applications in C using pointers.
CO4	Develop applications in C usingstructures and union.
CO5	Design applications using sequential and random-access fileprocessing.

COs				PR	OGRA		UTCO	MES	(POs	)			PROGRAM SPECIFIC OUTCOMES (PSOs)			
COS	РО 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3	
CO1	3	3	3	2	2	1	1	1	1	1	1	1	2	2	2	
CO2	3	3	3	2	2	1	1	1	1	1	1	1	2	2	2	
CO3	3	3	3	2	2	1	1	1	1	1	1	1	2	2	2	
CO4	3	3	3	2	2	1	1	1	1	1	1	1	2	2	2	
CO5	3	3	3	2	2	1	1	1	1	1	1	1	2	2	2	

GE 12	07	ENGINEERING PRACTICES LAB	Т	С
			4	2
<b>DBJE</b>	CTIVE	S:		
•	To pro	ovide exposure to the students with hands on experience on various basic engineer	ing	
	praction	ces in Civil, Mechanical, Electrical and Electronics Engineering		
LIST C	OF EXF	PERIMENTS		
GROU	PA(C	IVIL & MECHANICAL)		
I	CIVIL	ENGINEERING PRACTICE 13		
	Build	•		
	(a)	Study of plumbing and carpentry components of residential and industrial		
		buildings. Safety aspects.		
		bing Works:		
	(a)	Study of pipeline joints, its location and functions: valves, taps, couplings,		
		unions, reducers, elbows in household fittings.		
	(b)	Study of pipe connections requirements for pumps and turbines.	С	0
	(C)	Preparation of plumbing line sketches for water supply and sewage works.		2
	(d)	Hands-on-exercise:		
		Basic pipe connections – Mixed pipe material connection – Pipe connections		
	( )	with different joining components.		
	(e)	Demonstration of plumbing requirements of high-rise buildings.		
	-	entry using Power Tools only:		
	(a)	Study of the joints in roofs, doors, windows and furniture.		
	(b)	Hands-on-exercise:		
	MECI	Wood work, joints by sawing, planing and cutting. <b>IANICAL ENGINEERING PRACTICE</b> 18		
	(a) (b) <b>Sheet</b> (a) (b) (c) <b>Mach</b> (a) (b)	Preparation of butt joints, lap joints and T- joints by Shielded metal arc welding. Gas welding practice <b>Machining:</b> Simple Turning and Taper turning Drilling Practice <b>Metal Work:</b> Forming & Bending: Model making – Trays and funnels. Different type of joints. <b>ine assembly practice:</b> Study of centrifugal pump Study of air conditioner <b>onstration on:</b> Smithy operations, upsetting, swaging, setting down and bending. Example –Exercise – Production of hexagonal headed bolt. Foundry operations like mould preparation for gear and step cone pulley. Fitting – Exercises – Preparation of square fitting and V – fitting models.	С	0
	P B (E	LECTRICAL & ELECTRONICS)		
<u>GROU</u>		TRICAL ENGINEERING PRACTICE 13		
	ELEC		1	
	-			
	1.	Residential house wiring using switches, fuse, indicator, lamp and energy meter.		<u> </u>
	1. 2.	Fluorescent lamp wiring.	С	0
	1.		С	0

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IV E	LECTRONICS ENGINEERING PRACTICE 16	
1		oding
	measurement of AC signal parameter (peak-peak, rms period, frequency)	
	CR.	C
2		
3	0	
4		eneral
	purpose PCB. Measurement of ripple factor of HWR and FWR.	
		60 PERIO
ST OF	EQUIPMENT FOR A BATCH OF 30 STUDENTS	
		Quanti
.No.	Description of Equipment	require
	CIVIL	
	Assorted components for plumbing consisting of metallic pipes, plastic pipes,	45
1.	flexible pipes, couplings, unions, elbows, plugs and other fittings.	15 sets
2.	Carpentry vice (fitted to work bench)	15 Nos
3.	Standard woodworking tools 15 Sets.	15 Sets
4.	Models of industrial trusses, door joints, furniture joints	5 each
	Power Tools:	
	(a) Rotary Hammer	
	(b) Demolition Hammer	
5.	(c) Circular Saw	2 Nos
	(d) Planer	
	(e) Hand Drilling Machine	
	(f) Jigsaw	
	MECHANICAL	
1.	Arc welding transformer with cables and holders.	5 Nos
2.	Welding booth with exhaust facility.	5 Nos
3.	Welding accessories like welding shield, chipping hammer, wire brush, etc.	5 Sets
4.	Oxygen and acetylene gas cylinders, blow pipe and other welding outfit.	2 Nos
5.	Centre lathe.	2 Nos
6.	Hearth furnace, anvil and smithy tools.	2 Sets
7.	Moulding table, foundry tools.	2 Sets
8.	Power Tool: Angle Grinder.	2 Nos
9.	Study-purpose items: centrifugal pump, air-conditioner.	1 each
	ELECTRICAL	
1.	Assorted electrical components for house wiring.	15 Set
2.	Electrical measuring instruments.	10 Sets
	Study purpose items: Iron box, fan and regulator, emergency lamp.	1 each
3.	Megger (250V/500V).	1 No.
3. 4.		
3. 4.	Power Tools	
4.	Power Tools: (a) Range Finder	2 Nos
	Power Tools: (a) Range Finder (b) Digital Live-wire detector	2 Nos
4.	<ul><li>(a) Range Finder</li><li>(b) Digital Live-wire detector</li></ul>	2 Nos
4. 5.	(a) Range Finder (b) Digital Live-wire detector ELECTRONICS	2 Nos
4.	<ul><li>(a) Range Finder</li><li>(b) Digital Live-wire detector</li></ul>	

3.	Sma	II PCE	Bs.											10	) Nos.
4.	Mult	imete	rs											1(	) Nos.
5.	Stud	dy pu	rpose	e item	<b>s:</b> Te	lepho	ne, Fl	M rad	io, lov	v-volta	ge pov	ver sup	oply	1	each
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COURS	SE OUT	СОМ	ES												
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COs CO1	<b>PO1</b>	-	-	PO	PO	РО	PO	PO	PO	PO		-		OMES (	PSOs)
		-	3	PO	PO 5	PO 6	PO	PO	PO	PO		12	PSO1	OMES ( PSO2	PSOs) PSO3
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CO1 CO2	3 3	<b>2</b> 1 2	<b>3</b> 3 3	PO	PO 5 -	<b>PO</b> 6 3 3	PO 7 - -	PO	PO	PO		<b>12</b> 3 3	<b>PSO1</b> 3 3	OMES ( PSO2 3 3	<b>PSOs)</b> <b>PSO3</b> 3 3

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10. R	ealtim	e app	licatio	on usi	ng str	ucture	es and	d unic	ons.							
										lom-ac	cess fi	ile.				CO3
12. S	olving	probl	ems v	with c	omma	and lir	ie arg	umen	nt.							
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OBJECTIVES       • To understand the basic concepts of probability, one and two dimensional random variables and to introduce some standard distributions applicable to engineering which can describe real life phenomenon.         • To understand the basic concepts of random processes which are widely used in engineering applications.       • To acquaint the knowledge of testing of hypothesis for small and large samples, which plays an important role in real life problems.         • To introduce the basic concepts of classifications of design of experiments which plays very important roles in the field of agriculture and statistical quality control.       12 <b>UNIT I PROBABILITY AND RANDOM VARIABLES</b> 12         Probability – The axioms of probability – Conditional probability – Baye's theorem - Discrete andcontinuous random variables – Moment generating functions – Binomial, Poisson, Geometric, Uniform, Exponential and Normal distributions.       C01 <b>UNIT II TWO - DIMENSIONAL RANDOM VARIABLES</b> 12         Joint distributions – Correlation and linearregression – Central limit theorem (for independent and identically distributed random variables).       12         UNIT II <b>RANDOM PROCESSES</b> 12         Classification – Stationary process – Markov process - Poisson process – Discrete parameter Markov chain – Chapman Kolmogorov equations – Limiting distributions.       12         UNIT II <b>RANDOM PROCESSES</b> 12         Classification – Statistical hypothesis - Large sample tests based on norm distributions for mean, variance and proportion - Con	MA1354	PROBABILITY AND BAYESIAN INFERENCE			-	
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important roles in the field of agriculture and statistical quality control.         UNIT I       PROBABILITY AND RANDOM VARIABLES       12         Probability – The axioms of probability – Conditional probability – Baye's theorem - Discrete andcontinuous random variables – Moments – Moment generating functions – Binomial.       CO1         Poisson, Geometric, Uniform, Exponential and Normal distributions.       12         Joint distributions – Marginal and conditional distributions – Covariance – Correlation and linearregression – Central limit theorem (for independent and identically distributed random variables).       CO2         UNIT II       RANDOM PROCESSES       12         Classification – Stationary process – Markov process - Poisson process – Discrete parameter Markov chain – Chapman Kolmogorov equations – Limiting distributions.       CO3         UNIT IV       TESTING OF HYPOTHESIS       12         Sampling distributions for mean, variance and proportion - Contingency table (test for independent) – Goodness of fit.       12         UNIT V       BAYESIAN INFERENCE       12         Bayesian Inference for Discrete random variables - Bayesian Inference for Continous random variables - Bayesian Inference for Continous random variables - Bayesian Inference for Discrete random variables - Bayesian Inference for Continous random variables - Bayesian Inference for Continous random variables - Bayesian Inference for Discrete random variables - Bayesian Inference for Continous random variables - Bayesian Inference for Discrete random variables - Bayesian Inference for Contino	<ul> <li>To acquire</li> <li>importa</li> </ul>	uaint the knowledge of testing of hypothesis for small and large samples, int role in real life problems.			•	
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<ul> <li>variables – Bayesian Inference for Binomial proportions - Comparing Bayesian and Frequentist inferences for proportion.</li> <li>CO5</li> <li>TEXT BOOKS</li> <li>1. Johnson, R.A., Miller, I and Freund J., "Miller and Freund's Probability and Statistics forEngineers", Pearson Education, Asia, 9th Edition, 2017.</li> <li>2. Ibe, O.C., —Fundamentals of Applied Probability and Random Processes", Elsevier, 2nd Indian Reprint, 2014.</li> <li>3. Bolstad, W. M., Curran, J. M. Introduction to Bayesian Statistics. : Wiley. (Unit V Chapter 6, 7, 8 and 9), Wiley, 2016</li> <li>REFERENCE BOOKS</li> <li>1. Hwei Hsu, "Schaum's Outline of Theory and Problems of Probability, Random Variables and Random Processes", Tata McGraw Hill Edition, New Delhi, 2017.</li> <li>2. Yates, R.D. and Goodman. D. J., "Probability and Stochastic Processes", 2nd Edition, Wiley India Pvt. Ltd., Bangalore, 2014.</li> <li>3. Papoulis, A. and Unnikrishnapillai, S., "Probability, Random Variables and Stochastic</li> </ul>				-1		12
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	India P	vt. Ltd., Bangalore, 2014.				•
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- 4. Ross, S.M., "Introduction to Probability and Statistics for Engineers and Scientists", 4thEdition,Elsevier, 2009.
- 5. Spiegel. M.R., Schiller. J. and Srinivasan, R.A., "Schaum's Outline of Theory and Problems of Probability and Statistics", Tata McGraw Hill Edition, 2008.

### COURSE OUTCOMES Upon completion of the course, students will be able to The course gives exposure to random variables and well-founded knowledge of standard CO1 distributions which can describe real life phenomena. CO2 The course paves ideas to handle situations involving more than one random variable and functions of random variables. CO3 The course gives an understanding and characterizes phenomena which evolve with respect to time in a probabilistic manner and modelling the real life phenomena. CO4 Students will gain the knowledge on Large Samples and Samples. These concepts are very useful in biological, economical and social experiments and all kinds of generalizations based on information about a smaller sample and larger samples. Apply the appropriate test in the problems related with sampling. Students will be able to do design of experiments, carry them out, and analyze the data. CO5 MAPPING OF COs WITH POs AND PSOs **PROGRAM SPECIFIC** PROGRAM OUTCOMES (POs) OUTCOMES (DSOc)

COs															r303j
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	1	-	-	-	-	1	1	3	2	1
CO2	3	3	2	2	2	1	-	-	-	-	1	1	3	2	1
CO3	3	2	2	1	1	1	-	-	-	-	1	1	3	2	1
CO4	3	3	2	3	3	2	1	-	-	-	2	2	3	2	1
CO5	3	3	2	3	2	2	1	-	-	-	1	2	2	1	1

CS1302	DATA STRUCTURES L T	Ρ	С
	(Common to CSE, AI-DS & IT ) 3 1	0	3
OBJECTIVES			
<ul> <li>To und</li> </ul>	lerstand the concepts of ADTs.		
<ul> <li>To lear</li> </ul>	n linear data structures like lists, stacks, and queues.		
<ul> <li>To lear</li> </ul>	n Non-linear tree data structures.		
<ul> <li>To app</li> </ul>	ly Graph structures		
<ul> <li>To und</li> </ul>	lerstand sorting, searching and hashing algorithms		
UNIT I	LINEAR DATA STRUCTURES – LIST		g
implementatio	a Types (ADTs) – List ADT – array-based implementation – linked list n — singly linked lists- circularly linked lists- doubly-linked lists – applications of nial Manipulation – All operations (Insertion, Deletion, Merge, Traversal).		01
	LINEAR DATA STRUCTURES – STACKS, QUEUES		g
to postfix expr – applications	ession – Queue ADT – Operations – Circular Queue – Priority Queue – deQueue of queues.	C	02
UNIT III	NON LINEAR DATA STRUCTURES – TREES		g
	ree traversals – Binary Tree ADT – expression trees – applications of trees – tree ADT –Threaded Binary Trees- AVL Trees – B-Tree – B+ Tree – Heap – f heap.	С	03
	NON LINEAR DATA STRUCTURES – GRAPHS		g
	epresentation of Graph – Types of graph – Breadth-first traversal – Depth-first pological Sort – Bi-connectivity – Cut vertex – Euler circuits – Applications of		04
	SEARCHING, SORTING AND HASHING TECHNIQUES		9
	near Search – Binary Search. Sorting – Bubble sort – Selection sort – Insertion sort – Radix sort. Hashing- Hash Functions – Separate Chaining – Open	С	05
sort – Shell	Rehashing – Extendible Hashing.		

### **TEXT BOOKS**

- 1. Mark Allen Weiss, —Data Structures and Algorithm Analysis in Cll, 2nd Edition, Pearson Education, 1997.
- 2. Reema Thareja, —Data Structures Using CII, Second Edition, Oxford University Press, 2011.
- 3. Michael T. Goodrich, Roberto Tamassia, Michael H. Goldwasser, Data Structures and Algorithms in Python, Wiley, 2013.
- 4. Bradley N. Miller, David L. Ranum, "Problem Solving with Algorithms and Data Structures using Python", Second Edition, 2013.
- 5. Rance D. Necaise, Data Structures and Algorithms Using Python, John Wiley & Sons, 2011.

### **COURSE OUTCOMES**

### Upon completion of the course, students will be able to

CO1	Implement abstract data types for linear data structures.
CO2	Apply the different linear data structures to problem solutions.
CO3	Implement abstract data types for non-linear data structures.
CO4	Apply Graph data structure for the real world problems.
	Critically analyze the various sorting, searching algorithms and hash functions that result in a
CO5	collision free scenario for data storage and retrieval.

COs					PROGRAM SPECIFIC OUTCOMES (PSOs)										
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	2	2	2	-	-	-	2	2	2	3	3	3
CO2	3	3	3	2	2	2	-	-	-	2	2	2	3	3	3
CO3	3	3	3	2	2	2	-	-	-	2	2	2	3	3	3
CO4	3	3	3	2	2	2	-	-	-	2	2	2	3	3	3
CO5	3	3	3	2	2	2	-	-	-	2	2	2	3	3	3

	INTRODUCTION TO ARTIFICIAL INTELLIGENCE	Т	Ρ	С
	Common to AI & DS 3	0	0	3
OBJECTIVES				
•	art basic knowledge about Artificial Intelligence			
	n the methods of solving problems using Artificial Intelligence			
	n to represent knowledge in solving Alproblems			
	erstand the concept of Planning in various situations			
<ul> <li>To und</li> </ul>	erstand the application of AI namely Expert Systems			
UNIT I	INTRODUCTION			
	efinition – Foundation and History of AI - Future of Artificial Intelligence nts– Environments – Structure of Agents - Typical Intelligent Agents	e –	С	0
	PROBLEM SOLVING METHODS			1
	ng Methods - Search Strategies- Uninformed - Informed - Heuristics - Lo			
Search Algori Constraint Sa	thms and Optimization Problems - Searching with Partial Observation tisfaction Problems – Constraint Propagation - Backtracking Search - Ga mal Decisions in Games – Alpha - Beta Pruning	s -	С	02
UNIT III First Order Dra	KNOWLEDGE REPRESENTATION	( <b>0</b> rd		1
Chaining – Re Objects – Time	edicate Logic – Prolog Programming – Unification – Forward Chaining-Backw solution – Knowledge Representation - Ontological Engineering-Categories e and Event Calculus - Mental Events and Mental Objects - Reasoning Syste – Reasoning with Default Information	and	С	0
<del></del>				
planning – Co	PLANNING oduction – Planning Problem – Planning with State Space Search - Partial Or Instruction and Use of Planning Graphs - Conditional Planning – Continu Iti Agent Planning		С	:04
UNIT V	EXPERT SYSTEMS			
Expert system	hs – Architecture of expert systems, Roles of expert systems – Knowle Meta knowledge, Heuristics. Typical expert systems – MYCIN, DART, XO0 s shells.	ЭŇ,		0
	TOTAL : 45	PER	20	D
	sell and P. Norvig, "Artificial Intelligence: A Modern Approach, Prentice		ТЬ	air
	• • •	⊓ali,	11	ш
Edition 2. Dan W 2006.	. Patterson - Introduction to Artificial Intelligence and Expert Systems, PHI,	New	De	۱h
REFERENCE	BOOKS			_
1. M. Tir Bartlett 2. Nils J. 3. I. Brat Educat	n Jones - Artificial Intelligence: A Systems Approach(Computer Science), Publishers, Inc.; First Edition, 2008. Nilsson - The Quest for Artificial Intelligence, Cambridge University Press, to - Prolog: Programming for Artificial Intelligence, Fourth edition, Addis ional Publishers Inc., 2011. ackson, "Introduction to Expert Systems", 3rd Edition, Pearson Education, 200	2009 on-V		

### **COURSE OUTCOMES**

### Upon completion of the course, students will be able to

CO1 Implement basic AI Algorithms

CO2 Use appropriate search algorithms to solve AI based problems

CO3 Represent a problem using first order and predicatelogic

CO4 Design a simple agent system with associated planning technique.

CO5 Apply AI techniques to real-world problems to develop expert system

COs				PR	OGR/	AM O	UTCC	MES	(POs	PROGRAM SPECIFIC OUTCOMES(PSOs)					
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	2	-	-	1	2	2	3	3	3	3
CO2	3	3	3	3	3	2	-	-	1	2	2	3	3	3	3
CO3	3	3	3	3	3	2	-	-	1	2	2	3	3	3	3
CO4	3	3	3	3	3	2	-	-	2	2	2	3	3	3	3
CO5	3	3	3	3	3	2	-	-	2	2	2	3	3	3	3

ML1301         DATA FOUNDATION         L         T         P         C           OBJECTIVES					
			3	0	0
•	•				
• Io uno	derstand distinct analysis tools and practice ethical decision and actions.				
					9
Discrete and Concepts of Social Media	Continuous) Big Data: Structured, Unstructured and semi-structured - Me metadata – Types of metadata – Uses Data Source: Enterprise Data Data Source, Public Data Source – Web Scrapping- Basic Concepts	etac Soι	lata: irce,	С	:01
					9
Imputation of Discretization Process. Sign	Missing values - Data cleaning - Data Reduction, Data Transformation at Exploratory Data Analysis (EDA) – Philosophy of EDA - The Data nificance of EDA in data science - Basic tools (plots, graphs and se	nd I Scie	Data ence		:02
					_
					9
Centre of Exc Quality- Data	ellence Model – Roles and Responsibilities- Data GovernanceData Priva Extraction-Extraction and ETL(Extract,Load,Transform)-Types- Physical -	cy-l	Data		:03
	Data Analysis and Visualization				9
table-lookup Modelling- for Visualizations	functions-Data visualizations for quantitative and qualitative data- char ecast models using advanced lookup and data validation tools. Tableau: ( in Tableau-Data hierarchies, filters, groups, sets, calculated fields-Map	ts-E Crea	xce	C	:04
	ETHICS AND RECENT TRENDS				Q
		=thi	<u>- 25</u>		J
					:05
· · ·	TOTAL	: 4!	5 PE	RIC	DS
	<ul><li>Publications Co., 1st edition,2016.</li><li>2. Ethics and Data Science, D J Patil, Hilary Mason, Mike Loukides, O' R</li></ul>				g
Muelle	r, Sarah Guido,O'Reilly; 1st edition, October 2016.	•			
	i June, 2019	uD	1311	''y, <i>'</i>	

COURSE	OUT	СОМ	ES												
Upon co	mplet	ion o	f the	cours	se, st	udent	ts wil	l be a	ble to	)					
CO1 Ex	kplore	the fu	undar	nenta	l conc	epts	of Dat	ta scie	ence						
CO2 UI	nderst	tand [	Data S	Scienc	ce Pro	cess	and T	ools	of ED	A					
CO3 Ad	ddress	s how	Orga	nizati	onal s	structu	ure's i	nfluer	nce ef	ficienc	y and e	effectiv	eness.		
CO4 Ar	nalyse	e and	Valida	ate da	ita usi	ng Sp	bread	sheet	s and	Tablea	au.				
								privac	cy, da	ta sha	aring a	nd de	cision-ma	aking an	d Build
in	teract	ive da	shbo	ards f	or Bu	sines	S								
				Μ		NG O	F CO	s WI	TH PC	)s AN[	D PSO	s			
COs				PR	OGR/		UTCC	MES	(POs	5)				RAM SP OMES (	
COS	РО 1	PO 2	PO م	PO 4	РО 5	P0 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO2	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO3	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO4	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO5	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2

ML1302	OBJECT ORIENTED SOFTWARE ENGINEERING	Ρ	С
	Lab Integrated 3 0	2	4
progra Inherit • Desigr and sp • To pr		uctui ulati	on eds
UNIT I	JAVA FUNDAMENTALS-OBJECTS, CLASSES AND INTERFACES	9	)+6
Operators and Objects - Imp – Abstract Cla - Object: The LAB COMPO • Create differe and C abstra • Create metho having rectan param 'super	<ul> <li>Va - Java buzzwords- JVM architecture – Data Types and Literals in Java- d Control Statements in Java - ArrayList - Strings and StringBuffer - Working with lementing Classes - Static Variables and Methods – Packages - Nested Classes ass- Interfaces –Local and Anonymous Classes – Inheritance – Extending a class Cosmic Superclass – Wrapper classes – Object Cloning.</li> <li>NENT:</li> <li>a an abstract class Shape with a abstract method area() to find the area of nt shapes and a instance variable radius. Extends the Shape class by Cylinder one class with appropriate members and methods to find the volume of cylinder one. Write a driver class ShapeDemo with main method in JAVA to implement the ction and display the volume of the shapes.</li> <li>a class named 'Rectangle' with two data members 'length' and 'breadth' and two ds to print the area and perimeter of the rectangle respectively. Its constructor parameters for length and breadth is used to initialize length and breadth of the gle. Let class 'Square' inherit the 'Rectangle' class with its constructor having a eter for its side (suppose s) calling the constructor of its parent class as (s,s)'. Print the area and perimeter of a rectangle and a square. And repeat the example to print the area of 10 squares.</li> </ul>	C	01
UNIT II	EXCEPTION, IO STREAMS AND CONCURRENT PROGRAMMING	9	)+(
Exceptions – Streams- Thr Priorities - Syn LAB COMPO • Write a whites • Deduct Each t will find Maxim	<ul> <li>andling - The Exception Hierarchy – Keywords – Checked and unchecked User defined Exceptions - Input/Output Streams- Byte Streams, Character eads – Multithreaded Programming – Thread Creation – Life Cycle – Thread nchronization of Threads.</li> <li><b>NENT:</b></li> <li>a Java program to count the number of characters, count, sentences, paragraphs, paces in a file</li> <li>be a Java program to perform the following tasks using three different threads.</li> <li>thread will be responsible for its own task only. Among these three threads one d the average number of the input numbers, one will be responsible for finding the number from the input array of numbers, and one will be responsible for its of numbers.</li> </ul>		02
		+	)+(
UNIT III	PLANNING & SCHEDULING	9	/+(

Development - Software Requirements Specification, Software prototyping - Software proj planning - Scope - Resources - Software Estimation - Empirical Estimation Models – Plann	
<ul> <li>Risk Management - Software Project Scheduling - Object Oriented Estimation &amp; Schedulin LAB COMPONENT:</li> <li>To Perform Software Requirement Specification of the specified problem and draw a flow characteristic spe</li></ul>	ing g.
<ol> <li>Health Care</li> <li>Airlines</li> <li>Education</li> </ol>	
UNIT IV ANALYSIS AND DESIGN	9+6
Analysis Modeling - Data Modeling - Functional Modeling & Information Flow - Behavior Modeling-Structured Analysis - Object Oriented Analysis - Domain Analysis-Object orient Analysis process - Object Relationship Model - Object Behaviour Model, Design modelling w UML. Design Concepts & Principles - Design Process - Design Concepts - Modular Desig Design Effective Modularity - Introduction to Software Architecture - Data Design - Transfor Mapping - Transaction Mapping - Object Oriented Design - System design process - Obj design process - Design Patterns	ted /ith n - prm
LAB COMPONENT:	CO4
<ul> <li>Understanding different actors and use-cases in detail of the specified problestatement and draw it using StarUML</li> </ul>	em
<ul> <li>To draw the structural view diagram: Class diagram of specified problem statem using StarUML</li> </ul>	ent
<ul> <li>To draw the Behavioral View diagram: State Chart diagram and Activity diagram, us StarUML</li> </ul>	ing
<ul> <li>To draw Component and Deployment diagram using StarUML</li> </ul>	
UNIT V IMPLEMENTATION, TESTING AND MAINTENANCE	9+6
Top - Down, Bottom-Up, object oriented product Implementation & Integration. Software Testing methods-White Box, Basis Path-Control Structure - Black Box - Unit Testing Integration testing - Validation & System testing - Testing Tools –JUNIT testing- Software Maintenance & Reengineering.	g -
LAB COMPONENT:	
<ul> <li>Implement the system as per the detailed design</li> <li>Write the test cases and create test plan document for the given system.</li> <li>Study of any Open Source Testing tool( Example Testlink)</li> </ul>	CO5
<ul> <li>Study of Web testing tool( Example Selenium)</li> <li>Study of Bug tracking tool ( Example bugzilla)</li> <li>Study of any Test Management tool ( Example Testdirector)</li> </ul>	
PRACTICALS: 30	PERIODS
THEORY: 45 TOTAL : 75	
<b>TEXT BOOKS</b> 1. Cay S. Horstmann, "Core Java SE 9 for the Impatient", 2nd Edition, Addison-Wesley,	2017 .
<ol> <li>Roger. S. Pressman and Bruce R. Maxim, "Software Engineering – A Practitioner's A</li> </ol>	Approach",

DEEE				<u> </u>												
REFEI 1. 2.	He C > Gra Gu	rbert Kavie ady ide"	schil er , "Ja Booc - Ado	dt , "T ava P h, Ja	rograi mes Wesle	mming Rumb ey, 19	g – A baugh 999. 4	Pract , Ivar . Ali I	ical A Jaco Bahra	pproa obson	ch", Ta - "th	ata Mc e Unif	Graw- ied M	Hill Editio	v Delhi. 2 on, 2011 Languag evelopme	e User
COUR	SE	OUT	СОМ	ES												
Upon	com	plet	ion o	f the	cours	se, st	udent	ts will	l be a	ble to	)					
CO1	Uno	derst	and t	he fur	ndame	ental i	deas	behin	d the	objec	t orien	ted ap	proach	to prog	ramming	].
CO2	An	A modern coverage of concurrent programming that focuses on high-level synchronization														
	Со	Constructs.														
CO3	Uno	derst	and s	oftwa	re de	velop	ment	proce	ess mo	odels						
CO4						•		•	IL diag							
CO5					•							nariso	n of va	rious tos	ting tech	niques
000	T(C)	oogn	120 11		meag			Sungi				panso				inques
												D PSO				
									MES			5-30	3		RAM SP	
COs	-	PO	PO	PO	PO	PO	PO	PO	PO	、 PO	, PO	PO	PO		UCOME	
		1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
CO1		1	1	1	1	1	1	-	-	1	1	1	1	2	1	1
CO2		1	1	1	1	1	1	-	-	1	1	1	1	2	1	1
CO3	;	1	2	2	1	1	1	-	-	2	1	2	1	1	1	1
CO4		1	2	2	1	2	1	1	1	2	1	2	1	1	1	1
CO5	5	1	1	1	1	2	-	1	1	2	1	2	1	1	1	1

ML1303	OPTIMIZATION FOR MACHINE LEARNING L T	Ρ	C
OBJECTIVE	<u>3</u> 0	0	3
	ver the core concepts of continuous optimization		
<ul> <li>To lease</li> </ul>	arn about unconstrained and constrained optimization problems.		
	arn methods and algorithms for both convex and non-convex optimization settings		
UNIT I			1
Mathematica	l optimization - Least-squares problem – Linear programming - Role of		
optimization,	Convex optimization - Non-linear optimization - Local and global optimization -	С	<b>O</b>
Convexity, E	xamples		
UNIT II	CONVEX SETS AND FUNCTIONS		1
Affine and C	Convex sets - Operations that preserve convexity - Generalized inequalities -	Τ	
Separating I	nyper-plane theorem - Convex functions – Basic properties and examples -	С	0
Conjugate fu	nction, conjugate sets.		
	CONVEX OPTIMIZATION PROBLEMS		
Definition an	d examples - Optimization problems - Convex optimization - Linear optimization -		
	otimization problems - Geometric programming - Semi-definite programming -		:0
•			.0
Generalized	inequality constraints - Vector optimization .		1
	DUALITY		
	y - Lagrange dual function - Lagrange dual problem – Geometric Interpretation -		
•	rong duality – Saddle point interpretation- Interpretation of dual variables - KKT		0
	nditions for non-convex and convex problems.		
optimality co			
	METHODS AND ALGORITHMS		
	d minimization: Descent methods -Gradient descent method - Steepest descent		
	wton methods – Convergence Analysis.	С	0
	TOTAL : 45 PE		
			<u> </u>
	ghui Lan, Lectures on Optimization - Methods for Machine Learning, 2019.	_	
•	en Boyd and Lieven Vandenberghe, Convex Optimization, Cambridge University	Pre	es
2004.			
REFERENC	EBOOKS		
1. Dimit	i P. Bertsekas, Convex Analysis and Optimization, Athena-Scientific, 2003	_	_
	roy Introductory Locturos on Convey Optimization: A Pasia Course, Springer, 200	3	
	rov, Introductory Lectures on Convex Optimization: A Basic Course, Springer, 200		
2. Neste	on Ben-Tal and Arkadi Nemirovski, Lectures on Modern Convex Optimization, 2001		

COUR	RSE OUTCOMES
Upon	completion of the course, students will be able to
CO1	Know basic terminology and concepts in convex optimization.
CO2	Understand the foundations of classic continuous optimization problems, in particular
	identifying convexity, smoothness, feasible region, and dual reformulation.
CO3	Design and analyze optimization algorithms for convex optimization problems.
CO4	Use duality and decomposition for parallelization of optimization algorithms.
CO5	Solve standard convex optimization problems arising in various scientific and engineering
	applications.

COs				PR	OGR		UTCC	MES	(POs	5)				PECIFIC (PSOs)	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	-	2	-	1	-	-	-	2	1	1	1	1	1	1
CO2	2	-	2	-	1	-	-	-	2	1	1	1	1	1	1
CO3	2	1	2	1	1	1	-	-	2	1	1	2	2	2	2
CO4	2	1	2	1	1	1	-	-	2	1	1	2	2	2	2
CO5	2	2	2	2	1	1	-	1	2	2	2	2	2	2	2

DS1307	DATA STRUCTURE LABORATORY USING PYTHONLT	P C
	Common for AI-DS 0 0	4 2
OBJECTIVE		
	oduce the concepts of primitive data structures.	
	lerstand the process in linear and non-linear data structures.	
	oduce the concepts of sorting, searching and hashing.	
LIST OF EXH		
1. IMPLI	MENTATION OF LIST	
Write Python p	programs to	
	Array implementation of Stack ADTs.	
b)	Array implementation of Queue ADTs.	
2. LIST ADT		
Array	implementation of List ADT.	C01
3. IMPLEME	ENTATION OF STACK AND QUEUE	
Write Python p	programs to	
a)	Design and implement Single Linked List.	
b)	Design and implement Stack and its operations using List.	
c)	Design and implement Queue and its operations using List.	
4. APPLICA	TIONS OF LINEAR DATA STRUCTURE	
Write Python p	rograms for the following:	
a)	Design and implement polynomial ADT using list	
b)	Uses Stack operations to convert infix expression into postfix expression.	
c)	Uses Stack operations for evaluating the postfix expression.	CO2
5. APPLICA	TIONS OF TREE	
a)	Write a Python program to Design and implement binary tree.	
b)	Traverse the above binary tree recursively in pre-order, post-order & in-order.	
6. IMPLEME	INTATION OF TREE	
Write a Python	program to Design and implement binary search tree.	
7. IMPLEME	INTATION OF ADVANCED TREE	
a)	Design and Implement AVL tree using Templates.	CO3
b)	Design and Implement heap tree using Templates.	
8. IMPLEME	ENTATION OF SHORTEST PATH ALGORITHMS	
Write Python	programs for the following:	CO3
	Design and Implement Dijkstra's algorithm	
b)	Design and Implement Floyd Warshall algorithm.	
-	ENTATION OF MINIMUM SPANNING TREE	
-	programs for the following:	
a)		
b)	Design and Implement Prim's algorithm.	_
	RAVERSAL & APPLICATIONS	
-	programs to implement the following algorithms:	
a)	Depth first search. Breadth first search.	
b)	טולמעווז וווטן אלמוטוו.	

	c)	Topl	ogica	l Sorti	ng.										
11. <b>SO</b>	RTING	&SE/	ARCH	ING /	AND I	HASH	I TAB		IPLE	MENT	ATION				
	a)	Write	e Pyth	non p	rograi	ms fo	or imp	leme	nting	the fo	llowing	g sortii	ng techr	niques to	<b>b</b>
		arran	ge a	list of	intege	ers in	ascer	nding	order						
				Insert											
				Selec		ort									
				Quick											
		-		Merge											
	b)		-	•	•		•					•	search.		
	c)	vvrite	Pyth	on pro	ogram	is for	Imple	ment	Hash	ng – a	ny two	COIIISI	on techn	· ·	
													ΤΟΤΑ	L : 60 PF	ERIODS
REFER															
1.	Rance I	D. Nec	aise, I	Data S	tructur	res and	l Algo	rithms	s Using	g Pytho	on, Will	y Stude	ent Editio	n, 2016.	
WEB R	EFERI	ENCE	S												
1.	https://c	louda	cadem	iy.com	/lab/p	ython-	-lab-1/	,							
2.	https://v	www.p	ython	.org/d	ownlo	ads/									
COUR	SE OUT	COM	IES												
Upon c	ompleti	on of t	the co	urse, s	studer	nts wil	l be a	ble to							
CO1	Write	functio	ons to	impleı	nent li	inear a	and no	n-linea	ar data	structu	ire opei	rations			
CO2	Sugges	st appr	opriat	e linea	r / noi	n-linea	ar data	struct	ure op	eration	s for sc	olving a	given pro	oblem	
CO3	Apply	appro	priate	hash f	unctio	ns tha	t resul	t in a c	collisio	on free	scenari	o for da	ata storag	e and retr	ieval
				Ν	ЛАРР	'ING (	OF CO	Os WI	TH P	Os AN	D PSO	S			
					0.07								PROG	RAM SP	ECIFIC
COs				PR	OGRA	AM O	UTCO	OMES	(POs	)			OUTO	COMES (	PSOs)
005	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	1	1	-	-	2	2	2	3	3	3	3	2
CO2	3	3	3	1	1	-	-	2	2	2	3	3	3	3	2
CO3	3	3	3	1	1	_	_	2	2	2	3	3	3	3	2

S130			Ρ	С
	Common to AI & DS 0 0	4	4	2
	TIVES			
	To get familiarized with the structure of agents			
	To solve simple toy world problems			
	To understand and develop solutions through search strategies.			
•	To develop solutions for constraint satisfaction problems.			
٠	To increase the knowledge about real-world problems and how to plan and act in the r	əal	WC	rl
	and to get familiarized with expert systems			
IST O	F EXPERIMENTS			
1.	Developed a simple reflex agent program in Python for the vacuum-cleaner wor			
	problem. This particular world has just two locations: squares A and B. The vacuu			
	agent perceives which square it is in and whether there is dirt in the square. It ca	n		
	choose to move left, move right, suck up the dirt, or do nothing.			
2.	Solve the 8-puzzle problem, which consists of a 3x3 board with eight numbered tile			
	and a blank space. A tile adjacent to the blank space can slide into the space. Th			
	objective is to reach a specified goal state as given below. Find minimum number	of		
	steps required to reach the goal.			
			C	C
	3 4 5			
	6 7 8			
	6 7 8			
	Goal State			
	Write a Python program to solve N Queen Problem using backtracking. The N Queen			
	the problem of placing N chess queens on an N×N chessboard so that no two queer	S		
	attack each other.	$ \rightarrow $		
	Write a Python program for a path search problem to find a path from point A to point	В		
	using A* Search Algorithm.			
5.	Using Hill Climbing Search Algorithm, find the solution for a Travelling Salesma			
	Problem, which has to find the shortest route from a starting location and back to the	е		
	starting location after visiting all the other cities.	_		
	Given an undirected graph and a number m, determine if the graph can be coloured			
	with at most m colours such that no two adjacent vertices of the graph are colored with			
	the same color. Here coloring of a graph means the assignment of colors to all vertices		С	D
7.	Solve the cryptarithmetic puzzle SEND+MORE=MONEY using a Python program. Fir		-	_
	digits that replace letters to make a mathematical statement true. Each letter in th			
	problem represents one digit (0–9). No two letters can represent the same digit. When	а		
	letter repeats, it means a digit repeats in the solution.			
8.	Write a Python program to solve Sudoko. Given an initial 9x9 grid of cells contain	-		
	numbers between 1 and 9 or blanks, all blanks must be filled with numbers. You w			
	Sudoko if you find all values such that every row, column, and 3x3 subsquare contair	S		
	the numbers 1–9, each with a single occurrence.	_		
9.	A job shop consists of a set of distinct machines that process jobs. Each job is a serie			
	of tasks that require use of particular machines for known durations, and which must b			
	completed in specified order. Implement the job shop scheduling problem to schedu	е		
	the jobs on the machines to minimize the time necessary to process all jobs.		С	0:
10.	Demonstrate the use of MYCIN: a medical expert system. Implement a small examp		5	
	of an expert system; which defines a few contexts, parameters, and rules, and presen			
	a rudimentary user interface to collect data about an infection in order to determine th	е		
	identity of the infecting organism.			

TOTAL : 60 PERIODS

### LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS Standalone desktops with Python 3 Interpreter for Windows/Linux 30 Nos. **REFERENCE BOOKS** 1. S. Russell and P. Norvig, "Artificial Intelligence: A Modern Approach, Prentice Hall, Third Edition, 2009. 2. Dan W. Patterson - Introduction to Artificial Intelligence and Expert Systems, PHI, New Delhi, 2006. WEB REFERENCES 1. https://www.tutorialspoint.com/artificial\_intelligence\_with\_python/index.htm 2. https://www.edureka.co/blog/artificial-intelligence-with-python/ COURSE OUTCOMES Upon completion of the course, students will be able to Familiarized with the structure of agents, implement simple agents and develop solutions for CO1 simple toy world problems. CO2 Implement and develop solutions for problems through different search strategies. Identify constraints of problems and develop solutions for constraint satisfaction problems. CO3 Approach a real world problem, develop a plan and then solve those problems and use expert systems. **MAPPING OF COs WITH POs AND PSOs PROGRAM SPECIFIC PROGRAM OUTCOMES (POs) OUTCOMES (PSOs)** COs PO PSO2 PSO1 PSO3 1 2 3 4 5 6 7 8 9 10 11 12 CO1 3 3 3 3 1 1 1 1 2 2 2 3 3 3 3 **CO2** 3 3 3 3 1 1 1 1 2 2 2 3 3 3 3 3 3 2 2 3 3 3 CO3 3 3 1 1 1 2 2 3

HS1310	PROFESSIONAL SKILLSLAB	L	Τ	P	С
	( Common to IT )	0	0	2	1
OBJECTIVES	a the Frenkeyshility and Cancer Chills of students				
	ce the Employability and Career Skills of students				
	he students towards grooming as a professional				
	nem Employable Graduates				
Develo	p their confidence and help them attend interviews successfully.				
	RIMENTS				
UNIT I				1	6
	Soft Skills- Hard skills & soft skills - employability and career Skills-G				
	nal with values—Making an Oral Presentation–Planning and preparing				~ 1
	Organizing the presentation to suit the audience and context; Connecting			C	01
	ng presentation; Projecting a positive image while speaking; Emph language-General awareness of Current Affairs.	asis	s on		
enective body	anguage-General awareness of Current Analis.				
					6
Self-Introduction	on-organizing the material - Introducing oneself to the audience – introdu	icing	g the		
	ering questions – individual presentation practice— Making a Powe				
	- Structure and format; Covering elements of an effective presentatio				
	amics. Making an Oral Presentation-Planning and preparing a			С	02
	Organizing the presentation to suit the audience and context; Connecting				
effective body	ng presentation; Projecting a positive image while speaking; Emph	asis	s on		
chective body					
					6
Introduction to	Group Discussion- Participating in group discussions - understandin	g g	roup		
	instorming the topic questioning and clarifying -GD strategies- Struct			С	03
	GD; Techniques of effective participation in group discussion; Prepa				
group discussi	on; Accepting others' views / ideas; Arguing against others' views or idea	s, e	etc		1
					6
	c speaking; Preparing for a speech; Features of a good speech; Speakin	a w	vith a		-
	Famous speeches may be played as model speeches for learning th				
	g). Interview etiquette – dress code – body language – attending job inte				04
	be interview -one to one interview &panel interview –Job Interviews: purp				
	to prepare for an interview; Language and style to be used in an interview	v; T	ypes		
of interview qu	estions and how to answer them.				-
					6
	differences between groups and teams- managing time managing	ctr	000-		6
networking pr	ofessionally- respecting social protocols understanding career managing	aen	nent-	С	05
	ong- term career plan making career changes	gon			
1 3	TOTAL	: 3	0 PE	RIO	DS
	PMENT FOR A BATCH OF 30 STUDENTS				
One Server 30 Desktop Co	mouters				
()nd Hand Mill					
One Hand Mik					
One LCD Proj	BOOKS				
One LCD Proj	BOOKS eld, Jeff Soft Skills for Everyone. Cengage Learning: New Delhi, 2015				
One LCD Proj REFERENCE 1. Butterfi		ent	Blac	ksw	an:

- 3. Raman, Meenakshi and Sangeeta Sharma. Professional Communication. Oxford University Press: Oxford, 2014
- 4. S. Hariharanetal. Soft Skills. MJP Publishers: Chennai, 2010
- 5. Interact English Lab Manual for Undergraduate Students,. OrientBalckSwan: Hyderabad, 2016.

#### COURSE OUTCOMES Upon completion of the course, students will be able to

CO1 Make effective presentations

CO2 Participate confidently in Group Discussions

CO3 Attend job interviews and be successful in them.

CO4 Develop adequate Soft Skills required for the workplace

CO5 Develop their speaking skills to enable them speak fluently in real contexts

### MAPPING OF COs WITH POS AND PSOs

COs				PR	OGRA		UTCC	MES	(POs	)				RAM SP OMES (	
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	-	-	-	-	-	-	-	1	2	3	-	-	2	1	2
CO2	-	1	-	2	-	-	-	-	-	3	-	-	1	-	2
CO3	-	2	-	3	-	-	-	-	1	2	-	-	-	-	2
CO4	-	-	-	-	1	-	-	-	2	2	-	-	-	-	2
CO5	-	2	1	1	2	-	2	-	-	3	-	-	1	2	2

MA1454	DISCRETE MATHEMATICS & GRAPH THEORY	PC
		0 4
OBJECTIVES		
	oduce Mathematical Logic, Inference Theory and proof methods.	
	vide fundamental principles on combinatorial counting techniques.	
	nonstrate an understanding of relations and functions	
	iliar with the most fundamental Graph Theory topics and results <b>LOGIC AND PROOFS</b>	40
UNIT I	LOGIC AND PROOFS	12
	antifiers – Rules of Inference – Introduction to Proofs – Proof Methods and	CO1
Strategy.		001
Chalogy		
UNIT II	COMBINATORICS	12
Mathematical	Induction – Strong Induction and Well Ordering – The Basics of Counting - The	
Ŷ	inciple – Permutations and Combinations – Recurrence Relations -Generating	CO2
	olving Linear Recurrence Relations Using Generating Functions- Inclusion -	002
Exclusion – Pr	inciple and Its Applications.	<u>i</u>
	SETS AND FUNCTIONS	12
-	on sets – Types of relations and their properties – Partitions – Equivalence	
	tial ordering – Poset – Hasse diagram. Functions: Characteristic function of a set	CO3
	ctions – Recursive functions – Permutation functions.	000
Ŭ		
UNIT IV	GRAPHS	12
	duction – Isomorphism – Sub graphs – Walks, Paths, Circuits –Connectedness –	CO4
Components –	Euler graphs – Hamiltonian paths and circuits	
		- 10
	TREES	12
	erties of trees – Distance and centers in tree – Rooted and binary trees Minimal spanning trees.	CO5
	TOTAL : 60 PER	RIODS
TEXT BOOKS		
	h H. Rosen, "Discrete Mathematics and its Applications", Tata McGraw Hill Pub.	
	, Seventh Edition, Special Indian Edition, New Delhi, 2011.	
•	P. Grimaldi, "Discrete and Combinatorial Mathematics: An Applied Introduction",	
	n Education, Fifth Edition, New Delhi, 2014.	"
	gh Deo, "Graph Theory: With Application to Engineering and Computer Sci e Hall of India, 2003.	ence",
Fiend		
REFERENCE	BOOKS	
	ur Lipschutz and Mark Lipson," Discrete Mathematics", Schaum's Outlines,	Tata
	w Hill Pub. Co. Ltd., Third Edition, New Delhi, 2013.	
	s Koshy," Discrete Mathematics with Applications", Elsevier Publications, Boston, 2	2004.
	. and Holton D.A, "A First Look at Graph Theory", Allied Publishers, 1995.	_
	L., Kandel A. and Baker T.P. "Discrete Mathematics for Computer Scientist	s and
Mather	naticians", Prentice Hall of India, 1996.	

5. Liu C.L., "Elements of Discrete Mathematics", Mc Graw Hill, 1985.

00110			<u>~~</u> M	<b>F</b> 0												
COUR Upon				-	cours	se, st	udent	ts will	l be a	ble to	)					
CO1	Con	nstru rectn	ct ma less (	athem	natical	l argu	Iment	s usir	ng log	gical o	connec	tives	and qu	uantifiers	y contra and ve erences	rify the
CO2	mat com	hem npute	atica e and	l theo inter	rems pret t	using he me	) matl eaning	hemat g in th	tical in ne con	nducti ntext	on. De	emonst particu	trate b Ilar ap	asic cou	unctions nting pri . Helps t design.	nciples,
CO3	•	•		•		basic pertie		emati	cal ob	ojects	such a	as sets	, funct	ions, and	d relation	s verify
CO4	App clus		•	aph th	neory	conce	epts i	n data	a stru	ctures	s, data	minin	g, ima	ge segn	nentation	and in
CO5														re helpfi computa	ul in ana tion.	lysis of
				-	Μ	APPI	NG O	F CO	s WI	гн рс	)s ANI	D PSO	S	-		
COs					PR	OGR/	AM O	UTCC	MES	(POs	;)				RAM SP OMES (	
000		PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3
CO1		3	3	2	2	1	1	1	0	0	1	1	2	2	1	1
CO2	2	3	3	2	2	1	1	1	0	0	1	1	2	2	1	1
CO3	3	3	3	2	2	1	1	1	0	0	1	1	2	2	1	1
CO4	•	3	3	2	2	1	1	1	0	0	1	1	2	2	1	1
CO5	5	2	2	2	2	1	1	1	0	0	1	1	2	2	1	1

CS1401		P (	С
		0	3
OBJECTIVES	rn the general framework for analyzing algorithm efficiency		
	conversant with algorithms for common problems.		
	alyse the algorithms for time/space complexity.		
	te algorithms for a given problem using different design paradigms.		
	derstand computational complexity of problems		
UNIT I	INTRODUCTION		
Algorithm – Fu	indamentals of Algorithmic Problem Solving – Important Problem Types – The Analysis		
Framework –	Asymptotic Notations and Basic Efficiency Classes - Mathematical Analysis of	CO	)]
Nonrecursive a	nd Recursive Algorithms – Empirical Analysis of Algorithms.		
UNIT II	DECREASE AND CONQUER AND DIVIDE-AND-CONQUER		(
Decrease-and-C	Conquer- Insertion Sort - Binary Search - Computing a Median and the Selection		
Problem – Di	ivide-and-Conquer - Merge Sort - Quicksort - The Closest -Pair and Convex -Hull	CO	)ź
Problems by D	ivide-and-Conquer.		
	-		
UNIT III	DYMANIC PROGRAMMING AND GREEDY TECHNIQUE		,
The Knapsack	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm –	CO	
The Knapsack Floyd's Algorithm	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's	со	
The Knapsack Floyd's Algorithm	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm –	СО	
The Knapsack I Floyd's Algori Algorithm – Hu	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes.	CO	).
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT	СО	
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Meth	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in	co	).
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Meth	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT		).
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Meth	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in		).
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Meth	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in	CO	).
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in as – The Stable Marriage Problem.	CO	). 
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's uffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in as – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION	CO	
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Meth Bipartite Graph UNIT V P, NP, and NP-	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS	CO	
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V P, NP, and NP- – Subset-Sum	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS Complete Problems – Backtracking – n-Queens Problem – Hamiltonian Circuit Problem	CO	); ;
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V P, NP, and NP- – Subset-Sum	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS • Complete Problems – Backtracking – n-Queens Problem – Hamiltonian Circuit Problem Problem – Branch-and-Bound – Assignment Problem – Knapsack Problem – Traveling	CO	); 
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V P, NP, and NP- – Subset-Sum Salesman Probl	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS • Complete Problems – Backtracking – n-Queens Problem – Hamiltonian Circuit Problem Problem – Branch-and-Bound – Assignment Problem – Knapsack Problem – Traveling	CO	);
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V P, NP, and NP- – Subset-Sum Salesman Probl	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS • Complete Problems – Backtracking – n-Queens Problem – Hamiltonian Circuit Problem Problem – Branch-and-Bound – Assignment Problem – Knapsack Problem – Traveling lem – Approximation Algorithms for the Traveling Salesman Problem and the Knapsack TOTAL : 45 PEF	CO	
The Knapsack I Floyd's Algori Algorithm – Hu UNIT IV Graphical Metl Bipartite Graph UNIT V P, NP, and NP- – Subset-Sum Salesman Probl Problem.	Problem and Memory Functions – Optimal Binary Search Trees – Warshall's Algorithm – ithm – Greedy Technique – Prim's Algorithm – Kruskal's Algorithm – Dijkstra's iffman Trees and Codes. ITERATIVE IMPROVEMENT hod – The Simplex Method – The maximum Flow Problem – Maximum Matching in is – The Stable Marriage Problem. BACKTRACKING, BRANCH-AND-BOUND AND APPROXIMATION ALGORITHMS • Complete Problems – Backtracking – n-Queens Problem – Hamiltonian Circuit Problem Problem – Branch-and-Bound – Assignment Problem – Knapsack Problem – Traveling lem – Approximation Algorithms for the Traveling Salesman Problem and the Knapsack TOTAL : 45 PEF	CO	

2.	Thom	as H.	Corm	en, C	harles	s E. L	eiser	son,	Ronal	d L. F	livest,	Cliffor	d Stein,	"Introdu	ction to
		thms",													
REFE	•	E BOOI													
				"The	Alaori	ithm Γ	Desiar	ו Man	ual" (	Secon	d Editio	on Sni	inger, 20	008	
2.					•		•						•	ion, 201 <sup>2</sup>	1
		•				-	•							gorithms	
5.						-	ΓΓΙΟ	yranni	my,	volum	C I - I	unuan		gonunna	, mu
COUD		n, Addi		vesiey	/, 199	7.									
		TCOM						<b>.</b> .							
-		tion of t		-											
CO1	Abilit	y to inve	estigate	e an al	gorith	m's ef	ficien	cy wit	h respe	ect to ru	inning	time			
CO2	Desig	n and in	npleme	ent pro	oblems	s using	g algor	rithmic	c desig	n techi	niques	such as	decrease	and cond	quer and
	divide	and cor	nquer												
CO3	Abilit	y to und	erstan	d the d	lesign	techni	ques s	uch as	s Dyna	mic pro	ogramn	ning an	d Greedy	technique	e
CO4	Abilit	y to und	erstan	d the i	terativ	e desi	gn tecl	nnique	es						
CO5	Under	stand th	e varia	ations	among	g tracta	able ar	nd intra	actable	e proble	ems				
				N	APP	ING (	OF CO	Os WI	TH P	Os ANI	D PSO	s			
													PROG	RAM SP	ECIFIC
COs				PR	OGRA	AM O	UTCO	OMES	6 (POs	)			OUTO	COMES (	(PSOs)
005	РС	1 PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	-	-	-	3	-	2	3	3	2	2
CO2	3	3	3	3	2	-	-	-	3	-	2	3	3	2	2
CO3	3	3	3	3	2	-	-	-	3	-	2	3	3	2	2
CO4	3	3	3	3	2	-	-	-	3	-	2	3	3	2	2
	3	3	3	3	2	-	-	-	3	-	2	3	3	2	2
CO5															

CS1402	OPERATING SYSTEMS	L 1	Γ	Ρ	С
	(Common to CSE, AI-DS & IT)	3 (	)	0	3
OBJECTIVES					
<ul> <li>To und</li> </ul>	erstand the basic concepts and functions of operating systems.				
<ul> <li>To und</li> </ul>	erstand Processes and Threads				
<ul> <li>To ana</li> </ul>	lyze Scheduling algorithms.				
<ul> <li>To und</li> </ul>	erstand the concept of Deadlocks.				
<ul> <li>To ana</li> </ul>	lyze various memory management schemes.				
<ul> <li>To und</li> </ul>	erstand I/O management and File systems.				
	amiliar with the basics of Linux system and Mobile OS like iOS and Androi	id			
UNIT I	OPERATING SYSTEM OVERVIEW				9
	stem Overview-Basic Elements, Instruction Execution, Interrupts, M	/lemc	orv		
• •	che Memory, Direct Memory Access, Multiprocessor and Multicore Organi		-		
•	stem overview-objectives and functions, Evolution of Operating Sy			С	01
Computer Sys	stem Organization Operating System Structure and Operations- System	i Cal	lls,		
System Progra	ams, OS Generation and System Boot.				
UNIT II	PROCESS MANAGEMENT				9
Processes – F	Process Concept, Process Scheduling, Operations on Processes, Inter-p	proce	ss		
Communicatio	n; CPU Scheduling – Scheduling criteria, Scheduling algorithms, M	lultip	le-		
processor sch	eduling; Threads- Overview, Multithreading models, Threading issues; P	'roce	SS		
Synchronizatio	on – The critical-section problem, Semaphores, Classical proble	ms	of	C	02
-	n, Monitors; Deadlock – System model, Deadlock characterization, Meth-				
•	locks, Deadlock prevention, Deadlock avoidance, Deadlock detection, Re	cove	ery		
from deadlock				<u> </u>	
	STORAGE MANAGEMENT				9
Main Memor		Pagir	•		
-	Segmentation with paging, 32 and 64 bit architecture Examples; Virtual M		-	C	03
•	, Demand Paging, Need for Page Replacement, Page Replacement Alg	orith	m,		
	ashing; Allocating Kernel Memory, OS Examples.			<u> </u>	
UNIT IV	FILE SYSTEMS AND I/O SYSTEMS	م ماريا:			9
0	system – Overview of Mass Storage Structure, Disk Structure, Disk Scho		•		
•	nent, swap space management; File-System Interface - File concept, A				
	ctory Structure, Directory organization, File Sharing and Protection; File Spectra Allocation, Matheda			C	04
-	n- File System Structure, Directory implementation, Allocation Methods ement, Efficiency and Performance, Recovery; I/O Systems – I/O Har				
	) interface, Kernel I/O subsystem, Streams, Performance.	uwa	16,		
	CASE STUDY			L	9
	- Design Principles, Kernel Modules, Process Management, Scheduling, M	<u>lem</u> r	rv		
•	Input-Output Management, File System, Inter-process Communication;		-		
•	Android - Architecture and SDK Framework, Media Layer, Services Laye			C	05
OS Layer, File	· · · · · · · · · · · · · · · · · · ·	.,			
	TOTAL :	: 45	PEF		DS
TEXT BOOKS					
	m Silberschatz, Peter Baer Galvin and Greg Gagne, —Operating Syst	em (	Con	cer	ots.
	tion, John Wiley and Sons Inc., 2012.				,
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REFE	REN	CE E	300ł	٢S												
1.				sri, A. Editio			, Dav	id Lev	/ine, -	—Оре	erating	Syste	ms – A	Spiral /	Approach	n∥, Tata
2.		liam I, 20		ngs, "	Opera	ating	Syste	ms –	Intern	als a	nd Des	sign Pr	inciple	s", 7 th I	Edition, F	Prentice
3.	Ach	nyutS	S.God	lbole,	AtulK	ahate	e, —O	perati	ing Sy	/stem	sll, Mc	Graw H	Hill Edu	ucation, 2	2016.	
4.	And	drew	S. Ta	anenb	aum,	—Mo	dern	Opera	ating S	Syster	ns∥, 4t	h Editi	on, Pe	arson Eo	ducation,	2014.
5.				here, Educa		erating	g Sys	tems:	A C	oncep	ot-Base	ed App	oroach'	', Secon	nd Editio	n, Tata
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COUR	SE C	OUT	СОМ	ES												
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CO1	Ana	alyze	varic	ous so	hedu	ling al	gorith	ms.								
CO2	Und	derst	and c	leadlo	ock, p	reven	tion a	nd av	oidan	ماد مم	orithm	S.				
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(Common to CSE, AI-DS & IT ) 3 0	Ρ	С
OBJECTIVES	2	4
<ul> <li>To learn the fundamentals of data models, ER diagrams and to study SQL and r database design.</li> <li>To familiarize relational model with Relational Database design and Normal Forms.</li> </ul>	curre d Qu	ency uery
UNIT I INTRODUCTION TO RELATIONAL DATABASES	9	+ 6
<ul> <li>Purpose of Database System – Views of data – Data Models – Database System Architecture Entity-Relationship model – E-R Diagrams – Enhanced-ER Model – ER-to-Relational Mapping–Introduction to relational databases – Relational Model – Keys – Relational Algebra – SQL fundamentals – Advanced SQL features</li> <li>Lab Component <ul> <li>Data Definition Commands, Data Manipulation Commands for inserting, deleting, updating and retrieving Tables and Transaction Control statements .Database Querying – Simple queries, Nested queries, Sub queries and Joins</li> <li>Queries using Aggregate functions (COUNT, SUM, AVG, MAX and MIN), GROUP BY, HAVING and Creation and dropping of Views, Synonyms, Sequences.</li> <li>Conceptual Designing using ER Diagrams (Identifying entities, attributes, keys and relationships between entities, cardinalities, generalization, specialization etc.)</li> </ul> </li> </ul>	с	:01
UNIT II ER MODEL AND RELATIONAL DATABASE DESIGN		) + 6
<ul> <li>Embedded SQL- Dynamic SQL - Functional Dependencies - Non-loss Decomposition - First, Second, Third Normal Forms, Dependency Preservation - Boyce/Codd Normal Form - Multivalued Dependencies and Fourth Normal Form - Join Dependencies and Fifth Normal Form</li> <li>Lab Component <ul> <li>Simple Embedded SQL Program to demonstrate the concepts.</li> <li>Database Design using normalization and Implementation for any application.</li> </ul> </li> </ul>		:02
	u	1 1 6
UNIT III       TRANSACTIONS         Transaction Concepts – ACID Properties – Schedules – Serializability – Concurrency Control – Need for Concurrency – Locking Protocols – Two Phase Locking – Deadlock – Transaction Recovery – Save Points – Isolation Levels – SQL Facilities for Concurrency and Recovery.         Lab Component       • Usage of Transaction control language commands like commit, rollback and save point.         • Develop Programs using BEFORE and AFTER Triggers for INSERT, DELETE and UPDATE statements	c	<u>) + 6</u> :03
UNIT III       TRANSACTIONS         Transaction Concepts – ACID Properties – Schedules – Serializability – Concurrency Control –         Need for Concurrency – Locking Protocols – Two Phase Locking – Deadlock – Transaction         Recovery – Save Points – Isolation Levels – SQL Facilities for Concurrency and Recovery.         Lab Component         • Usage of Transaction control language commands like commit, rollback and save point.         • Develop Programs using BEFORE and AFTER Triggers for INSERT, DELETE and UPDATE statements         UNIT IV       IMPLEMENTATION TECHNIQUES	C 9	
UNIT III         TRANSACTIONS           Transaction Concepts – ACID Properties – Schedules – Serializability – Concurrency Control – Need for Concurrency – Locking Protocols – Two Phase Locking – Deadlock – Transaction Recovery – Save Points – Isolation Levels – SQL Facilities for Concurrency and Recovery.           Lab Component         • Usage of Transaction control language commands like commit, rollback and save point.           • Develop Programs using BEFORE and AFTER Triggers for INSERT, DELETE and UPDATE statements	C 9	:03
UNIT III         TRANSACTIONS           Transaction Concepts – ACID Properties – Schedules – Serializability – Concurrency Control – Need for Concurrency – Locking Protocols – Two Phase Locking – Deadlock – Transaction Recovery – Save Points – Isolation Levels – SQL Facilities for Concurrency and Recovery.           Lab Component         • Usage of Transaction control language commands like commit, rollback and save point.           • Develop Programs using BEFORE and AFTER Triggers for INSERT, DELETE and UPDATE statements           UNIT IV         IMPLEMENTATION TECHNIQUES           RAID – File Organization – Organization of Records in Files – Indexing and Hashing –Ordered Indices – B+ tree Index Files – B tree Index Files – Static Hashing – Dynamic Hashing. Query Processing Overview – Algorithms for SELECT and JOIN operations – Query optimization using Heuristics and Cost Estimation.           Lab Component         • Implementation of B tree and B+ Tree.	C 9 C	:O3 ) + 6

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	syste	m from	failure	es.											
CO4	Able	to orgai	nize, ii	ndex t	he file	es and	d to o	otimiz	e the	given	queries	6			
CO5							-			•	•		ted data	hases a	and XML
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CO5	5 3	3	3	3	2	1	1	-	-	2	2	2	2	3	3

	FOUNDATIONS OF MACHINE LEARNING	L	Т	P	С
	Common for IT, AI-DS & CSE	3	0	0	3
OBJECTIVES					
<ul> <li>To und</li> </ul>	erstand the basic concepts of machine learning and probability theory.				
🛠 To app	reciate supervised learning and their applications.				
<ul> <li>To und</li> </ul>	erstand unsupervised learning like clustering and EM algorithms.				
<ul> <li>To und</li> </ul>	erstand the theoretical and practical aspects of probabilistic graphical mo	odels	5.		
<ul> <li>To lear</li> </ul>	n other learning aspects such as reinforcement learning, representatior	n lea	rning	j, de	еер
learnin	g, neural networks and other technologies.				
UNIT I	INTRODUCTION				9
Machine Learn	ng - Types of Machine Learning - Supervised Learning - Unsupervised L	earni	ng –		
Basic Concepts	in Machine Learning - Machine Learning Process - Weight Space - Testing	Mac	chine		201
Learning Algor	thms - A Brief Review of Probability Theory -Turning Data into Probabilit	ies –	The		.01
Bias-Variance 7	rade-off, FIND–S Algorithm, Candidate Elimination Algorithm				
UNIT II	SUPERVISED LEARNING			1	9
Linear Models	for Regression – Linear Basis Function Models – The Bias-Variance Decomp	oositi	on –		
Bayesian Linear	Regression - Common Regression Algorithms - Simple Linear Regression -	Mu	ltiple		
-	ion – Linear Models for Classification – Discriminant Functions – Pro			C	C <b>O2</b>
	els – Probabilistic Discriminative Models – Laplace Approximation – Bayesian				.01
•	ommon Classification Algorithms - k-Nearest Neighbors - Decision Trees -	Rar	dom		
	Support Vector Machines				-
UNIT III	UNSUPERVISED LEARNING			1	9
	s and EM - K-Means Clustering - Dirichlet Process Mixture Models -	-			
-	erarchical Clustering - The Curse of Dimensionality - Dimensionality Red			C	C <b>O</b> 3
	onent Analysis – Latent Variable Models (LVM) – Latent Dirichlet Allocation (	LDA	.)		
UNIT IV	GRAPHICAL MODELS			1	9
•	orks – Conditional Independence – Markov Random Fields – Learning – Nai	ve B	ayes	С	C <b>O</b> 4
	rkov Model – Hidden Markov Model.				
UNIT V	ADVANCED LEARNING				9
	Learning – Representation Learning – Neural Networks – Active Learning – 1	Ense	mble	C	CO5
Learning – Boo	strap Aggregation – Boosting – Gradient Boosting Machines – Deep Learning		<b>7 DE</b>		
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TEXT BOOKS				~ ~	
	Alpaydin, "Introduction to Machine Learning", Third Edition, Prentice Hall	of I	ndia,	201	15.
REFERENCE	BOOKS				
1. Christo	pher Bishop, "Pattern Recognition and Machine Learning", Springer, 200	6.			
	P. Murphy, "Machine Learning: A Probabilistic Perspective", MIT Press, 2				
-	n Marsland, "Machine Learning – An Algorithmic Perspective", Secon	d E	dition	, C	RC
Press,					
	itchell, "Machine Learning", McGraw-Hill, 2017.				
	Hastie, Robert Tibshirani, Jerome Friedman, "The Elements of Statis	stica	l Lea	arnir	ng",
	Edition, Springer, 2008.	_	_		_
	Nelli, "Python Data Analytics with Pandas, Numpy, and Matplotlib", S	Seco	ond E	Editi	ion,
	2018.				
Apress					
COURSE	DUTCOMES Deletion of the course, students will be able to				

CO1 (	ain kn	owledg	ge abo	ut bas	ic con	cepts (	of mac	chine l	earnin	g techn	iques				
CO2 I	Develop	predi	ctive r	nodel	based	on bot	th inpu	it and	output	t data					
CO3 A	bility t	o unde	erstand	l the u	nsupe	rvised	learni	ng alg	orithn	n and di	imensio	onality	reduction	technique	es
CO4 I	Design s	system	s that	use th	e appr	opriate	e grap	hical r	nodels	s of mad	chine le	arning			
CO5 A	bility t	o addr	ess th	e prob	lem of	flearn	ing co	ntrol s	trateg	ies for a	autonor	nous ag	gents		
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CO1	3	3	3	3	2	2	2	2	2	2	2	2	3	3	2
CO2	3	3	3	3	2	2	2	2	2	2	2	2	3	3	2
CO3	3	3	3	3	2	2	2	2	2	2	2	2	3	3	2
CO4	3	3	3	3	2	2	2	2	2	2	2	2	3	3	2
CO5	3	3	3	3	2	2	2	2	2	2	2	2	3	3	2

ML1402	STATISTICS FOR MACHINE LEARNING	L	Ρ	Т	С
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OBJECTIVES	· · · · · · · · · · · · · · · · · · ·				
Be farr	iliar with estimation theory and related concepts.				
Be pro	vide basic applications of testing of hypothesis.				
To intre	oduce correlation functions and ARIMA models.				
To pro	vide fundamental applications on fourier analysis and SARIMA models.				
• To der	nonstrate VC dimension				
UNIT I	ESTIMATION THEORY				Ś
Introduction to	estimation theory-Goodness of estimators-Fishers information -Prope	ertie	s of		_
estimators; bia	as, variance, efficiency- C-R bound- consistency			C	01
UNIT II	BAYESIAN LEARNING			1	Ş
Regression -N	⊥ Iaximum Likelihood Estimator-MAP Estimator -Evidence Function and La	apla	cian		
Approximator-	Latent Variables-EM Algorithm.			C	02
UNIT III	ARMA MODELS			1	Ģ
Auto- and cro	ss-correlation functions- Partial correlation functions -Linear random pro	ces	ses-		
Auto-regressiv	ve-Moving average and ARMA models.			C	03
UNIT IV	ARIMA MODELS AND FOURIER ANALYSIS			1	Ģ
Models for no	n-stationary processes-Trends, heteroskedasticity and ARIMA models	-Fo	urier		_
analysis of de	erministic signals- DFT and periodogram.				04
UNIT V	STATISTICAL LEARNING THEORY				Ģ
Computationa	Learning Theory-Introduction-General Framework for Concept Learning-	PAC	)		05
Learning Mod	el-VC Dimension-Learning in the presence of noise.				US
	TOTAL	: 45	5 PEI	RIO	DS
TEXT BOOKS	6				
1.Theodoridis	S, Machine Learning: A Bayesian and Optimization Pers	spec	tive.	Uni	teo
Kingdom: Else	evier Science,2020.				
2.Kukar, N	I., Kononenko, I, Machine Learning and Data Mining. United Kin	ngdo	m: E	lsev	∕ie
Science,2007					
3.Jonathar	D.Cryer,Kung Sik Chan,Time Series Analysis,Springer,Second Edition,20	008.			
4.Robert H	Shumway, Time Series Analysis and its Applications, Springer, Fourth Edit	ion,2	2016		
5.Jerome H	I.Friedman,Robert Tibshirani,The Elements of Statistical Learning,Springe	er.			
REFERENCE	BOOKS				
	hy,Machine Learning: A probabilistic perspective,MIT Press,2012				
1. Kevin Murp					
•	I.R., Schiller. J. and Srinivasan, R.A., Schaum's Outline of Theory an	d P	roble	ems	0

COUR	SE C	DUT	СОМ	ES												
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CO2	Арр	ly te	sting	of hy	pothe	sis re	lated	conce	epts.							
CO3	Арр	ly th	e cro	ss-co	rrelati	ion fu	nction	s and	ARIN	/IA mo	odels.					
CO4	Spe	cify	and r	nanip	ulate	non-s	tation	ary p	roces	ses ar	nd SAF	RIMA n	nodels			
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CO2	2	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO3	;	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
CO4		3	3	3	3	2	-	-	-	-	2	2	2	3	3	2
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✤ To	o imple	ement	Pagir	ng Teo	chniqu	ues ar	nd File	Mana	agem	ent Teo	chnique	es.					
LIST OF I	EXPE	RIME	NTS														
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<b>2.</b> Im	pleme	entatio	on of S	Shell F	Progra	ims.											
<b>3.</b> Im	pleme	entatio	on of C	CPU S	Sched	uling /	Algorit	hms.								C	01
<b>4.</b> Im	pleme	entatio	on of F	Produc	cer Co	onsum	ner pro	oblem	using	Sema	phore.						
<b>5.</b> Im	pleme	entatio	on of l	nter-p	roces	s Con	nmuni	catior	n using	g Share	ed mer	nory.					
<b>6.</b> Im	pleme	entatio	on of T	Thread	ding a	nd Sy	nchro	nizatio	on Ap	plicatio	ons.						
<b>7.</b> Im	pleme	entatio	on of E	3anke	rs Alg	orithm	n for E	eadlo	ock Av	oidanc	e.					С	02
<b>8.</b> Im	pleme	entatio	on of E	Deadlo	ock De	etectio	on Alg	orithm	า.								
<b>9.</b> Im	pleme	entatio	on of C	Contig	uous	Memo	ory All	ocatio	n.								
<b>10.</b> lm	pleme	entatio	on of N	Vemo	ry Ma	nager	nent s	chem	e usir	ng Pagi	ing.						
<b>11.</b> lm	pleme	entatio	on of F	Page F	Replac	cemei	nt Alg	orithm	IS.							С	<b>O</b> 3
<b>12.</b> lm	pleme	entatio	on of E	Directo	ory St	ructur	es.										
<b>13.</b> In	nplem	entati	on of	File A	llocati	on St	rategi	es.									
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ML14(	)8	MACHINE LEARNING LABORATORY	L	Т	Р	С
		Common for IT, AI-DS & AI-ML	0	0	4	2
	To imp	te use of Data sets in implementing the machine learning algorithms lement the machine learning concepts and algorithms in any suitable langerstand the practical aspects of probabilistic graphical models.	gua	ge of	chc	bic
LIST (	OF EXPI	ERIMENTS				
1.	-	ent and demonstrate the FIND-S algorithm for finding the most esis based on a given set of training data samples. Read the training dat ile	-			20
2.	demon	given set of training data examples stored in a .CSV file, implem strate the Candidate-Elimination algorithm. Output a description of the eses consistent with the training examples.				
3.	Use an	program to demonstrate the working of the decision tree based ID3 a appropriate data set for building the decision tree and apply this know a new sample	-			
4.		n Artificial Neural Network by implementing the Back propagation algories same using appropriate data sets	ithm	and	C	CO
5.		program to implement the naïve Bayesian classifier for a sample train red as a .CSV file. Compute the accuracy of the classifier, considering ets.	-			
6.	Classifi	ing a set of documents that need to be classified, use the naïve E er model to perform this task. Built-in Java classes/API can be used to n. Calculate the accuracy, precision, and recall for your data set.				
7.	demons	program to construct a Bayesian network considering medical data. Use this mo trate the diagnosis of heart patients using standard Heart Disease Data Set. You thon ML library lasses/API				
8.	for clus and co	EM algorithm to cluster a set of data stored in a .CSV file. Use the same stering using k-Means algorithm. Compare the results of these two al pmment on the quality of clustering. You can add Java/Python M API in the program.	gori	thms	C	CO:
9.	Print bo	program to implement k-Nearest Neighbor algorithm to classify the iris on the correct and wrong predictions. Java/Python ML library classes can problem.				
10.	-	ent the non-parametric Locally Weighted Regression algorithm in ord ints. Select appropriate data set for your experiment and draw graphs	der	to fit		
		ΤΟΤΑ	L:6	50 PE	RIC	)D
REFEI	RENCE	BOOKS				
1.		n Geron, "Hands-On Machine Learning with Scikit-Learn, Keras, and Tensor nd Techniques to Build Intelligent Systems", Second Edition, O'Reilly Media	Flov	v : C	once	pt

2. Fabio Nelli, "Python Data Analytics with Pandas, Numpy, and Matplotlib", Second Edition, Apress,

3.		ictical				U	•				lver's ( Apress		o Build	ing Real-	World In	telligent
W	EB R	REFE	RENC	ES		-					_					
	2. Web Resources: https://www.anaconda.com/enterprise-machine-learning-getting-started/															
<ul><li>CO1 Update the general and specific boundary for each new example in concept learning</li><li>CO2 Develop supervised learning predictive model for general data set</li></ul>																
CO2	De	velop	supe	ervise	d lear	ning p	predic	tive n	nodel	for ge	eneral o	data se	et			
CO3		ility t blem	-	ply k	nowle	dge i	repres	sentat	ion a	ind m	nachine	e learr	ning te	echnique	s to rea	l world
	•				N	<b>IAPP</b>	ING (	OF CO	)s WI	TH P	Os ANI	D PSO:	5			
COs	5				PR	OGRA	AM O	UTCO	OMES	6 (POs	)				RAM SPI COMES (	
		PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		3	3	3	3	2	-	-	-	-	2	2	2	3	3	3
CO2		3	3	3	3	2	-	-	-	-	2	2	2	3	3	3
CO3		3	3	3	3	2	-	-	-	-	2	2	2	3	3	3

ML1501	REINFORCEMENT LEARNING	L	Р	т	С
METOOT		3	0	0	3
OBJECTIVES					•
This course pro	ovides an introduction to some of the foundational ideas on which moder	ר rei	nfor	cem	ent
learning is bu	ilt, including Markov decision processes, value functions, Monte Ca	arlo	estir	mati	ion,
temporal differ	ence learning, eligibility traces, function approximation& Q Learning. 7	his	cou	rse	will
develop an int	tuitive understanding of these concepts (taking the agent's perspecti	ve),	whi	le a	also
focusing on tl	he mathematical theory of reinforcement learning. Programming as	sign	men	its a	and
projects will red	quire implementing and testing complete decision making systems.				
UNIT I	INTRODUCTION TO RL				9
Bandwidth opti	malities-Epsilon greedy theory- Concentration bounds-Probably approxin	nate	;		1
correct (PAC)	-Upper confidence bound theory (UCB)-Medium Elimination-Thomson Sa	amp	ling		:01
theory –Thoms	on sampling with Gaussian reward- Policy search- Gradient Bandwidths-	•			
Contextual Bar	ndwidth –returns- value functions.				
UNIT II	MARKOV DECISION PROCESSES & DYNAMIC PROGRAMMING				9
Markov Decisi	on Processes (MDP)- Introduction-Markov Property-MDP modelling-	Bell	man	Τ	<u> </u>
Equations - Be	ellman optimality equation- Cauchy sequence- Green's equation- Conv	erge	ence		:02
Proof- LPI Co	nvergence- Value iterations- policy iterations- Dynamic Programming	- M	onte		02
Carlo (MC)- M	C policy evaluation- MC control.				
UNIT III	MONTE CARLO & TEMPORAL DIFFERENCE METHODS			1	9
OFF Policy Mo	nte Carlo control – Temporal difference- Optimality of TD(0)- State-actio	n–			1
reward-state-a	action (SARSA) - TD(0) Control- Q Learning – Eligibility traces-Backward	l Vie	₩	С	03
of Eligibility trac	ces- Eligibility trace control.				
UNIT IV	Deep Q Learning				9
Function Appr	oximation – Linear Parameterization- State aggregation methods- LS	TD	and	Τ	1
LSTDQ- LSPI	and Fitted Q - Deep Q Network (DQN) - Fitted Q- Iteration- Actor	r C	ritic-	С	04
Reinforce – Po	licy gradient with function approximation				
UNIT V	Hierarchical RL				9
Introduction- T	ypes of optimality- Semi MDP- Learning with options- Hierarchical abstra	ct			:05
machines- MAX	XQ- MAXQ value function decomposition- option discovery.				05
	TOTAL	: 45	5 PE	RIO	DS
TEXT BOOKS					
1. Richard	S. Sutton and Andrew G. Barto. Introduction to Reinforcement Learning	ig, 2	2nd I	Editi	ion,
MIT Pre	ess. 2017. [Draft copies available now]				
2. Neuro [	Dynamic Programming. Dimitri Bertsikas and John G. Tsitsiklis. Athena S	cien	itific.	199	96

# **REFERENCE BOOKS**

1. Algorithms for Reinforcement Learning by Csaba Szepesvari, Morgan and Claypool, 1 edition (2010)

COURSE OUTCOMES																
COUF	COURSE OUTCOMES Upon completion of the course, students will be able to															
Upon	COI	mplet	ion o	f the	cours	se, st	udent	ts wil	l be a	ble to	)					
CO1	Βι	uild a	Reinfo	orcem	nent L	earnir	ng sys	stem f	for se	quenti	ial dec	ision m	naking.			
CO2	CO2 Understand the space of RL algorithms (Temporal- Difference learning, Monte Carlo, Sarsa, Q-															
	learning, Policy Gradients, Dyna, and more).															
CO3																
	begin implementing a solution.															
CO4	CO4       Understand how RL fits under the broader umbrella of machine learning, and how it															
	CO4 Understand how RL fits under the broader umbrella of machine learning, and how it complements deep learning, supervised and unsupervised learning															
CO5																
000	01	100131									Ds ANI					
												7 930	5	PROG	RAM SP	ECIFIC
COs					PR	1				(POs				C		S
	,	PO 1	PO 2	PO 3	РО 4	РО 5	PO 6	PO 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
<b>CO</b> 1	1	2	2	2	2	2	-	-	-	1	1	1	1	2	2	2
CO2	2	2	2	2	2	2	-	-	-	1	1	1	1	2	2	2
CO3		2	2	2	2	2	-	-	-	1	1	1	1	2	2	2
CO4	1	2	2	1	2	2	-	-	-	1	1	1	1	2	2	2
COS	5	2	2	2	2	2	-	-	-	1	1	1	1	2	2	2

DS1502	ADVANCED ARTIFICIAL INTELLIGENCE SYSTEMS	Ρ	С
		0	3
OBJECTIVES			
<ul> <li>To ana</li> </ul>	lyze Probabilistic Reasoning for knowledge		
To give	e understanding of main abstractions of decision making.		
To und	lerstand a wide variety of learning algorithms.		
To und	lerstand the different ways of designing software agents		
To und	lerstand the application of AI namely Robotics		
UNIT I	UNCERTAINTY AND REASONING		ļ
Uncertainty -	Basic Probability Notation – Axioms of Probability – Bayes Rule - Probabilistic		
Reasoning -	Bayesian Networks – Semantics – Inference – Other Approaches to Uncertain	СС	2
Reasoning – I	Dempster Shafer Theory – Fuzzy sets and Fuzzy Logic		
UNIT II	DECISION MAKING		9
Utility Theory	- Utility Functions – Decision Networks – Value of Information – Decision		
	ert Systems – Sequential Decision Problems – Value Iteration – Policy Iteration –	СС	יר
			<i>.</i>
Decision Theo	pretic Agents		
		l	
	LEARNING METHODS		(
Learning from	Observations - Forms of Learning – Inductive Learning – Learning Decision		
Learning from Trees – Ense	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data –	СС	
Learning from Trees – Ense	Observations - Forms of Learning – Inductive Learning – Learning Decision	СС	; ;
Learning from Trees – Ense Naïve Bayes I	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks	co	5:
Learning from Trees – Ense Naïve Bayes I <b>UNIT IV</b>	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks SOFTWARE AGENTS	co	
Learning from Trees – Ense Naïve Bayes I <b>UNIT IV</b> Architecture fo	A Observations - Forms of Learning – Inductive Learning – Learning Decision         mble Learning - Explanation Based Learning – Learning with Complete Data –         Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks         SOFTWARE AGENTS         or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA		<b>D</b> ;
Learning from Trees – Ense Naïve Bayes I <b>UNIT IV</b> Architecture fo	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks SOFTWARE AGENTS	CCC	<b>D</b> ;
Learning from Trees – Ense Naïve Bayes I <b>UNIT IV</b> Architecture for ACL – Speed systems	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks  SOFTWARE AGENTS or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA ch Acts - Argumentation among Agents – Trust and Reputation in Multi-agent		<b>D</b>
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V	Observations - Forms of Learning – Inductive Learning – Learning Decision         mble Learning - Explanation Based Learning – Learning with Complete Data –         Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks         SOFTWARE AGENTS         or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA         ch Acts - Argumentation among Agents – Trust and Reputation in Multi-agent         ROBOTICS		<b>D</b> ;
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V Robot Hardwa	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks  SOFTWARE AGENTS or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA ch Acts - Argumentation among Agents – Trust and Reputation in Multi-agent		<b>D</b>
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V Robot Hardwa	Observations - Forms of Learning – Inductive Learning – Learning Decision         mble Learning - Explanation Based Learning – Learning with Complete Data –         Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks         SOFTWARE AGENTS         or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA         ch Acts - Argumentation among Agents – Trust and Reputation in Multi-agent         ROBOTICS         are – Robotic Perception – Planning to Move, Planning Uncertain Movements –		
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V Robot Hardwa	Observations - Forms of Learning – Inductive Learning – Learning Decision         mble Learning - Explanation Based Learning – Learning with Complete Data –         Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks         SOFTWARE AGENTS         or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA         th Acts - Argumentation among Agents – Trust and Reputation in Multi-agent         ROBOTICS         are – Robotic Perception – Planning to Move, Planning Uncertain Movements –         otic Software Architectures – Application Domains		
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V Robot Hardwa Moving – Rob TEXT BOOKS 1. S. Rus	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks  SOFTWARE AGENTS or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA th Acts - Argumentation among Agents – Trust and Reputation in Multi-agent  ROBOTICS are – Robotic Perception – Planning to Move, Planning Uncertain Movements – otic Software Architectures – Application Domains  TOTAL : 45 PEF Sell and P. Norvig, "Artificial Intelligence: A Modern Approach, Prentice Hall,		
Learning from Trees – Ense Naïve Bayes I UNIT IV Architecture for ACL – Speed systems UNIT V Robot Hardwa Moving – Rob TEXT BOOKS 1. S. Rus Edition	Observations - Forms of Learning – Inductive Learning – Learning Decision mble Learning - Explanation Based Learning – Learning with Complete Data – Models – Learning with Hidden Variables – The EM Algorithm – Neural Networks      SOFTWARE AGENTS or Intelligent Agents – Examples - Agent communication – KQML- KIF - FIPA th Acts - Argumentation among Agents – Trust and Reputation in Multi-agent      ROBOTICS are – Robotic Perception – Planning to Move, Planning Uncertain Movements – otic Software Architectures – Application Domains      TOTAL : 45 PEF		

**REFERENCE BOOKS** 

- 1. Gerhard Weiss, Multi Agent Systems , Second Edition, MIT Press, 2013
- 2. S. Kaushik, Artificial Intelligence, Cengage Learning, 1st Edition, 2011
- 3. David L. Poole and Alan K. Mackworth, Artificial Intelligence: Foundations of Computational Agents ,Cambridge University Press, 2010.
- 4. Nils J. Nilsson,- The Quest for Artificial Intelligence, Cambridge University Press, 2009

#### COURSE OUTCOMES

### Upon completion of the course, students will be able to

CO1	Acquire theoretical knowledge about principles for logic-based representation and reasoning
CO2	Develop a decision making model that utilizes Artificial Intelligence.
CO3	Develop an understanding what is involved in learning models from data.
CO4	Select appropriately from a range of techniques when implementing intelligent systems
CO5	Gain knowledge on the functions of Robots

### MAPPING OF COs WITH POs AND PSOs

Cos				PR	OGR/		UTCC	MES	(POs	;)			PROGRAM SPECIF OUTCOMES (PSO						
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	PO ۹	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3				
CO1	3	3	3	3	3	1	-	-	1	2	2	3	3	3	3				
CO2	3	3	3	3	3	1	-	-	1	2	2	3	3	3	3				
CO3	3	3	3	3	3	1	-	-	1	2	2	3	3	3	3				
CO4	3	3	3	3	3	1	-	•	2	2	2	3	3	3	3				
CO5	3	3	3	3	3	1	-	-	2	2	2	3	3	3	3				

ML1502	NATURE INSPIRED COMPUTING TECHNIQUES	Ρ	Т	С
OBJECTIVES	3	0	0	3
• To und	derstand the fundamentals of nature inspired techniques which influence com	putin	a	
	dy the Swarm Intelligence and Immuno computing techniques.	F	5	
	arn fundamental concepts of fuzzy logic and artificial neural network			
UNITI				9
From Nature	to Nature Computing, Philosophy, Three Branches: A Brief Overv	view,		
Individuals,	Entities and agents - Parallelism and Distributivity Interact			
,AdaptationFe	edback-Self-Organization-Complexity, Emergence and ,Bottom-up Vs	-	C	:01
•	nination, Chaos and Fractals.	•		
UNIT II	SWARM INTELLIGENCE			9
Introduction -	│ Ant Colonies, Ant Foraging Behavior, Ant Colony Optimization, SACO and s	cope		
of ACO algor	ithms, Ant Colony Algorithm (ACA), Swarm Robotics, Foraging for food, S	ocial	С	:02
Adaptation of	Knowledge, Particle Swarm Optimization (PSO).			
UNIT III				9
Introduction-	Immune System, Physiology and main components, Pattern Recognition	and		<u> </u>
Binding , Imm	une Network Theory- Danger Theory, Evaluation Interaction Immune Algorit	hms-		
-Genetic Algo	rithms, Reproduction-Crossover, Mutation, Evolutionary Programming, Ge	netic	C	:03
Programming.				
UNIT IV	FUNDAMENTALS OF FUZZY LOGIC			9
Basic concep	ts: fuzzy set theory- basic concept of crisp sets and fuzzy sets- complement	ents-		<u> </u>
union intersed	tion- combination of operation- general aggregation operations- fuzzy relation	ions-		·~ 4
compatibility r	elations-orderings- morphisms- fuzzy relational equations-fuzzy set and syste	ems-		:04
Fuzzy inferen	ce.			
UNIT V	INTRODUCTION TO NEURAL NETWORKS			9
Introduction	<ul> <li>history-Applications-Biological inspiration -Neuron Model and Net</li> </ul>	work		<u> </u>
Architecture:	Objectives – notation – neuron model – Network Architectures – A laye	ər of		
neurons – mu	Itiple layers of Neurons-recurrent networks – An Illustrative example - Percer	ptron	С	:05
Learning Rule	Perceptron Learning Rule : Perceptron architecture –Perceptron learning rule	ule –		
proof of conve	rgence			
	TOTAL : 4	5 PE	RIO	DS
TEXT BOOKS	;			
1. Leand	ro Nunes de Castro, "Fundamentals of Natural Computing, Basic Concepts,	Algor	ithn	ns
and Ap	oplications", Chapman & Hall/ CRC, Taylor and Francis Group, 2007			
'				
	e J Klir / Bo Yuan ," Fuzzy Sets and Fuzzy Logic Theory and Applications", P	rentic	еH	lall

Applications", Prentice Hall, First Edition.

### **REFERENCE BOOKS**

1. Floreano D. and Mattiussi C., "Bio-Inspired Artificial Intelligence: Theories, Methods, and Technologies", MIT Press, Cambridge, MA, 2008.

Albert Y.Zomaya, "Handbook of Nature-Inspired and Innovative Computing", Springer, 2006.

3. Marco Dorrigo, Thomas Stutzle," Ant Colony Optimization", PHI,2005

### **COURSE OUTCOMES**

Upon completion of the course, students will be able to understand

CO1 The concepts of Natural systems and its applications.

CO2 Basic Natural systems functions(operations) and Natural design considerations.

CO3 The Integration of Hardware and software in Natural applications.

CO4 The basic concept of fuzzy sets, fuzzy logic & defuzzification

CO5 The basics of Artificial Neural Networks

|--|

COs				PR	OGR/		UTCO	MES	(POs	;)			ECIFIC S		
005	РО 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	PO ۹	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	2	2	2	2	1	1	-	-	1	1	1	1	2	2	2
CO2	2	2	2	2	1	1	-	-	1	1	1	1	2	2	2
CO3	2	2	2	2	1	1	-	-	1	1	1	1	2	2	2
CO4	2	2	2	2	1	1	-	-	1	1	1	1	2	2	2
CO5	2	2	2	2	1	1	-	-	1	1	1	1	2	2	2

ML1503 WEB PROGRAMMING (LAB INTEGRATED) L	Т	Ρ	С
3	0	2	4
OBJECTIVES			
<ul> <li>To understand and explore HTML, CSS and Javascript</li> </ul>			
<ul> <li>To design interactive web pages using Scripting languages</li> </ul>			
<ul> <li>To understand the concepts of TypeScript and practice Angular JS Framework</li> </ul>			
<ul> <li>To work with Express, a Node.js web application framework</li> </ul>			_
To develop solution to complex problems using appropriate method, technologies, f	rame	wor	ks,
web services and content management       UNIT I     Web Essentials, HTML & CSS			9
UNIT I         Web Essentials, HTML & CSS           Internet-Basic         Internet Protocols -The World Wide Web-HTTP request message-resp	0000		Э
message-Web Clients-Web Servers - XHTML: Syntax and Semantics - HTML Basic Element			
HTML5 control elements – Semantic elements – Drag and Drop – Audio – Video control			
CSS3 – Inline, embedded and external style sheets – Rule cascading – Inheritan			
Backgrounds - Border Images - Colors - Shadows - Text - Transformations - Transition			01
Animations.			
Lab Component			
<ul> <li>Design a Webpage using all HTML elements</li> </ul>			
Create a web page with all types of Cascading style sheets and CSS Selectors			-
UNIT II Client-Side Scripting and HTML DOM			9
Introduction JavaScript in Perspective-Syntax-Variables and Data Types-Statem			
Operators-Literals-Functions-Objects-Arrays-Built-in Objects-JavaScript Debuggers.			
Introduction to the Document Object Model DOM History and Levels-Intrinsic Event Hand Modifying Element Style-The Document Tree-DOM Event Handling	anng-		
Lab Component		C	02
Write Client Side Scripts for Validating Web Form Controls using DHTML Design the follo	wina	Ŭ	02
using JavaScript and DOM			
a. Include Image Slide Show and Digital clock			
b. Develop a web application to implement online quiz system			
UNIT III WEB APPLICATIONS AND ANGULAR.JS		-	9
Web Application Frameworks - MVC (Model-View-Controller) framework - Jumping			
TypeScript - Learning the Different Types Understanding Interfaces - Implementing Class			
Implementing Modules - Understanding Functions - Why Angular? Understanding Angu			
Adding Angular to Your Environment-Using the Angular CLI - Creating a Basic An Application Angular Components - Component Configuration - Building a Template-Inje	0		
Directives – Expressions - Using Expressions - Using Pipes - Building a Custom Pipe	cung		
Lab Component		С	<b>O</b> 3
• Use built-in Angular directives to show and hide elements and display lists of data.			
• Design a shopping cart application using AngularJS. Your shopping webpage sh	nould		
have the provisions for selecting the list of items from different category, Once the i			
are selected on clicking the submit button the items in the cart with its price shoul	d be		
displayed			
UNIT IV INTRODUCTION TO NODE.JS	<del></del>		9
Understanding Node.js - Event Model – Express Framework - Configuring Routes - U	•		
Requests Objects - Using Response Objects - Handling POST Body Data Sending			
Receiving Cookies - Implementing Sessions - Applying Basic HTTP Authenticati			
Implementing Session Authentication - Working with JSON - Processing URLs - Proces Query Strings and Form Parameters - Understanding Request, Response, and Server Ob	•		
<ul> <li>Implementing HTTP Clients and Servers in Node.js - Creating a simple server, Rend</li> </ul>	•		04
HTML, Rendering JSON Data- MongoDB-Manipulating and Accessing MongoDB Docum	•		
from Node.js	iciito		
Lab Component			
<ul> <li>Design an online super market using Express JS and MongoDB database</li> </ul>	اھ ڊ		
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			y the	produ	uct de	etails (	of diff							results , rice field	
		Servin			-	-									
UNIT V					ORK		1-								9
Impleme in AJAX															
methods															
React JS															
Lab Con					00		agne	aonin	gana	00110		ondon			CO5
To Build	•														
	AJAX	•••													
b) A	Applica	tion us	sing F	React.	.JS										
TEXT BO	OOKS												TOTAL	_ : 45 PE	RIODS
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Angular		-	-	-	/, All	Lenne			105 1	abolua	a, ng-	000K,		nplete B	OOK ON
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4. Krasi 5. Jeffre 2007				e.js by	y Exai	mple	Paper	back'	', May	201		spectiv	ve", Pear	rson Edu	ucation,
5. Jeffre	ey C. J	Jackso	on, "V	e.js by	y Exai	mple	Paper	back'	', May	201		spectiv	ve", Pear	rson Edu	ucation,
5. Jeffre 2007 <b>WEB RE</b>	ey C EFERE https://	Jacksc NCES /javas	on, "V <b>S</b> cript.i	e.js by Veb T	y Exai ſechn	nple ologie	Paper	back'	', May	201		spectiv	ve", Pear	rson Edu	ucation,
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5. Jeffre 2007 WEB RE	ey C. C EFERE https:// https:// https://	Iackso Inces Javas /www. /angul /nodej	on, "V cript.i types lar.io/ js.org/	e.js by Veb T nfo/ criptla	y Exai Fechn ang.o	nple ologie	Paper	back'	', May	201		spectiv	ve", Pear	rson Edu	ucation,
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CO3

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	(Common to AI-DS)	0	0	4	2
OBJE	CTIVES				
•	To be able to reason under uncertainty of the real-world.				
٠	To understand supervised learning techniques.				
•	To increase knowledge about learning with hidden variables.				
•	To understand how to use natural language processing.				
٠	To get familiarized with basics of robotics.				
LIST (	OF EXPERIMENTS				
1.	Implement a Python program of automatic Tic Tac Toe game using random r	umbe	r.		
	Apply Bayes' Rule to a scenario of drug screening, which is a mandatory federal or many other jobs which promise a drug-free work environment.				
3	Demonstrate the application of Bayesian Network for the Monty Hall Pro-	blem	The	-	
0.	Monty Hall problem is a brain teaser, in the form of a probability puzzle. A				
	you're on a game show, and you're given the choice of three doors: Behind				
	a car; behind the others, goats. You pick a door, say No. 1, and the host,				; <b>0</b> ,
	what's behind the doors, opens another door, say No. 3, which has a goa				•
	says to you, "Do you want to pick door No. 2?" Is it to your advantage to s				
	choice?	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	y e ai		
4	Write a Python program to create a fuzzy control system which models how		niaht		
	choose to tip at a restaurant. When tipping, you consider the service and for		0		
	rated between 0 and 10. You use this to leave a tip of between 0 and 25%.	<i>,</i> ou qu	ianty,		
5	Formulate a decision tree, which is applicable in the field of medical science	es tha	t will		
0.	help predict whether or not a patient has diabetes.				
6	Implement Adaptive Boosting in Python for a simple fruit classification	n prot	olem		
0.	Consider classification of the fruits into oranges or apples. The characterist				
	provided for the fruits to be classified are weight and size (diameter). Clas				
	fruit as either apple or orange just based on the data on the size and weights	•	11011		:02
7	For a coin toss example with incomplete information, we have missing da		1 the		-
	problem of estimating $\theta$ , where $\theta$ is the probability of heads or tails is hard				
	Apply Expectation Maximization (EM) Algorithm to start with a guess f				
	calculate z, then update $\theta$ using this new value for z, and repeat till converge				
	label of the coin is indicated by z.	Joneo.			
8	Perform text classification for a real-world example. Consider a model	canah	le of		
0.	predicting whether a given movie review is positive or negative. Us				
	sentiments which are classified into different categories and based upo				
	classification give either a positive review or a negative review.		.0/.(		
9	Given a robot which can only move in four directions, UP (U), DOWN (D), LE	FT (I.)	and		
0.	RIGHT(R). Given a string consisting of instructions to move. Output the coord				:0:
	robot after executing the instructions. Initial position of robot is at origin $(0, 0)$		, oi a		•
10	A robot moves in a plane starting from the original point (0, 0). The robot		nove		
10	toward UP, DOWN, LEFT and RIGHT with a given steps. Write a program				
	the distance from current position after a sequence of movement and origin				
	the distance is a float, then just print the nearest integer.				
		AL:6	0 PE	RIO	D
		<u></u>	• • -		
LIST (	OF EQUIPMENT FOR A BATCH OF 30 STUDENTS				
Standa	alone desktops with Python 3 Interpreter for Windows/Linux 30 Nos.				
REFE	RENCE BOOKS				
1.	S. Russell and P. Norvig, "Artificial Intelligence: A Modern Approach, Pl	entice	Hal	l, TI	nir
	Edition, 2009.				
2.	Kevin Night and Elaine Rich, Nair B., "Artificial Intelligence (SIE)", Mc Graw H	lill- 20	08.		

WEB RE	FERE	NCES	5												
3. https://learn-robotics.com/															
COURS		<u></u>	<b>E</b> 6												
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with hidden variables.CO3Use natural language processing and program basics of robotics.															
CO3 U	se na	ural la	angua	age pr	ocess	sing a	na pro	ogram	Dasio	cs of ro	DODICS	•			
				Μ	APPI	NG O	F CO	s WI	TH PC	)s AN[	D PSO	S			
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COs				FN	JGRA				(FU3	<b>)</b>			OUTC	OMES (	PSOs)
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	1	2	3	4	5	6	7	8	9	10	11	12	F301	F302	F303
CO1	3	3	3	3	2	2	1	1	2	2	2	3	3	3	3
CO2	3	3	3	3	2	2	1	1	2	2	2	3	3	3	3
CO3	3	3	3	3	3	2	1	1	2	2	2	3	3	3	3

ML1601       DEEP LEARNING       L       T       P       C         3       1       0       3       1       0       3         OBJECTIVES         •       To familiarize the fundamental concepts and principles of neural networks.       •       To explore the basic concepts of deep learning.         •       To familiarize with CNN and RNN models.       •       •       To inderstand and develop deep learning architectures.       •       •       To implement various applications using deep learning.       •
OBJECTIVES         • To familiarize the fundamental concepts and principles of neural networks.         • To explore the basic concepts of deep learning.         • To familiarize with CNN and RNN models.         • To understand and develop deep learning architectures.         • To implement various applications using deep learning.         UNIT I         INTRODUCTION TO DEEP LEARNING         Basic Concept of Neurons – Perceptron Algorithm – Shallow Neural Networks – Non Linear Activation Functions - Gradient Descent and Backpropagation – Shallow and Deep Learning Networks         UNIT II       IMPROVING NEURAL NETWORKS         Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient - Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –
<ul> <li>To familiarize the fundamental concepts and principles of neural networks.</li> <li>To explore the basic concepts of deep learning.</li> <li>To familiarize with CNN and RNN models.</li> <li>To understand and develop deep learning architectures.</li> <li>To implement various applications using deep learning.</li> <li>UNIT I</li> <li>INTRODUCTION TO DEEP LEARNING</li> <li>Basic Concept of Neurons – Perceptron Algorithm – Shallow Neural Networks – Non Linear Activation Functions - Gradient Descent and Backpropagation – Shallow and Deep Learning Networks</li> <li>UNIT I</li> <li>IMPROVING NEURAL NETWORKS</li> <li>Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient - Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –</li> </ul>
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UNIT I       INTRODUCTION TO DEEP LEARNING       S         Basic Concept of Neurons – Perceptron Algorithm – Shallow Neural Networks – Non Linear Activation Functions - Gradient Descent and Backpropagation – Shallow and Deep Learning Networks       CO1         UNIT II       IMPROVING NEURAL NETWORKS       S         Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient - Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –       CO2
Basic Concept of Neurons – Perceptron Algorithm – Shallow Neural Networks – Non Linear         Activation Functions - Gradient Descent and Backpropagation – Shallow and Deep Learning         Networks         UNIT II         IMPROVING NEURAL NETWORKS         Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini         Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient -         Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and         Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –
Activation Functions - Gradient Descent and Backpropagation – Shallow and Deep Learning Networks       CO1         Networks       IMPROVING NEURAL NETWORKS       S         Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient - Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –       CO2
Networks       Improving NEURAL NETWORKS         UNIT II       IMPROVING NEURAL NETWORKS         Overfitting – Regularization – Dropout – Vanishing and Exploding Gradients Problem - Mini         Batch Gradient Descent – Weight Initialization Strategies - Nesterov Accelerated Gradient -         Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and         Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –
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Momentum – RMSProp – ADAM - Mitigation — Heuristics for Avoiding Bad Local Minima and Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –
Faster Training – Mini Batch Gradient Descent - Batch Normalization - Adversarial Training –
Optimization for Training Deep Models.
UNIT III CONVOLUTIONAL NEURAL NETWORKS S
Convolution Operations – Pooling Layers – ResNets – CNN Architectures - Transfer Learning –
Data Augmentation – Image Classification using Transfer Learning – Autoencoders – Deep CO3
Generative Models – Generative Adversarial Networks (GANs) – Evaluation GANs.
UNIT IV SEQUENCE MODELS AND NATURAL LANGUAGE PROCESSING S
Recurrent Neural Networks – Vanishing Gradients in RNNs - Gated Recurrent Units - Long Short Term Memory (LSTM) Networks – Bidirectional RNNs - Sequence Prediction – Transfer
Learning – Language Models – Word Embeddings – Beam Search - Attention Models –
Transformer Networks.
UNIT V APPLICATIONS OF DEEP LEARNING
Image segmentation – Object Detection – Image Captioning – Image generation with
Generative adversarial networks - Video to Text with LSTM models - Attention models for
Computer Vision – Case Study: Named Entity Recognition – Opinion Mining using Recurrent COS
Neural Networks – Parsing and Sentiment Analysis using Recursive Neural Networks –
Sentence Classification using Convolutional Neural Networks.
TOTAL : 45 PERIODS
TEXT BOOKS
1. Ian J. Goodfellow, Yoshua Bengio, Aaron Courville, "Deep Learning", MIT Press, 2017.
2. Francois Chollet, "Deep Learning with Python", Manning Publications, 2018
REFERENCE BOOKS
<b>REFERENCE BOOKS</b> 1. Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia
1. Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia
1. Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.
<ol> <li>Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.</li> <li>Ragav Venkatesan, Baoxin Li, "Convolutional Neural Networks in Visual Computing", CRC Press</li> </ol>
<ol> <li>Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.</li> <li>Ragav Venkatesan, Baoxin Li, "Convolutional Neural Networks in Visual Computing", CRC Press 2018.</li> </ol>
<ol> <li>Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.</li> <li>Ragav Venkatesan, Baoxin Li, "Convolutional Neural Networks in Visual Computing", CRC Press 2018.</li> <li>Navin Kumar Manaswi, "Deep Learning with Applications Using Python", Apress, 2018. 4. Joshua F</li> </ol>
<ol> <li>Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.</li> <li>Ragav Venkatesan, Baoxin Li, "Convolutional Neural Networks in Visual Computing", CRC Press 2018.</li> <li>Navin Kumar Manaswi, "Deep Learning with Applications Using Python", Apress, 2018. 4. Joshua F Wiley, "R Deep Learning Essentials", Packt Publications, 2016.</li> </ol>
<ol> <li>Phil Kim, "Matlab Deep Learning: With Machine Learning, Neural Networks and Artificia Intelligence", Apress, 2017.</li> <li>Ragav Venkatesan, Baoxin Li, "Convolutional Neural Networks in Visual Computing", CRC Press 2018.</li> <li>Navin Kumar Manaswi, "Deep Learning with Applications Using Python", Apress, 2018. 4. Joshua F</li> </ol>

COUR	SE	OUT	СОМ	ES												
Upon	-			-	cours	se, st	udent	ts wil	l be a	ble to	)					
CO1	Kn	ow th	ne imp	oortan	ce of	deep	learn	ing in	mach	nine le	arning	applic	ations			
CO2	De	Design and implement deep learning applications.														
CO3	De	sign	and ir	nplen	nent C	CNN a	ind RI	NN.								
CO4	Design and implement CNN and RNN. Understand the use of different deep learning models in image processing.															
CO5	Explore the applications of deep learning in various domains.															
					М	APPI	NG O	F CO	s WI	гн рс	)s AN[	D PSO	s			
COs					PR	) GR	AM O	UTCC	MES	(POs	5)				RAM SP OMES (	
COS		PO 1	PO 2	PO 3	PO 4	РО 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1		1     2     3     4     5     6     7     8     9     10     11     12     F301     F302     F303       1     1     1     1     1     1     2     1     1     12     2     2     2														

CO2

CO3

CO4

CO5

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ML1602	AUTONOMOUS MOBILE ROBOT L P	<u> </u>	C
OBJECTIVE	<u> </u>	0	3
	derstand the fundamental concepts of Autonomous mobile robotics.		
	now about robot sensory perception algorithms, sensor suites and robot control	thr	ouah
	bry feedback.	unv	ougn
	iderstand the basic concepts and algorithms required for locomotion and mot	مانم	robot
	natics.		0000
• To ge	t deep knowledge about mapping and localization.		
· ·	nderstand the basic concepts and algorithm required for mobile robot plan	ning	and
navig		0	
	FUNDAMENTAL CONCEPTS OF AUTONOMOUS MOBILE ROBOTICS		9
	to Robotics- Robot features, sensors, manipulators- Application areas-State	of	
	earch and adoptionRobotic hardware systems- Intelligence and embodimer		CO1
	Ilenges of Mobile Autonomous Robots- Challenges of Autonomous Manipulation.		
	ROBOTICSENSORS AND VISION		9
	sors- Proprioception of robot kinematics and internal Forces- Sensors using light	t_	
	ng sound- Inertia-based sensors- Beacon-based sensors-Vision- Images as two		
			CO2
	signals- From signals to information- Basic image operations- Feature extraction	1-	
	AND Error Propagation.		
			9
	Introduction- Legged Mobile Robots- Wheeled Mobile Robots- Aerial Mobi		
	bile Robot Kinematics: Introduction-Kinematic Models and Constraints- Mobi		CO3
	uverability- Mobile Robot Workspace- Beyond Basic Kinematics- Motion Contr	וכ	
(Kinematic C			
UNIT IV	LOCALIZATION AND MAPPING		9
Introduction-			
Programmed	Solutions- Belief Representation- Map Representation- Probabilistic Map Base	d	CO4
Localization-	Examples of Localization Systems- Autonomous Map Building.		
UNIT V	PLANNING AND NAVIGATION		9
Introduction-	Planning and Reacting- Path Planning- Obstacle avoidance- Bug algorithm-		
Vector field h	istogram- The bubble band technique- Curvature velocity techniques- Dynamic		CO5
window appr	oaches- The Schlegel approach to obstacle avoidance- Nearness diagram-		
Gradient me	hod- Adding dynamic constraints- Navigation Architectures.		
	TOTAL : 45 P	ERI	ODS
TEXT BOOK	S		
	luction to Autonomous Mobile Robots ,2nd edition 2011 Roland Siegwart,	Illa	hR.
	h, and DavideScaramuzza	ma	

REFE	RE	NCE	BOO	٢S												
1.	Pr	obabi	ilistic	roboti	cs, M	IT Pre	ess, T	hrun,	Burga	ards, a	and Fo	x. 200	5			
2.														lichael 、	Jenkin. 2	2nd ed.
	Ca	ambri	dge U	nivers	sity P	ress, ž	2010.				•••					
3.	Ro	bot N	Nodel	ing ar	nd Co	ntrol.	Mark	W. S	pong,	Seth	Hutch	inson a	and M.	Vidyasa	gar. Joh	n Wiley
	3. Robot Modeling and Control. Mark W. Spong, Seth Hutchinson and M. Vidyasagar. John Wiley and Sons, 2006.															
4.	4. Computational Principles of Mobile Robotics, Gregory Dudek, Michael Jenkin, Cambridge															
University Press, 2010.																
5.	Αι	utonoi	mous	Robo	ts, Ge	eorge	A. Be	ekey, I	MIT P	ress,	2005.					
COUR	RSE	OUT	СОМ	ES												
Upon	100	mplet	ion o	f the	cours	se, st	udent	s wil	l be a	ble to	)					
CO1	Ur	nderst	tand t	he fur	ndame	ental o	conce	pts of	<sup>:</sup> Auto	nomo	us mol	bile rot	ootics			
CO1Understand the fundamental concepts of Autonomous mobile roboticsCO2Discuss the essential of Robotic Sensors and Vision																
CO3	Ur	nderst	tand	the c	once	ots ai	nd al	gorith	ms fo	or mo	bile ro	obot la	ocomo	ion and	mobile	e robot
	Ki	nema	tics		-			-								
CO4	Ge	et firm	n gras	p of th	ne alg	orithn	ns for	mapp	oing a	nd loc	alizati	on				
CO5	De	escrib	e the	conce	epts a	nd alg	gorith	m req	uired	for m	obile ro	bot pla	anning	and nav	rigating	
					M	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S		-	
					חח					(00-				PROG	RAM SP	ECIFIC
COs	6				PR	JGRA				(POs	)			0	UCOME	S
		P01	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1	2	1	1	-	-	-	1	1	2	2	2	2	1	2
CO2	2	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO3	3	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO4	1	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO5	5	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2

ML1603	PROBABILISTIC GRAPHICAL MODELS		P	<u>T</u>	C
OBJECTIVES	3	3	1	0	3
To develop th	e knowledge and skills necessary to design implement and apply probabil	isti	c gra	aph	ical
models to solv	re real problems		•		
• To understar	nd bayesian networks, undirected graphical models and their temporal exte	nsi	ons.		
To introduce	exact and approximate inference methods				
• To learn esti	mation of the parameters and the structure of graphical models.				
UNIT I	REPRESENTATION				9
Representatio	I are a second to the second term of term	ion	s to		
graphs, Undir	ected Graphical Models - parameterization, Markov network independe	enc	ies,	С	:01
Bayesian to M	arkov networks, partially directed models				
UNIT II	LOCAL PROBABILISTIC AND TEMPORAL MODELS				9
Local probabi	istic Models - Tabular conditional probability distributions (CPDs), detern	nin	istic		_
CPDs, contex	kt specific CPDs, independence of causal influence, continuous var	iab	les,		
conditional Ba	yesian networks, Template based representations - temporal models, di	irea	cted	C	02
models, undire	ected models, structural uncertainty - Gaussian network models.				
UNIT III	INFERENCE				9
Inference - Va	I riable elimination, conditioning, inference with structured CPDs, exact infer	ren	ce -		
clique trees,	message passing, inference as optimization, exact inference as optimi	zat	ion,		
propagation-b	ased approximation, propagation with approximate messages, Particle-	Ba	sed	С	:03
Approximate	nference - likelihood weighting and importance sampling, Markov chain	Mo	onte		
Carlo methods	s, collapsed particles, Deterministic search methods.				
UNIT IV	MAXIMUM A POSTERIORI(MAP)				9
MAP Inference	e - variable elimination for MAP, Max product in clique trees, Max-product	t be	elief		
propagation in	loopy cluster graphs, MAP as a linear optimization problem, graph cuts for	r M	AP,		
Inference in te	emporal models - Inference in hybrid networks - variable elimination in Ga	us	sian		04
networks - nor	n-linear dependencies - inference in temporal models				
UNIT V	LEARNING				9
Learning - Le	arning Graphical Models - learning as optimization, learning tasks, Para	am	eter		<u> </u>
estimation -	learning with shared parameters, Bayesian networks, Structure learn	ning	g in	С	:05
Bayesian netw	ork - constraint based approaches, structure scores, structure search.				
	TOTAL :	45	PE	RIO	DS
TEXT BOOKS	6				
1. Daphne Ko	ler, Nir Friedman, Probabilistic Graphical Models - Principles and Techniqu	ies	,		
	2009				
The MIT Press	3, 2003.				

#### **REFERENCE BOOKS**

1. Kiren R Karkera, Building Probabilistic Graphical Models with Python, Packt, 2014

2. Adnan Darwiche, Modeling and Reasoning with Bayesian networks, First edition, Cambridge University Press, 2014

3. Christopher M. Bishop, Pattern Recognition and Machine Learning, Second edition, Springer, 2011

4. Kevin P. Murphy, Machine Learning: a Probabilistic Perspective, MIT Press, 2012

# **COURSE OUTCOMES**

Upon completion of the course, students will be able to

CO1	Explore the various representations of Probabilistic Graphical Models.

CO2 Understand different Local Probabilistic and Temporal Models.

CO3 Apply inference as an optimization tool in various Probabilistic Graphical Models.

CO4 Understand MAP inference techniques and inference in temporal models.

CO5 Apply learning as an optimization tool for decision making.

### MAPPING OF COs WITH POs AND PSOs

COs				PR	OGRA		UTCC	MES	(POs	5)				RAM SP	
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	-	3	-	-	2	2	2	3	3	2
CO2	3	3	3	3	2	-	2	-	-	2	2	2	3	3	2
CO3	3	3	3	3	2	-	1	-	-	2	2	2	3	2	2
CO4	3	3	3	3	2	-	-	3	-	2	2	2	3	3	2
CO5	3	3	3	3	2	-	-	-	-	2	2	2	3	2	2

ML1604		Т	С						
OBJECTIVES		0	3						
	• d the basics of big data and analytics.								
	he frameworks for working with big data								
•	out stream computing.								
	put recommender systems and data analytics methods in R.		1						
UNITI	INTRODUCTION TO BIG DATA AND HADOOP		Ş						
Types of Digi	tal Data - Characteristics of Data - Evolution of Big Data - Definition of Big Data -								
Challenges w	vith Big Data - Vs of Big Data - Non Definitional traits of Big Data - Business								
Intelligence v	s. Big Data - Understanding Big Data Storage - Examples of Big Data in Real Life	С	01						
- Big Data Ap	pplications - History of Hadoop, Apache Hadoop, Analysing Data with Hadoop -								
Hadoop Strea	Iming								
UNIT II	BIG DATA FRAMEWORK AND NOSQL		9						
Hadoop Ecos	ystem - Overview of: Apache Spark, Pig, Hive, Hbase, Sqoop - What is NoSQL?		]						
NoSQL data	architecture patterns: Key-value stores, Graph stores, Column family (Bigtable)								
stores, Document stores - Mongo DB: Introduction – Features - Data types - Mongo DB Query									
	RUD operations – Arrays - Functions: Count – Sort – Limit – Skip – Aggregate -								
•••	Cursors – Indexes - Mongo Import – Mongo Export.								
	MAP REDUCE		9						
	The Map Tasks - Grouping by Key - The Reduce Tasks – Combiners - Details of								
•	Execution - Coping With Node Failures - Algorithms Using MapReduce: Matrix-								
•									
•	lication by MapReduce – Relational Algebra Operations - Computing Selections	~	<u> </u>						
	e - Computing Projections by MapReduce – Union – Intersection and Difference	C	0						
•	ce - Computing Natural Join by MapReduce - Grouping and Aggregation by								
•	- Matrix Multiplication - Matrix Multiplication with One MapReduce Step -								
	e of MapReduce with use of real life databases and applications.		1						
UNIT IV	STREAM MEMORY								
Introduction to	o Streams Concepts – Stream Data Model and Architecture - Stream Computing,								
Sampling Dat	a in a Stream - Filtering Streams - Counting Distinct Elements in a Stream -								
Estimating m	oments - Counting oneness in a Window - Decaying Window - Real time	С	0						
Analytics Plat	form(RTAP) applications - Case Studies - Real Time Sentiment Analysis, Stock								
Market Predic	tions. Using Graph Analytics for Big Data: Graph Analytics								
UNIT V	RECOMMENDATION SYSTEM AND REVIEW OF BASIC DATA ANALYTIC		9						
	METHODS USING R								
Recommenda	Ition System: Collaborative Recommendation- Content Based Recommendation -		<u> </u>						
	ased Recommendation - Hybrid Recommendation Approaches –Introduction to R	С	0						
-	Data Analysis – Statistical methods for evaluation.	_							
			D						

### TEXT BOOKS

1. Seema Acharya, Subhasini Chellappan, "Big Data Analytics – 2<sup>nd</sup> Edition" Wiley 2019.

2. Anand Rajaraman and Jeffrey David Ullman, "Mining of Massive Datasets – 3<sup>rd</sup> Edition", Cambridge University Press, 2020.

3. Dietmar Jannach and Markus Zanker, "Recommender Systems: An Introduction – 2<sup>nd</sup> Edition", Cambridge University Press, 2015.

4. EMC Education Services, "Data Science and Big Data Analytics: Discovering, Analyzing, Visualizing and Presenting Data", Wiley publishers, 2015.

### **REFERENCE BOOKS**

1. Kyle Banker, Piter Bakkum, Shaun Verch, "MongoDB in Action - 2<sup>nd</sup> Edition", Manning Publications, 

2. Tom White, "HADOOP: The definitive Guide – 4<sup>th</sup> Edition", O Reilly 2015.

3. Vignesh Prajapati, "Big Data Analytics with R and Hadoop", Packt Publishing 2013

## **COURSE OUTCOMES**

CO3

CO4

CO5

Upon completion of the course, students will be able to

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CO1	Learn Big Data and Hadoop															
CO2	Le	Learn NoSQL databases and management.														
CO3	Learn MapReduce															
CO4	4 Perform analytics on data streams															
CO5	5 Learn recommendation systems for large volumes of data															
	MAPPING OF COs WITH POs AND PSOs															
COs	PROGRAM OUTCOMES (POs)													RAM SPECIFIC		
		PO 1	PO 2	PO 3	РО 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	I	1	1	1	1	1	1	1	-	-	-	1	1	2	2	2
CO2	2	1	2	2	1	2	1	1	-	-	-	1	1	2	2	2

ML1607					DE	EP LE	ARN	ING L	ABO	RATO	RY			L	Τ	Ρ	С
														0	0	4	2
	troduc				arning	g algo	orithm	s, the	prob	lem se	ttings,	and th	neir appli	catio	ons t	o sc	olve
	al woi	•			lao of	nour		worko	and	doon la	ornino						
			-		-					•	earning					ما دا سه	~ ~
Ar	rtificia	Neu	ral Ne	twork									nd remei			-	-
	oply l etworl		ng al	gorith	ms o	n pei	ceptr	on ar	nd ap	ply ba	ick pro	opagat	tion lear	ning	on	Ne	ura
• De	esign	Conv	olutio	nal Ne	eural	Netwo	ork an	d clas	ssifica	tion us	sing Co	onvolut	tional Ne	ural	Net	vork	
LIST OF																-	
<u>1. To</u>									<u> </u>								
			<u> </u>								propa	<u> </u>					
													Designer			- c	:01
	•		ind d	emor	strate	e the	new	deel	o nei	iral ne	etwork	tor c	lassificat	tion	and		
	gress			Deel		4-4-			:				n na al'at'a				
													predictio	n			
											es dat						
										gnize	objects	s in im	ages			_	
<b>8.</b> W													<u> </u>			-	:02
	Write a program to Train on CPU, GPU, multiple GPUs, in parallel on your desktop or on clusters in the cloud, and work with data sets too large to fit in memory																
																_	
											ork, VG					_	
Ne	etworl	(	•		•				•		•		Recurren	nt Ne	eura	С	:0:
<b>12.</b> Ci	reate	Simpl	e Sec	luenc	e Clas	ssifica	ation N	letwo	rk Us	ing De	ep Net	work [	Designer				
													TOTAL	.:6	0 PE	RIO	)D
LIST OF																	
Standalor	ne des	sktops	s with	Pytho	on 3 li	nterpr	eter fo	or Wir	ndows	s/Linux	30 No	s.					
COURSE	OUT	СОМ	ES														
Upon co	mplet	ion o	f the	cours	se, sti	udent	ts will	l be a	ble to	)							
CO1 Ur	nderst	and t	he im	pleme	entatio	on pro	cedui	res fo	r the [	Deep le	arning	g algor	ithms.				
CO2 De	esign	MatLa	ab/Py	thon p	orogra	ams fo	or vari	ous L	earnir	ng algo	rithms						
CO3 To	o learr	n data	scier	nce ar	nd des	sign a	nd im	pleme	ent va	rious c	onvolu	itional	Neural N	letw	orks		
						<u> </u>											
				Μ	APPI	NG O	F CO	s WI	гн рс	)s AN[	) PSO	s					
				PR	OGR/		UTCO	MES	(POs	)			PROG OUTC				
COs	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO					
	1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PS	02	PS	<b>50</b> 3

CO2

CO3

#### ML1608 SOCIALLY RELEVANT PROJECT Ρ С L Т 0 0 4 2 Choose any project of solving social problems Team Project with a maximum of two in a team • Need to concentrate on software development methodologies • Documentation is based on the standards • Evaluation pattern is like Lab examination, Need to submit a report, presentation with demo. • MAPPING OF COs WITH POs AND PSOs **PROGRAM SPECIFIC** PROGRAM OUTCOMES (POs)

COs				FN	JOR				(FU3	·)			OUTC	OMES (	PSOs)
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
CO2	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
CO3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3

ML1701	STATISTICAL NATURAL LANGUAGE PROCESSING	L	Τ	Ρ	С
		3	1	0	3
OBJECTIVES					
	n the fundamentals of natural language processing				
	lerstand word level and syntactic analysis.				
	lerstand the syntax analysis and parsing				
	lerstand the role of semantics of sentences and pragmatics				
<ul> <li>To get</li> </ul>	knowledge about the machine translation				
UNIT I	INTRODUCTION				9
	History of NLP- Challenges and Applications of NLP - Ambiguity and U				
	NLP Phases - Language Modelling- Various Grammar-based Language				
	nguage Model- N-gram Language Models – Markov Process- E				:0
	and smoothing - Evaluating language models- Regular Expres	sion	Text		
Normalization	–Minimum Edit Distance.				
	PART OF SPEECH TAGGING AND SYNTACTIC PARSING			_	
	Named Entities and Named Entity Tagging- Conditional Random Fields	s (CF	RFs)-	Τ	
	Named Entity Recognition- HMM Part-of-Speech Tagging-Trigran				:02
	ls- Decoding with HMMs: the Viterbi Algorithm- Syntactic Parsing-		cient		,04
parsing for cor	ntext-free grammars (CFGs)- Semantic Parser – Semantic Role Labellin	g			
		0		$^{\perp}$	
	res of Information Retrieval systems - Information Retrieval Models -				
Information D					
	etrieval Models - Non-classical models of IR -Alternative Models			C	:0
Evaluation of	the IR System- Natural Language Processing in IR -Relation M	atchi	ng -	C	:0
Evaluation of		atchi	ng -	C	:0
Evaluation of	the IR System- Natural Language Processing in IR -Relation M	atchi	ng -	C	0
Evaluation of Knowledge-ba	the IR System- Natural Language Processing in IR -Relation M used Approaches - Conceptual Graphs in IR -Cross-lingual Information R	atchi	ng -	C	0
Evaluation of Knowledge-ba	the IR System- Natural Language Processing in IR -Relation M	atchi letrie	ng - val.		
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural	the IR System- Natural Language Processing in IR -Relation M used Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regres Networks - Error Analysis – Vector Space models – Language Modellin	atchi atrie ssion g wit	ng - val. , Naï'	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural	the IR System- Natural Language Processing in IR -Relation M used Approaches - Conceptual Graphs in IR -Cross-lingual Information R ne Learning for NLP Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regres	atchi atrie ssion g wit	ng - val. , Naï'	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo	the IR System- Natural Language Processing in IR -Relation M used Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regres Networks - Error Analysis – Vector Space models – Language Modellin	atchi atrie ssion g wit	ng - val. , Naï'	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions -	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Indels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks	atchi atrie ssion g wit	ng - val. , Naï'	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b>	atchi atrie ssion g wit nilarit	ng - <u>val.</u> , Naï h y – 1	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic Question Ansy	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> wering with SQUAD – Dependency Parsing – Machine Translation – Cor	atchi atrie ssion g wit nilarit	ng - <u>val.</u> , Naï h y – 1	ve	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic Question Ansy	the IR System- Natural Language Processing in IR -Relation M ased Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin dels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> wering with SQUAD – Dependency Parsing – Machine Translation – Cor Text Summarization	atchi atchi assion g wit nilarit	ng - val. , Naï h :y – 1 nce	ve D	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic Question Answ Resolution – T	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> vering with SQUAD – Dependency Parsing – Machine Translation – Cor Tota	atchi atchi assion g wit nilarit	ng - val. , Naï h :y – 1 nce	ve D	
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic Question Answ Resolution – T	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> vering with SQUAD – Dependency Parsing – Machine Translation – Cor Tota	atchi atchi ssion g wit nilarit	ng - val. , Naï h ry – 1 nce <b>5 PE</b>	D RIC	D
Evaluation of Knowledge-ba Unit IV Machi Vocabulary & Bayes, Neural Sequential Mo Convolutions - Unit V Applic Question Answ Resolution – T TEXT BOOKS 1. Daniel Natura	the IR System- Natural Language Processing in IR -Relation M Ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin Idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> wering with SQUAD – Dependency Parsing – Machine Translation – Cor Text Summarization Jurafsky, James H. Martin, "Speech and Language Processing: Ar I Language Processing, Computational Linguistics and Speech Reco	atchi atchi assion g wit nilarit nfere L : 4	ng - val. , Naï h ty – 1 nce <b>5 PE</b>	ve D RIC	<b>)D</b> :
Evaluation of Knowledge-ba	the IR System- Natural Language Processing in IR -Relation M ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> vering with SQUAD – Dependency Parsing – Machine Translation – Cor Text Summarization Jurafsky, James H. Martin, "Speech and Language Processing: Ar I Language Processing, Computational Linguistics and Speech Reco , Pearson Publication, 2014	atchi atchi atchi ssion g wit nilarit nilarit n Inti gnitic	ng - val. , Naï h xy – 1 nce <b>5 PE</b> coduc on", {	ve D RIC	DD: n tion
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Evaluation of Knowledge-ba	the IR System- Natural Language Processing in IR -Relation M ised Approaches - Conceptual Graphs in IR -Cross-lingual Information R <b>ne Learning for NLP</b> Feature Extraction – Bag of Words Model - ML for NLP: Logistic Regress Networks - Error Analysis – Vector Space models – Language Modellin idels - Embeddings for Words and Documents – Word2Vec - Cosine Sin Attention Mechanism – Transformers – Recursive Neural Networks <b>ations in NLP</b> wering with SQUAD – Dependency Parsing – Machine Translation – Cor Text Summarization Jurafsky, James H. Martin, "Speech and Language Processing: Ar I Language Processing, Computational Linguistics and Speech Reco , Pearson Publication, 2014 opher Manning, "Foundations of Statistical Natural Language Process indurkhya and Fred J. Damerau, "Handbook of Natural Language Process	atchi atchi atchi asion g wit nilarit nilarit n Inti gnitic ing",	ng - val. , Naï h ry – 1 roduc on", S MIT	ve D RIC	
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- YoavGoldberg,GraemeHirst, "Neural Network Methods for Natural Language Processing -Synthesis Lectures on Human Language Technologies", Morgan and Claypool Life Sciences, 2017.
- 5. DeeptiChopra,NisheethJoshiltiMathur, "Mastering Natural Language Processing with Python", First Edition, Packt Publishing Limited, 2016
- 6. Mohamed ZakariaKurdi "Natural Language Processing and Computational Linguistics 1: Speech, Morphology and Syntax", First Edition, ISTE Ltd. Wiley, 2016
- 7. AtefehFarzindar, DianaInkpen, "Natural Language Processing for Social Media, Second Edition, Morgan and Claypool Life Sciences, 2015

#### **COURSE OUTCOMES**

#### Upon completion of the course, students will be able to

CO1 To tag a given text with basic Language features

- CO2 To design an innovative application using NLP components
- CO3 To implement a rule based system to tackle morphology/syntax of a language

CO4 To design a tag set to be used for statistical processing for real-time applications

CO5 To apply NLG and machine translation

COs	PROGRAM OUTCOMES (POs) PROGRAM SPECIOUCOMES PROGRAM														
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	2	1	1	-	-	-	1	1	2	2	2	2	1	2
CO2	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO3	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO4	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2
CO5	1	2	1	1	-	-	-	1	1	2	2	2	2	2	2

	FORMAL LANGUAGES AND AUTOMATA THEORY	Ρ	С
<b>OBJECTIVES</b>	3 0	0	3
	retend a finite automate for a given language		
	rstand a finite automata for a given language. Irstand the relation between grammar and language		
	erstand the basic principles of working of a compiler		
	/ about the type checking procedure during the compilation		
-	erstand the storage structure of the running program		
UNIT I	AUTOMATA		9
Introduction to	formal proof – Additional forms of proof – Inductive proofs –Finite Automata (FA)	Τ	
– Deterministi	c Finite Automata (DFA) – Non-deterministic Finite Automata (NFA) – Finite	С	۰0
	Epsilon transitions- Equivalence and minimization of Automata.		
			Т
	CONTEXT FREE GRAMMARS AND LANGUAGES		
-		<del></del>	
	Grammar (CFG) – Parse Trees – Ambiguity in grammars and languages –		
	e Pushdown automata – Languages of a Pushdown Automata – Equivalence of		
Pushdown aut	omata and CFG- Deterministic Pushdown Automata- Normal forms for CFG -	C	0
Pumping Lem	ma for CFL – Closure Properties of CFL – Turing Machines – Programming		
Techniques for	TM.		
UNIT III	BASICS OF COMPILATION		9
Compilers – A	analysis of source program - Phases of a compiler - Grouping of phases -		
Compiler cons	truction tools – Lexical Analyzer : Token Specification – Token Recognition – A		0
language for	Specifying lexical analyzer - Top down parser : Table implementation of		.0.
	er – Bottom up Parser : SLR(1) Parser – Parser generators.		
Predictive Pars			
Predictive Pare		<u> </u>	
Predictive Pars	TYPE CHECKING AND RUNTIME ENVIRONMENTS		
UNIT IV	<b>TYPE CHECKING AND RUNTIME ENVIRONMENTS</b> d definitions – Construction of syntax trees – Type systems – Specification of a	  	
UNIT IV Syntax directer			
UNIT IV Syntax directer simple type ch	d definitions – Construction of syntax trees – Type systems – Specification of a	c	
UNIT IV Syntax directer simple type ch for a simple type	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage	c	
UNIT IV Syntax directer simple type ch for a simple type	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar	c	
UNIT IV Syntax directed simple type ch for a simple type organization –	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing	c	
UNIT IV Syntax directed simple type ch for a simple type organization – UNIT V	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing CODE GENERATION AND OPTIMIZATION	C	
UNIT IV Syntax directed simple type ch for a simple type organization – UNIT V Issues in the d	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing CODE GENERATION AND OPTIMIZATION esign of a code generator - The target machine - Run-time storage management	C	>o
UNIT IV Syntax directed simple type ch for a simple type organization – UNIT V Issues in the d - Basic blocks	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing CODE GENERATION AND OPTIMIZATION esign of a code generator - The target machine - Run-time storage management and flow graphs - Next-use information - A simple code generator - Register		
UNIT IV Syntax directed simple type ch for a simple type organization – UNIT V Issues in the d - Basic blocks allocation and	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing CODE GENERATION AND OPTIMIZATION esign of a code generator - The target machine - Run-time storage management and flow graphs - Next-use information - A simple code generator - Register assignment - The dag representation of basic blocks - Generating code from		
UNIT IV Syntax directed simple type ch for a simple type organization – UNIT V Issues in the d - Basic blocks allocation and	d definitions – Construction of syntax trees – Type systems – Specification of a ecker- Equivalence of type expressions – Type conversions – Attribute grammar be checking system – Runtime Environments: Source language issues – Storage Storage allocation strategies – Parameter passing CODE GENERATION AND OPTIMIZATION esign of a code generator - The target machine - Run-time storage management and flow graphs - Next-use information - A simple code generator - Register		

### **TEXT BOOKS**

1. J.E. Hopcroft, R. Motwani and J.D. Ullman, "Introduction to Automata Theory, Languages and Computations", Second Edition, Pearson Education, 2007.

2. Alfred V. Aho, Monica S.Lam, Ravi Sethi, Jeffrey D.Ullman, "Compilers : Principles,

Techniques and Tools", Second Edition, Pearson Education, 2008.

#### **REFERENCE BOOKS**

1. J.Martin, "Introduction to Languages and the Theory of computation" Third Edition, Tata Mc Graw Hill, 2007

2. Randy Allen, Ken Kennedy, "Optimizing Compilers for Modern Architectures: A Dependencebased Approach", Morgan Kaufmann Publishers, 2002.

- 3. Steven S. Muchnick, "Advanced Compiler Design and Implementation", Morgan Kaufmann Publishers - Elsevier Science, India, Indian Reprint 2003.
- 4. Muneeswaran. K, "Compiler Design", Oxford University Press, 2012.

#### COURSE OUTCOMES

#### Upon completion of the course, students will be able to

CO1	Design a finite automaton for a specific language.
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CO2 Design a Turing machine.

CO3 Select appropriate grammar for the implementation of compiler phases and Design a lexical analyzer and simple parser

CO4 Design and implement techniques used for optimization by a compiler.

CO5 Write a very simple code generator

COs				PR	OGRA		UTCC	MES	(POs	5)				RAM SP OMES (	
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO ۹	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	-	-	2	-	2	2	2	3	3	2
CO2	3	3	3	3	2	-	-	2	-	2	2	2	3	3	2
CO3	3	3	3	3	2	-	-	2	-	2	2	2	3	3	2
CO4	3	3	3	3	2	-	-	2	-	2	2	2	3	3	2
CO5	3	3	3	3	2	-	-	2	-	2	2	2	3	3	2

	IMAGE PROCESSING AND VISION TECHNIQUES	L	T	P	<b>C</b>
<b>OBJECTIVES</b>		3	0	0	3
<ul> <li>To revie</li> </ul>	w image processing techniques for computer vision.				
	he the image enhancement in the Spatial and Frequency Domain.				
	rstand Image Restoration and Image Compression.				
	erstand three-dimensional image analysis.				
	some applications of computer vision algorithms				
UNIT I	IMAGE PROCESSING FOUNDATION				9
Introduction-I	nage Processing Operations– Basic Image filtering operations:	N	oise		
	by Gaussian Smoothing- Median Filters- Mode Filters- Rank Order Filter				
	s in Industrial Applications of VisionThresholding- Adaptive Thresholdir			С	01
	nniques – corner and interest point detection – mathematical morphology	•	•		
	ches to Texture Analysis.				
	-				
UNIT II	IMAGE ENHANCEMENT IN THE SPATIAL AND FREQUENCY DOMA				9
Image enhanc	lement by point processing-Image enhancement by neighbourhood proc	cess	sing-		
Basic Gray Le	vel 20% Transformations-Histogram Processing-Enhancement Using Ar	rithm	netic		
•	rations-Zooming- Basics of Spatial Filters- Smoothening and Sharpening				
• •	ing Spatial Enhancement Methods. Introduction to Fourier Transform			С	02
	main-Smoothing and Sharpening Frequency Domain Filters- Homo				
Filtering			•		
				<u> </u>	
	IMAGE RESTORATION AND IMAGE COMPRESSION				9
		n in	the		9
Model of The	IMAGE RESTORATION AND IMAGE COMPRESSION Image Degradation / Restoration Process-Noise Models- Restoration loise Only Spatial Filtering- Periodic Noise Reduction by Frequency				9
Model of The presence of N	Image Degradation / Restoration Process-Noise Models- Restoration Ioise Only Spatial Filtering- Periodic Noise Reduction by Frequency	Don	nain		9
Model of The presence of N Filtering-Linea	Image Degradation / Restoration Process-Noise Models- Restoration Ioise Only Spatial Filtering- Periodic Noise Reduction by Frequency Position-Invariant DegradationsEstimation of Degradation Function-	Don Inve	nain erse		
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Upon CO1 CO2	comple Implem Unders	tion o nent fu stand t mage	of the Indam he im Resto	ental age e pratior	image nhane n and	u <b>dent</b> e proc	s will cessin	l <b>be a</b> g tech ne Sp	<b>ble to</b> nnique atial a	) es requ	iired fo			on		
<b>Upon</b> CO1 CO2 CO3	comple Implem Unders Apply I	tion o nent fu stand t mage 3D visi	of the Indam he im Resto	ental age e pratior chniqu	image nhano n and ues	udent e proc cemer Image	t <b>s wil</b> cessin nt in the Con	l <b>be a</b> g tech ne Sp npress	ble to nnique atial a sion.	es requ	iired fo			on		
Upon CO1 CO2 CO3 CO4	comple Implem Unders Apply I Apply 3	tion o nent fu stand t mage 3D visi	of the Indam he im Resto	ental age e oratior chniqu ns usi	image nhane n and ues ing co	udent e proc cemer Image	er vis	l <b>be a</b> g tech ne Sp npress	ble to nnique atial a sion. chniqu	es requ and Fre ues.	uired fo	y Dom		ion		
Upon CO1 CO2 CO3 CO4	comple Implem Unders Apply I Apply 3	tion o nent fu stand t mage 3D visi	of the Indam he im Resto	ental age e oratior chniqu ns usi	image nhand n and ues ing co <b>APPI</b>	udent e proc cemer Image ompute	essin tin tin ti e Con er visi	l <b>be a</b> g tech ne Sp npress	ble to nnique atial a sion. chniqu	es requ	uired fo	y Dom	ain.	GRAM SPE		
Upon CO1 CO2 CO3 CO4	comple Implem Unders Apply I Apply 3	tion o nent fu stand t mage 3D visi	of the Indam he im Resto	ental age e oratior chniqu ns usi	image nhand n and ues ing co <b>APPI</b>	udent e proc cemer Image ompute	essin tin tin ti e Con er visi	l be a g tech ne Sp npress ion tec s WIT	ble to nnique atial a sion. chniqu	es requ and Fre ues.	uired fo	y Dom	ain.			
Upon CO1 CO2 CO3 CO4 CO5	comple Implem Unders Apply I Apply 3 Develo	tion o nent fu stand t mage BD visi p appl	f the indam he im Resto on teo licatio	ental age e oratior chniqu ns usi <b>M</b>	image nhand n and ues ng co <b>APPI</b> PROG	udent e proc cemer Image ompute NG O RAM O	er vis <b>F CO</b>	l be a g tech ne Sp npress ion tec s WI1	ble to nnique atial a sion. chniqu Chniqu	es requ and Fre ues.	uired fo equence D PSO	y Dom	ain. PROG OUT	GRAM SPE COMES (PS	SOs)	03
Upon CO1 CO2 CO3 CO4 CO5 COs	Comple Implem Unders Apply I Apply 3 Develo	tion o hent fu itand t mage BD visi p appl	f the indam he im Resto on teo licatio	ental age e oratior chniqu ns usi <b>M</b> PO4	image nhand n and ues ng co <b>APPI</b> PROG	udent e proc cemer Image ompute NG O RAM O	er vis <b>F CO</b>	l be a g tech ne Sp npress ion tec s WI1	ble to nnique atial a sion. chniqu Chniqu	es requ and Fre ues.	uired fo equence D PSO	y Dom s P012	PROC OUT PSO1	GRAM SPE COMES (PS	SOs) PS	O3 }
Upon CO1 CO2 CO3 CO4 CO5 CO5 CO5	Comple Implem Unders Apply I Apply 3 Develo P01 3	tion o hent fu itand t mage BD visi p appl PO2 2	f the indam he im Resto on teo licatio	ental age e oratior chniqu ns usi <b>M</b> PO4 3	image nhand n and ues ng co <b>APPI</b> PROG	udent e proc cemer Image ompute NG O RAM O	er vis <b>F CO</b> <b>UTCON</b>	l be a g tech ne Sp npress ion tec s WI1	ble to nnique atial a sion. chniqu Chniqu	es requ and Fre ues.	uired fo equence D PSO	y Dom s P012 3	PROC OUT PSO1 -	GRAM SPE COMES (PS PSO2 -	SOs) PS	O3 3
Upon CO1 CO3 CO4 CO5 CO5 CO5	Comple Implem Unders Apply I Apply 3 Develo P01 3 -	tion o hent fu itand t mage BD visi p appl PO2 2 3	f the indam he im Resto on teo licatio	ental age e oratior chniqu ns usi <b>M</b> PO4 3 2	image nhand n and ues ng co <b>APPI</b> PROG	udent e proc cemer Image ompute NG O RAM O PO6 -	er vis F CO UTCOM	I be a g tech ne Sp npress ion tec s WIT MES (PC PO8 - -	ble to nnique atial a sion. chniqu ch	es requ and Fre Jes. Ds ANI P010 -	ired fo equence D PSO PO11	y Dom s P012 3 3	PROC OUT PSO1 - 3	GRAM SPE COMES (P PSO2 - -	SOs) PS	O3 3 3

ML1704	MACHINE INTELLIGENCE FOR NETWORK SCIENCES L T	Ρ	С
	3 1	0	3
OBJECTIVES			
• .To ur	nderstand human behaviour in social web and related communities.		
• To le	earn visualization of social networks.		
<ul> <li>Lear</li> </ul>	n to predict human behaviour in social web and related communities		
UNIT I	VISUALIZATION AND APPLICATIONS OF SOCIAL NETWORKS		9
Graph theory	- Centrality - Clustering - Node-Edge Diagrams - Matrix representation	-	
Visualizing	online social networks, Visualizing social networks with matrix-base	,   t	CO1
representatio	ns - Matrix and Node-Link Diagrams - Hybrid representations - Applications		
Cover networ	ks - Community welfare - Collaboration networks - Co-Citation networks.		
UNIT II	EXTRACTION AND MINING COMMUNITIES IN WEB SOCIAL NETWORKS		9
Extracting ev	volution of Web Community from a Series of Web Archive – Detecting	J	
Communities	in Social Networks - Definition of Community - Evaluating Communities	-	
Methods for	Community Detection & amp; Mining - Applications of Community Mining	3   (	CO2
Algorithms -	- Tools for Detecting Communities – Social Network Infrastructure and		002
Communities	- Decentralized Online Social Networks - Multi-Relational Characterization of	f	
Dynamic Soc	al Network Communities		
UNIT III	MACHINE LEARNING FOR GRAPHS - I		9
Machine Lear	ning for Graphs; Traditional Methods for ML in Graphs – Node Level Tasks, Nod	Э	
Level predict	ion, Link level prediction, Graph -level prediction; Node Embeddings. Labe	(	CO3
Propagation f	or Node Classification		
UNIT IV	MACHINE LEARNING FOR GRAPHS – II		9
Graph Neura	I Networks – Model, Design Space; Applications of GNN; Knowledge Grap	۱ (	CO4
Embeddings;	Reasoning over Knowledge Graphs; Subgraph mining with GNNs.		004
UNIT V	GENERATIVE MODELLING AND CASE STUDY		9
Traditional Ge	enerative Models for Graphs ; Deep Generative Models for Graphs; Graph neura	I	
networks in o	computational biology (GNN), Graph Embeddings in fraud detection, Network	3 (	CO5
recommende	d systems, Machine learning and Drug Discovery		
	TOTAL : 45 P	ERIC	ODS
TEXT BOOK	8		
1. Netwo	ork sciences by Albert-Laszlo Barabasi, Cambridge University Press		

3. Networks, Crowds, and Markets: Reasoning About a Highly Connected World by David Easley and Jon Kleinberg, Cambridge University Press (2010)

#### **REFERENCE BOOKS**

- 1. Peter Mika, Social Networks and the Semantic Web, First Edition, Springer 2007.
- 2. Borko Furht, Handbook of Social Network Technologies and Applications, 1st Edition, Springer, 2010

COUR	RSE	OUT	СОМ	ES												
Upon	com	nplet	ion o	f the	cours	se, st	udent	ts will	l be a	ble to	)					
CO1	Use	e sta	tistica	al soft	ware	to vis	ualize	netw	orks	and a	nalyze	their p	oroper	ties, con	necting t	hese to
	net	work	conc	epts a	and th	neorie	s									
CO2	Kno	ow ba	asic n	otatic	n and	d term	inolo	gy use	ed in r	netwo	rk scie	nce				
CO3	Gra	aph	Mach	ine L	.earni	ng us	ses t	he ne	etwork	< stru	icture	of the	unde	erlying d	ata to i	mprove
		•		tcome		0								, 0		
<u> </u>						do no					nd area	nh lou		liation to		
CO4	•			•	•				•		•		•	liction tas	SKS.	
CO5	То	unde	erstan	id hun	nan b	ehavi	our in	socia	l web	and	related	comm	nunities	5		
					Μ	APPI	NG O	F CO	s WI	гн рс	)s AN[	D PSO	s			
COs					PR	OGR/		UTCC	MES	(POs	;)				RAM SP OMES (	
COS		PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1		2	2	2	2	1	1	1	1	1	1	1	1	2	2	2
CO2	2	2	2	2	2	1	1	1	1	1	1	1	1	2	2	2
CO3	3	1	1	2	2	2	1	1	1	1	1	1	1	2	2	2
CO4	1	1	1	2	2	2	1	1	1	1	1	1	1	2	2	2
CO5	5	2	2	2	2	1	1	1	1	1	1	1	1	2	2	2

	NATURAL LANGUAGE PROCESSING LABORATORY	L	T	P	<b>C</b>
OBJECTIVES		0	0	4	2
	explain and apply fundamental algorithms and techniques in the	area	a of	nati	ura
langua	pe processing (NLP)				
	tand language modeling.				
to mani	pulate and analyze language data using Python				
LIST OF EXPE	RIMENTS				
	eneration- generate word forms from root and suffix information		_		
	logy- Understanding the morphology of a word by the use of Add-Delete		le		:01
senten	ns- to calculate bigrams from a given corpus and calculate probability of ce.	а			,UI
	s Smoothing- to apply add-one smoothing on sparse bigram table.				
	agging: Hidden Markov Model- to calculate emission and transition matr	ix wł	nich		
	nelpful for tagging Parts of Speech using Hidden Markov Model. agging: Viterbi Decoding- to find POS tags of words in a sentence using	Vito	rhi	_	
decodir		vite		С	:02
	POS Tagger- to know the importance of context and size of training co	orpus	in	1	
	Parts of Speech			<u> </u>	
8. Chunki tagset.	ng- to understand the concept of chunking and get familiar with the basi	C Chi	unk		
	Chunker- selecting proper features for training a model and size of trai	ining		C	:03
	in learning how to do cunking.				
10. Parsin <u>c</u>	: parsing specific kinds of data, focusing primarily on dates, times, and				
	ΤΟΤΑ	L:0	UPE	RIU	
LIST OF EQU	PMENT FOR A BATCH OF 30 STUDENTS				
Standalone de	sktops with Python 3 Interpreter for Windows/Linux 30 Nos				
PYTHON PAC	KAGES				
	xpected to know/ learn the following Python NLP packages				
	nltk.org/ (http://www.nltk.org/))				
	://spacy.io/ )				
Spacy ( https://www.spacy.com////////////////////////////////////					
<ul><li>Spacy ( https</li><li>TextBlob ( https</li></ul>	p://textblob.readthedocs.io/en/dev/				
<ul> <li>Spacy ( https</li> <li>TextBlob ( ht</li> <li>Gensim (http</li> </ul>	p://textblob.readthedocs.io/en/dev/ s://pypi.python.org/pypi/gensim)				
<ul> <li>Spacy ( https</li> <li>TextBlob ( ht</li> <li>Gensim (http</li> </ul>	p://textblob.readthedocs.io/en/dev/				
<ul> <li>Spacy ( https</li> <li>TextBlob ( ht</li> <li>Gensim (http</li> <li>Pattern (https</li> </ul>	p://textblob.readthedocs.io/en/dev/ s://pypi.python.org/pypi/gensim)				
<ul> <li>Spacy ( https</li> <li>TextBlob ( ht</li> <li>Gensim (http</li> <li>Pattern (https</li> </ul>	p://textblob.readthedocs.io/en/dev/ s://pypi.python.org/pypi/gensim) s://pypi.python.org/pypi/Pattern)				
<ul> <li>Spacy ( https</li> <li>TextBlob ( ht</li> <li>Gensim (http</li> <li>Pattern (https</li> </ul> DATASETS NLTK includes	a small selection of texts from the Project Gutenberg electronic text				
<ul> <li>Spacy ( https</li> <li>TextBlob ( htt</li> <li>Gensim (http</li> <li>Pattern (https</li> </ul> DATASETS NLTK includes archive, which	a small selection of texts from the Project Gutenberg electronic text contains some 25,000 free electronic books, hosted at				
<ul> <li>Spacy ( https:</li> <li>TextBlob ( http://www.gute</li> <li>Gensim (http://www.gute</li> </ul>	a small selection of texts from the Project Gutenberg electronic text contains some 25,000 free electronic books, hosted at enberg.org/.				
<ul> <li>Spacy (https:</li> <li>TextBlob (http://www.gute</li> <li>Gensim (http://www.gute</li> <li>DATASETS</li> <li>NLTK includes</li> <li>archive, which</li> <li>http://www.gute</li> <li>2. The Brown (http://www.gute</li> </ul>	<ul> <li>a small selection of texts from the Project Gutenberg electronic text contains some 25,000 free electronic books, hosted at enberg.org/.</li> <li>Corpus contains text from 500 sources, and the sources have been</li> </ul>		bter		
<ul> <li>Spacy ( https:</li> <li>TextBlob ( http://www.gute</li> <li>Pattern (https://www.gute</li> <li>2. The Brown ( categorized by</li> </ul>	<ul> <li>a small selection of texts from the Project Gutenberg electronic text contains some 25,000 free electronic books, hosted at enberg.org/.</li> <li>Corpus contains text from 500 sources, and the sources have been genre, such as news, editorial, and so on (http://icame.uib.no/brown/bc</li> </ul>	mlos	html	).	
<ul> <li>Spacy (https:</li> <li>TextBlob (http://www.gute</li> <li>Gensim (http://www.gute</li> <li>DATASETS</li> <li>NLTK includes</li> <li>archive, which</li> <li>http://www.gute</li> <li>2. The Brown (http://www.gute</li> </ul>	<ul> <li>a small selection of texts from the Project Gutenberg electronic text contains some 25,000 free electronic books, hosted at enberg.org/.</li> <li>Corpus contains text from 500 sources, and the sources have been genre, such as news, editorial, and so on (http://icame.uib.no/brown/bc</li> </ul>	mlos	html	).	

COURSE OUTCOMES

Upon completion of the course, students will be able to

CO1 Tag a given text with basic language features.

CO2 To implement a rule based system to tackle morphology/syntax of a language

CO3 To design a tag set to be used for statistical processing for real-time applications

				Μ	APPI	NG O	F CO	s WI1	ГН РС	)s AN[	D PSO	s				
60-		PROGRAM OUTCOMES (POs) PROG OUTC														
COs	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3	
CO1	3	3	3	3	2	2	1	1	2	2	2	3	3	3	3	
CO2	3	3	3	3	2	2	1	1	2	2	2	3	3	3	3	
CO3	3	3	3	3	3	2	1	1	2	2	2	3	3	3	3	

ML1708

### **CAPSTONE PROJECT- PHASE I**

L P T C 0 0 4 2

The purpose of this course is to apply the concept of Mathematics, Science and Engineering Fundamentals and an Engineering Specialization to solve complex engineering Problem.

COs				PRC	DGRA		UTCC	OMES	(PO:	s)			S	ROGRA PECIFI UCOME	C
	Р 01	P 02	P 03	P 04	Р 05	Р 06	P 07	P 08	Р 09	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
CO2	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
CO3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3

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The purp Fundar													l Engine ng Prob			
				N	IAPPI	NG C	F CO	s WI	ГН РС	)s AN[	D PSO	s				
COs				PR	OGR		UTCO	MES	(POs	)				BRAM DUCO		SIFI
	РО 1	PO 2	PO 3	РО 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	P	SO3
CO1	3	3	3	3	3	3	3	3	3	3	3	3	3	3		3
CO2	3	3	3	3	3	3	3	3	3	3	3	3	3	3		3
		1		1		1	1	1	1		1					

# PROFESSIONAL ELECTIVE – I (SEMESTER V)

ML1511	ADVANCED DATABASES		-	T	<b>C</b>
OBJECTIVE		3	0	0	3
• To ex	plore the features of Parallel and Distributed databases				
	miliar with a commercial relational database system (Oracle) by writing	SQ	Lus	sing	I
the sy				0	
-	ovide knowledge about XML Databases				
	ow about Temporal and Spatial Databases				
	miliar with the relational database theory, and be able to write relationa	al alo	iebr	а	
	ssions for queries				
	PARALLEL AND DISTRIBUTEDDATABASES :				8
	ystem Architectures: Centralized and Client-Server Architectures-	-Ser	ver		
-	itectures –Parallel Systems Distributed Systems –Parallel Database				
•	Interquery Parallelism - Intraquery Parallelism – Intraoperation Para				
	n Parallelism –Distributed Databases: -Homogeneous and Heteroge			C	01
	Distributed Data Storage –Distributed Transactions –Commit Protoc				
	Control in Distributed Databases –Distributed Query Processing.				
	OBJECTAND OBJECT RELATIONAL DATABASES				8
Object-Based	Databases: Complex Data Types–Structured Types and Inheritance ir	n SC	)L		
	tance –Arra y and Multiset Types in SQL –Object Identity and Reference				
	_ –Implementing O-R Features – Persistent Programming Languages -			C	02
	ted versus Object –Relational.				
	ANALYTICAL MODELING OF PARALLEL PROGRAMS				8
XML: Motiva	tion –Structure of XML Data –XML Document Schema –Queryin	ng a	and		
	on – Appl ication Program Interfaces to XML –Storage of XML Data	U			03
Applications.					
UNIT IV	SPATIAL AND TEMPORAL DATABASES				8
Spatial and T	 emporal Data and Mobility: Time in Databases –Spatial and Geographi	ic Da	ata		
Mobility a nd	Personal Databases.			C	04
UNIT V	MULTIMEDIA DATABASES				8
Multidimensio	⊥ onal Data Structures: k-d Trees – Point Quadtrees – MXQuadtree – R-T	Гree	-		
	ases: Representing Image DBs with Relations –Representing Image DI			С	05
R-Trees –Tex	kt/Document Databases: TV Trees - Video Databases – Audi o Databas	ses.			
	TOTAL :	45	PFF		20
	IOTAL .	+J			

#### **REFERENCE BOOKS**

- Abraham Silberschatz, Henry F. Korth, S. Sudarshan, "Database System Concepts", McGraw-Hill International Edition, Sixth Edition, 2011.
- V. S. Subramanian, "Principles of Multimedia Database Systems", Elsevier Publishers, 2001
- 3. R. Elmasri, S. B. Navathe, "Fundamentals of Database Systems", Pearson Education, Seventh Edition, 2016.

#### COURSE OUTCOMES

Upon completion of the course, students will be able to

- CO1 Understand Parallel Databases and Distributed Databases
- CO2 Apply query evaluation techniques and query optimization techniques
- CO3 Develop transaction processing systems with concurrency control.
- CO4 Understand Temporal and Spatial Databases

CO5 Design and develop a database application system as part of a team

COs				PRC	OGRA	M O	UTCC	OMES	6 (PO:	s)			S	ROGRA SPECIFI UCOME	С
	Р 01	Р 02	Р 03	Р 04	Р 05	Р 06	Р 07	Р 08	Р 09	PO 10	РО 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	2	2	2	2	1	-	-	-	-	1	1	1	2	2	2
CO2	2	2	2	2	1	-	-	-	-	1	1	1	2	2	2
CO3	2	2	2	2	1	-	-	-	-	1	1	1	2	2	2
CO4	2	2	2	2	1	-	-	-	-	1	1	1	2	2	2
CO5	2	2	2	2	1	-	-	-	-	1	1	1	2	2	2

		PC
OBJECTIVE		03
OBJECTIVE	<ol> <li>To understand the concepts of Semantic Web</li> <li>To build and implement a small ontology that is semantically descriptive your chosen problem domain</li> <li>To implement applications that can access, use and manipulate the ontology, represent data from a chosen problem in XML with appropria semantic tags</li> <li>To design and implement a web services application that "discovers" the data and/or other web services via the semantic web</li> <li>To discover the capabilities and limitations of semantic web technology different applications</li> </ol>	te he
UNIT I	Foundation of Semantic Web Technologies	9
visual and sy semantic web	to the Syntactic web and Semantic Web – Evolution of the Web – The vntactic web – Levels of Semantics – Metadata for web information - The b architecture and technologies –Contrasting Semantic with Conventional s –Semantic Modeling -Potential of semantic web solutions and challenges	<b>CO</b> 1
	ONTOLOGICAL ENGINEERING	9
aspects: cond Sub-propertie resources for Multilingual C	Taxonomies –Topic Maps – Classifying Ontologies - Terminological cepts, terms, relations between them – Complex Objects -Subclasses and es definitions –Upper Ontologies – Quality – Uses - Types of terminological ontology building – Methods and methodologies for building ontologies – Ontologies -Ontology Development process and Life cycle – Methods for arning – Ontology Evolution – Versioning	CO2
	STRUCTURING AND DESCRIBING WEB RESOURCES	9
Structured W Querying – P Vocabulary –	eb Documents - XML – Structuring – Namespaces – Addressing – rocessing - RDF – RDF Data Model – Serialization Formats- RDF Inferencing -RDFS – basic Idea – Classes – Properties- Utility Properties – ling for Combinations and Patterns- Transitivity	COS
UNIT IV	WEB ONTOLOGY LANGUAGE	9
Domain and I	anguages – Basic Notions -Classes- Defining and Using Properties – Range – Describing Properties - Data Types – Counting and Sets- perty Assertions – Advanced Class Description – Equivalence – Owl Logic.	CO4
UNIT V	SEMANTIC WEB TOOLS AND APPLICATIONS	9
Development	Tools for Semantic Web – Jena Framework – SPARL –Querying	COS

TEX	Т ВО	OK	5													
				Deve	loper	's Gu	ide to	o the	Sema	antic	Web.	Sprinc	er: 1s	t Editior	. Editior	1.2011
	•	•			•										antic W	
					ey; 1 e									,		
3.		-	•		•					omar	tic M/	ah Drii	mar S	econd E	dition	
5.	•										MIT Pr					
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REF	EREI	NCE	BOO	OKS												
1.	Robe	ert N	1. Co	lomb,	Onto	ology	and t	the S	emar	ntic W	/eb: V	olume	156 F	rontiers	in Artifi	cial
	Intel	ligen	ice ai	nd Ap	oplica	tions	(Fror	ntier i	n Arti	ficial	Intellio	gence	and A	pplicatio	ons), IO	S
	Pres	•		1	•		·					-			,, -	
2.				na an	d.lan	nes H	lendlø	er Se	eman	tic W	eb for	the W	orking	n Ontolo	gist: Effe	ective
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COU	IRSE					, vvc,		yan r	Caufm	iann;	2 edit	ion, 20	J11.			
	JRSE n cor	OU	TCO etion	MES of th	e col	urse,	stud	lents	will	be ab	ole to					
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Upo ( (	n cor 201 202	Dis	TCO etion scuss	MES of th abou	e cou ut bas S and	u <b>rse,</b> sic of l its p	stud sema	lents antic v	will	be ab	ole to					
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ML1513	ADVANCED DATA STRUCTURES L P	Т	C
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OBJECTIVES			
To under	rstand the usage of algorithms in computing.		
To learn	and use hierarchical data structures and its operations		
To learn	the usage of graphs and its applications.		
To select	at and design data structures and algorithms that is appropriate for problem	IS.	
To study	about NP Completeness of problems.		
UNIT I	ROLE OF ALGORITHMS IN COMPUTING		
Algorithms – A	Algorithms as a Technology- Insertion Sort – Analyzing Algorithms	-	
Designing Algor	rithms- Growth of Functions: Asymptotic Notation - Standard Notation	5	со
and Common F	Functions- Recurrences: The Substitution Method – The Recursion-Tree	;	1
Method			
UNIT II	HIERARCHICAL DATA STRUCTURES		
	Trace: Region Querying a Rinery search tree Insertion and Polation		
Binary Search 1	Trees: Basics – Querying a Binary search tree – Insertion and Deletion	-	
-		-	
Red-Black trees	s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B	-	co
Red-Black trees Trees: Definition	s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree	-	CC 2
Red-Black trees Trees: Definition Fibonacci Heap	s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree no: structure – Mergeable-heap operations- Decreasing a key and deleting	-	
Red-Black trees Trees: Definition Fibonacci Heap a node-Boundin	s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree os: structure – Mergeable-heap operations- Decreasing a key and deleting ng the maximum degree.	-	
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Red-Black trees Trees: Definition Fibonacci Heap a node-Boundin <b>UNIT III</b> Elementary Gra Depth-First Sea	s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree os: structure – Mergeable-heap operations- Decreasing a key and deleting ing the maximum degree. GRAPHS aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum	- J -	2
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees	<ul> <li>Bis: Properties of Red-Black Trees – Rotations – Insertion – Deletion - Bis operations on B-Trees – Deleting a key from a B-Trees is: structure – Mergeable-heap operations- Decreasing a key and deleting the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum s: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source</li> </ul>	-       	2
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths:	<ul> <li>Bis: Properties of Red-Black Trees – Rotations – Insertion – Deletion - Bis: operations on B-Trees – Deleting a key from a B-Trees is: structure – Mergeable-heap operations- Decreasing a key and deleting the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum is: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed</li> </ul>	-       	2
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs	<ul> <li>Bis: Properties of Red-Black Trees – Rotations – Insertion – Deletion - Bis of Btrees – Basic operations on B-Trees – Deleting a key from a B-Trees is: structure – Mergeable-heap operations- Decreasing a key and deleting of the maximum degree.</li> <li><b>GRAPHS</b></li> <li>Baph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum is: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matrix</li> </ul>	-       	2  CO
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication –	<ul> <li>s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree os: structure – Mergeable-heap operations- Decreasing a key and deleting ing the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum s: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri The FloydWarshall Algorithm;</li> </ul>	-       	2  CO 
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Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication – UNIT IV Dynamic Progra – Longest Com	<ul> <li>Bis: Properties of Red-Black Trees – Rotations – Insertion – Deletion - Bis of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree of Btrees – Mergeable-heap operations- Decreasing a key and deleting the maximum degree.</li> <li><b>GRAPHS</b></li> <li>Baph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum S: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri The FloydWarshall Algorithm;</li> <li><b>ALGORITHM DESIGN TECHNIQUES</b></li> <li>amming: Matrix-Chain Multiplication – Elements of Dynamic Programming mon Subsequence- Greedy Algorithms: An Activity-Selection Problem - Matrix Chain Multiplication - Elements of Dynamic Programming - Matrix-Chain Multiplication - Elements of Dynamic Programming - Matrix-Chain Multiplication - Elements of Dynamic Programming - Matrix-Chain Problem - Matrix - Matr</li></ul>	- - ) - ) - ) - ) - ) - ) - ) - ) - ) -	2 ? ?
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication – UNIT IV Dynamic Progra – Longest Com Elements of the	<ul> <li>s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree s: structure – Mergeable-heap operations- Decreasing a key and deleting of the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum s: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri The FloydWarshall Algorithm;</li> <li><b>ALGORITHM DESIGN TECHNIQUES</b></li> <li>amming: Matrix-Chain Multiplication – Elements of Dynamic Programming mon Subsequence- Greedy Algorithms: An Activity-Selection Problem – Greedy Strategy- Huffman Codes.</li> </ul>	- - ) - ) - ) - ) - ) - ) - ) - ) - ) -	2 CO 3 CO 4
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication – UNIT IV Dynamic Progra – Longest Com Elements of the UNIT V	<ul> <li>s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree as: structure – Mergeable-heap operations- Decreasing a key and deleting ing the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum s: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri The FloydWarshall Algorithm;</li> <li><b>ALGORITHM DESIGN TECHNIQUES</b> amming: Matrix-Chain Multiplication – Elements of Dynamic Programming mon Subsequence- Greedy Algorithms: An Activity-Selection Problem – Greedy Strategy- Huffman Codes.</li> <li><b>NP COMPLETE AND NP HARD</b></li> </ul>		2  CO CO
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication – UNIT IV Dynamic Progra – Longest Com Elements of the UNIT V NP-Completene	<ul> <li>Bis: Properties of Red-Black Trees – Rotations – Insertion – Deletion -Bit no f Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree is: structure – Mergeable-heap operations- Decreasing a key and deleting ing the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – Topological Sort – Strongly Connected Components- Minimum is: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri. The FloydWarshall Algorithm;</li> <li><b>ALGORITHM DESIGN TECHNIQUES</b></li> <li>amming: Matrix-Chain Multiplication – Elements of Dynamic Programming mon Subsequence- Greedy Algorithms: An Activity-Selection Problem - Greedy Strategy- Huffman Codes.</li> <li><b>NP COMPLETE AND NP HARD</b></li> <li>ass: Polynomial Time – Polynomial-Time Verification – NP- Completenes</li> </ul>		2 CO 3 CO 4
Red-Black trees Trees: Definition Fibonacci Heaps a node-Boundin UNIT III Elementary Gra Depth-First Sea Spanning Trees Shortest Paths: Acyclic Graphs Multiplication – UNIT IV Dynamic Progra – Longest Com Elements of the UNIT V NP-Completene	<ul> <li>s: Properties of Red-Black Trees – Rotations – Insertion – Deletion -B n of Btrees – Basic operations on B-Trees – Deleting a key from a B-Tree as: structure – Mergeable-heap operations- Decreasing a key and deleting ing the maximum degree.</li> <li><b>GRAPHS</b></li> <li>aph Algorithms: Representations of Graphs – Breadth-First Search – arch – Topological Sort – Strongly Connected Components- Minimum s: Growing a Minimum Spanning Tree – Kruskal and Prim- Single-Source The Bellman-Ford algorithm – Single-Source Shortest paths in Directed – Dijkstra's Algorithm; All-Pairs Shortest Paths: Shortest Paths and Matri The FloydWarshall Algorithm;</li> <li><b>ALGORITHM DESIGN TECHNIQUES</b> amming: Matrix-Chain Multiplication – Elements of Dynamic Programming mon Subsequence- Greedy Algorithms: An Activity-Selection Problem – Greedy Strategy- Huffman Codes.</li> <li><b>NP COMPLETE AND NP HARD</b></li> </ul>		2 CC 3 CC 4

# TEXT BOOKS

- 1. Alfred V. Aho, John E. Hopcroft, Jeffrey D. Ullman, —Data Structures and Algorithmsll, Pearson Education, Reprint 2006.
- 2. Robert Sedgewick and Kevin Wayne, —ALGORITHMSI, Fourth Edition, Pearson Education.
- 3. S.Sridhar, IIDesign and Analysis of AlgorithmsII, First Edition, Oxford University Press. 2014
- 4. Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, Clifford Stein, —Introduction to Algorithmsll, Third Edition, Prentice-Hall, 2011.

#### **REFERENCE BOOKS**

### **COURSE OUTCOMES**

Upon completion of the course, students will be able to

CO1	Upon t	he co	mple	tion c	of the	cour	se the	e stuc	lents	shoul	d be a	ble to:			
CO2	Design	data	struc	ctures	and	algoi	rithms	s to s	olve d	compu	iting p	roblem	าร		
CO3	Design	algo	rithm	s usir	ng gra	aph s	tructu	ire ar	nd vai	rious s	string r	natchi	ng algo	rithms to	o solve
	real-life	e prot	olems	;											
CO4	Apply s	suitab	le de	sign	strate	egy fo	or prol	blem	solvir	ng					
CO5	Unders	stand	the a	pplic	ations	s of N	IP Co	mple	te an	d NP	Hard	Conce	epts		
				МА			00	. WIT			D PSC	)6			
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			F	ROG	RAN		тсои	MES	POs	<b>`</b>				ROGRA SPECIFI	
COs			•						(. 00	,			-	UCOME	-
	PO1	PO	PO	PO	PO	PO	PO	PO	PO	PO1	P01	P01	PSO	PSO	PSO
		2	3	4	5	6	7	8	9	0	1	2	1	2	3
CO1	2	2	2	2	2	-	-	-	-	2	2	2	3	3	3
CO2	3	3	3	3	2	-	-	-	-	2	2	2	3	3	3
CO3	3	3	3	3	2	-	-	-	-	2	2	2	3	3	3
CO4	2	2	3	3	2	-	-	-	-	2	2	2	3	3	3
CO5	2	2	2	2	2	-	-	-	-	2	2	2	3	3	3

ML1514	LOGIC PROGRAMMING	L	Τ		С
OBJECTIVE	 S	3	0	0	3
	npart knowledge on				
	learn the basics and advanced concepts of Prolog				
	explain the basic concepts of knowledge representation				
	o explain the fundamentals of expert systems and knowledge repr	ese	ntat	ion	with
	rtainty				
	represent a problem using constraint and inductive logic programming.				
	understand the relation between prolog, modal and temporal logic.				
UNIT I	THE PROLOG LANGUAGE			ç	)
Introduction	to Prolog : Defining Relations - facts - rules - Recursive Rules - Syn	tax	and		
Meaning of	Prolog Programs - Data Objects - Matching - Declarative meaning of	f Pr	olog		
programs –	Procedural Meaning - Example - Order of clauses and goals - F	Rela	atior	1	CO1
between Pro	olog and logic - Lists – Operators - Arithmetic – Using Structures: Eight	t Qu	leer	1	
Problems					
UNIT II	PROGRAMMING STYLE AND TECHNIQUE			ç	)
	Dutput: Communication with files – Processing files of terms – Mani				
characters	- Constructing and decomposing atoms - Reading programs -	Bu	ilt-ir	1	
	Terms - Testing – Constructing and decomposing – Equality and compa				CO2
	anipulation – control facilities - Operations on Data Structures: Sorting			-	002
•	g sets by binary trees – Binary Dictionary - Insertion and deletion– Dis	spla	ying		
trees - Grap					
UNIT III	PROLOG IN ARTIFICIAL INTELLIGENCE			_	9
	em-Solving Strategies: Depth first search – Breadth first search – Ana				
	n techniques - Best First Heuristic Search –Best first search – Eight P				CO3
•	<ul> <li>Space saving techniques for best first search- Problem Decomposit</li> </ul>	ion	and		
AND/OR Gr					
	CONSTRAINT AND INDUCTIVE LOGIC PROGRAMMING				)
Constraint s	satisfaction and logic programming – CLP - real numbers – Schedu	ling	j— A	۱	
	programs-finite domains - Knowledge Representation and Expert Sys				~~ ^
	structure: expert system -if then rules -Rule based system - Forwa				CO4
	naining - An Expert System Shell- Knowledge representation format -De	esig	nıng		
	e engine – Inductive Logic Programming				<u> </u>
	MODAL AND TEMPORAL LOGIC				)
	- Basic Concepts - Relational Structures - Modal Languages - Mod				
	General Frames – Modal Consequence Relations – Normal Modal L				CO5
	ogic – Basic concepts and notion of logics-Logical Languages – Sema			-	
	em - Creating AI Characters for Fighting Games Using GeneticProgramn	ning	)		
TOTAL : 45					
TEXT BOOI			<u></u>		
	Bratko, "PROLOG Programming for Artificial Intelligence", Addison -W	esi	ey,	Pea	arso
	cation, Third Edition, 2001	ri d a			o ro ;+
	atrick Blackburn, Maarten de Rijke, Yde Venema, "Modal Logic ",Cambi o 2001	nag	e u	niv	ersit
Pies	s 2001				
REFERENC	EBOOKS				
	Kroger, Stephen Merz, "Temporal Logic and State Systems", Springer 20				
		JUQ			
	nonenko and N. Lavrac,"Prolog Through Examples", Sigma press,1989	۰ ۱۸	lilou	o	S
	lilsson and Jan Maluszynski,"Logic Programming and Prolog(2ED)", Joh	11 V	ney	à	SOU
Ltd,2			<b>h</b> "	<b>D</b>	
	rt Russell and Peter Norvig, "Artificial Intelligence A Modern Appro	Jac	Π,	rea	arsol
Educ	cation, Third Edition,2010		<b>-</b>		
Educ 5. Anto	ation, Third Edition,2010 ni Niederlinski," A Quick and Gentle Guide to Constraint Logic Pr se",Gliwice 2011	ogr	amr	ning	g vi

- Svorenova, M; Cerna, I.; Belta, C, "Optimal Temporal Logic Control for Deterministic Transition Systems With Probabilistic Penalties", IEEETrans. Autom. Control, vol. 60, issue: 6, pp.1528 -1541 ,2015
- 7. Giovanna Martinez-Arellano, Richard Cant and David Woods, "Creating AI Characters for Fighting Games Using Genetic Programming", IEEE Transactions on Computational Intelligence and AI in Games, vol. 9, No. 4,pp.423-434, 2017.

### **COURSE OUTCOMES**

Upon completion of the course, students will be able to

CO1 Develop prolog programs for simple application

CO2 Implement control structures in Prolog programs

CO3 Use Prolog for problem solving in artificial intelligence

CO4 Implement the expert systems satisfying various constraints

CO5 Develop simple applications using modal and temporal logic

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COs				PRC	DGRA		JTCC	MES	(POs	5)				GRAM S COMES	PECIFIC (PSOs)
COS	P 01	Р 02	P 03	Р 04	Р 05	Р 06	Р 07	P 08	Р 09	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO3
CO1	1	1	1	1	1	1	1	2	1	1	1	2	2	2	2
CO2	2	2	1	2	2	1	1	2	1	1	1	2	2	2	2
CO3	2	2	2	2	2	`1	1	2	1	1	1	2	2	2	2
CO4	2	2	2	2	2	1	1	2	1	1	1	2	2	2	2
CO5	2	2	2	2	2	1	1	2	1	1	1	2	2	2	2

ML1515	APPLICATION OF MACHINE LEARNING IN INDUSTRIES	L	Т	Ρ	
		3	0	0	3
OBJECTIVE	5				
•	Understand the concept of Machine Learning.				
•	Familiarize with applications of Machine Learning in Banking	sect	ors		
•	Appreciate the various applications in Communication				ntior
·	sectors.	anu	Lu	ucc	
•	Identify the applications in Health care and Government sector	ors			
•	Recognize the applications in Manufacturing, Transportation		dТ	oais	stics
	sectors.	i an	<b>~</b> _	egi	
UNIT I	MACHINES LEARNING IN BANKING AND SECURITIES			9	
Why machin	e learning in banking sector, Use of AI in banking and finance	ə, Fr	aud		
	bugh competition in banking industry, Risk modelling and inv				
banks, Custo	omer data management, Decreased customer experience and	loya	alty,		
	marketing, Role of machine learning: Challenges of banking				
	s, Widely used machine learning algorithms in banking and				
	ntion and detection systems, Rule based and machine learning				
	fraud detection, Anomaly detection: Ways to expose su				
	in banks, Advanced fraud detection systems, Risk mana				
	ase study: Application of machine learning for financ				:01
	, Credit risk analysis using machine learning classifier, Inv				
	ystems, Portfolio management systems, Objectives of				
	, Algorithmic trading, Deep learning for customer services, ( g approach, Al powered marketing systems, Deep learning i				
security Tyr	es of cyber-attacks in banks, Deep learning methods used i	in cy	/Dei /har		
	ep learning v/s restricted Boltzmann machines, Convolution				
	NNs), Recurrent neural networks, Machine learning technique				
	& sentiment/news analysis, Sentiment or news analysis,				
	nd opportunities: Banking and security domain.				
UNIT II		MED	DIA,	9	
	HEALTHCARE AND LIFE SCIENCE				
	ming in communication, media and entertainment, Usage of r				
Ų	nedia and entertainment industry, Machine learning technic	•			
	ntiment analysis, World embedding's, Sentiment analysis w				
	nemory networks, Real-time analytics in communication, me				
	t industries, Real time analytics and social media, Deep lear				
	analytics, Recommendations engines, Collaborative filtering,				
	orative filtering, Model based collaborative filtering, Conten rid recommendation systems, Summary of recommendation s				
	ng techniques on recommender systems. Applications of r				
	ealth and life sciences, The most important applications of r				:02
	ealthcare, Role of machine learning in drug discovery, Medica				
	y deep learning for medical image analysis, Neural network a				
	itecture, Comparisons between architecture of different types				
	dels, Machine learning in genetics and genomics, Genomics				
learning arch					
learning arch learning mod	I wo category of genomics. How to use deep learning eff				
learning arch learning mod background,	Two category of genomics, How to use deep learning eff deep learning models, Predictive medicine: Prognosis and dia	gnos			
learning arch learning mod background, Interpreting d		•	ncer		
learning arch learning mod background, Interpreting d	deep learning models, Predictive medicine: Prognosis and dia redictive medicine: Examples, ML applications in breast	•	ncer		
learning arch learning mod background, Interpreting of accuracy, P	deep learning models, Predictive medicine: Prognosis and dia redictive medicine: Examples, ML applications in breast d prognosis. MACHINE LEARNING IN EDUCATION, MANUFACTURIN	car			
learning arch learning mod background, Interpreting of accuracy, P diagnosis an UNIT III	deep learning models, Predictive medicine: Prognosis and diagredictive medicine: Examples, ML applications in breast d prognosis. MACHINE LEARNING IN EDUCATION, MANUFACTURIN PETROLEUM INDUSTRIES	car GA	ND	9	
learning arch learning mod background, Interpreting of accuracy, P diagnosis an UNIT III Advantages	deep learning models, Predictive medicine: Prognosis and dia redictive medicine: Examples, ML applications in breast d prognosis. MACHINE LEARNING IN EDUCATION, MANUFACTURIN	Car GA	ND emic	9	:03

What? Stakeholders: Who? Methods: How? Case study: Sentimental analysis for student's feedback using ML, Recommender systems in education, Domain model, Learner model, Students classification algorithm, Recommendation model, Case study: Application of ML in predicting students' performance, Proposed methodology, Data description, Sample data sets, Visualization, Selection of machine learning technique. Introduction, Applications of machine learning in manufacturing industry, Deep learning for smart manufacturing, Machine learning for quality control in manufacturing, Case study, Construction of CNN, Experimental results, Efficiency of CNN for defect detection, Comparative experiments, Machine learning for fault assessment, Time frequency methods, Spectrograms: Short-Time Fourier Transform (STFT), Scalograms: Wavelet transform, Hilbert-Huang transform, Proposed CNN architecture for fault classification based on vibration signals, Case study 1, Machinery failure prevention technology.WINT IVMACHINE LEARNING IN GOVERNMENT ADMINISTRATION AND UNIT IV	9
INSURANCE INDUSTRIESIntroduction, Risk and compliance, Type of government problems appropriate for Al applications, AI for citizen services use cases, Answering questions, Routing requests, Translation, Drafting documents, Chat bots for communication between citizen and government, Media richness theory, Chatbots in the public sector, Case study, Data management services, Knowledge processing services, Application services, An application scenario, Classifications of citizen complaints using ML, Case study, Step 1: Document collection, Step 2: Prepossessing, Step 3: Feature extraction, Term frequency- Inverse document frequency, Step 4: Feature selection, Step 5: Classification, How to implement, Result. Importance of machine learning in insurance, Potential use cases of machine learning in insurance industry, Case study on insurance climb analysis using machine learning algorithms, Case study on using machine learning for insurance pricing optimization, Personalized marketing in insurance industry, Predictive model for insurance underwriting, Case study: Risk prediction in life insurance industryUNIT VMACHINEMACHINELEARNINGINRETAILANDSUPPLYCHAIN,	CO4
TRANSPORTATION AND LOGISTICS, ENERGY AND UTILITIES           Introduction, Inventory management, Few use case examples, Benefits of predictive analytics to retailers, Robots-seeing to customer satisfaction, IoT: Prevention first, Predictive analytics: Weathering demand, Analysing buying patterns, Analysing traffic patterns, Assortment planning, Eliminate guess work, Feed the right stores, Get better information, Assortment planning to drive supply chain, Retail analytics, Domestic forecasting, Case study: Forecasting seasonal footwear demand using ML, Demand forecasting methods, Predictor variables in demand forecasting, Traditional techniques v/s machine learning techniques, Methodology, Machine learning techniques used, List of attributes from the aggregated data by month at the style level, Feature selection and engineering, List of attributes for feature selection, Dataset partitioning, Model building, Three step model, K-means clustering, Three steps followed in classification, Three sub-steps in prediction, Performance measurement, Results, Three step model, Machine learning models, Machine learning models use case. Introduction, Applications of ML and artificial intelligence in transportation, Applications of machine learning in transport, Incident detection, Predictive models, Application of Al in aviation and public transportation, Aviation, Shared mobility, Buses, Intelligence use cases in logistics, Back office AI, Cognitive customs, Predictive logistics, Predictive risk management, Seeing thinking and speaking logistics operations, ML powered customer experience, Limitations of AI techniques in transportation, Computation complexity of AI algorithms. Introduction, Smart grid, Smart grid technologies, Key characteristics of smart grid, Machine learning applications in smart grid, Machine learning techniques for renewable energy generation, Forecasting	CO5

# **TEXT BOOKS**

Data Mining & Predictive Modeling (IBM ICE Publications).

# COURSE OUTCOMES

Upon completion of the course, students will be able to

CO1	Understand the concept of Machine Learning.
CO2	Familiarize with applications of Machine Learning in Banking sectors.
CO3	Appreciate the various applications in Communication and Education sectors.
CO4	Identify the applications in Health care and Government sectors .
0.05	Recognize the applications in Manufacturing, Transportation and Logistics
CO5	sectors.

													-				
				PRO	GRA	MO	UTC	OME	S (PC	Ds)			PROGRAM SPECIFIC OUTCOMES (PSOs)				
COs	P 0 1	P 0 2	P 0 3	P 0 4	P 0 5	P 0 6	P 0 7	P 0 8	P 0 9	РО 10	РО 11	PO 12	PSO 1	PSO 2	PSO3		
CO1	1	1	1	1	1	1	1	2	1	1	1	2	2	2	2		
CO2	2	2	1	2	2	1	1	2	1	1	1	2	2	2	2		
CO3	2	2	2	2	2	`1	1	2	1	1	1	2	2	2	2		
CO4	2	2	2	2	2	1	1	2	1	1	1	2	2	2	2		
CO5	2	2	2	2	2	1	1	2	1	1	1	2	2	2	2		

# PROFESSIONAL ELECTIVE – II (SEMESTER VI)

ML1611	GREEN COMPUTING	L	P	T	C
OBJECTIVES		3	0	0	3
To acquire	knowledge to adopt green computing practices to minimize negative i	impa	acts	on	the
environmen	t, skill in energy saving practices in their use of hardware, examine techn	olog	y too	ols 1	that
can reduce	paper waste and carbon footprint by user, and to understand how to minir	nize	equ	ipm	ent
disposal req	uirements				
UNIT I	FUNDAMENTALS				9
Green IT Fund	damentals: Business, IT, and the Environment – Green computing: carbor	n foc	ot		<u> </u>
print, scoop	on power - Green IT Strategies: Drivers, Dimensions, and G	Goal	s –		
Environmental	lly				:01
Responsible E	Business: Policies, Practices, and Metrics.				
UNIT II	GREEN ASSETS AND MODELING				9
Green Assets	: Buildings, Data Centers, Networks, and Devices – Green Business	Pro	cess		
Management:	Modeling, Optimization, and Collaboration - Green Enterprise Architectur	re –			02
Environmenta	I Intelligence – Green Supply Chains – Green Information Systems: Desig	in ai	nd		02
Development	Models.				
UNIT III	GRID FRAMEWORK				9
Virtualizing of	IT systems - Role of electric utilities, Telecommuting, teleconference	ing	and		1
teleporting – N	Aterials recycling – Best ways for Green PC – Green Data center – Gree	n G	rid	С	03
framework.					
UNIT IV	GREEN COMPLIANCE				9
Socio-cultural	aspects of Green IT - Green Enterprise Transformation Roadmap -	- G	reen		
Compliance: F	Protocols, Standards, and Audits – Emergent Carbon Issues: Technologie	s ar	nd	С	04
Future.					
UNIT V	CASE STUDIES				9
The Environm	ientally Responsible Business Strategies (ERBS) – Case Study Scena	arios	s for		1
Trial Runs –	Case Studies - Applying Green IT Strategies and Applications to a	Hc	ome,	С	05
Hospital, Pack	aging Industry and Telecom Sector.				
	TOTAL	: 4	5 PE	RIC	DS
TEXT BOOKS	8				
1. Bhu	ivan Unhelkar, "Green IT Strategies and Applications-Using Environment	al Ir	ntellig	jen	ce",
CR	C Press, June 2011				
2. Wo	ody Leonhard, Katherrine Murray, "Green Home computing for dummies",	, Au	gust	200	)9.

# **REFERENCE BOOKS**

CO3

CO4

CO5

1. Alin Gales, Michael Schaefer, Mike Ebbers, "Green Data Center: steps for the Journey", Shoff/IBM rebook, 2011.

2. John Lamb, "The Greening of IT", Pearson Education, 2009.

3. Jason Harris, "Green Computing and Green IT- Best Practices on regulations & industry", Lulu.com, 2008.

4. Carl speshocky, "Empowering Green Initiatives with IT", John Wiley & Sons, 2010.

5. Wu Chun Feng (editor), "Green computing: Large Scale energy efficiency", CRC Press, 2012.

COUF	RSE	OUT	СОМ	ES												
Upon	cor	nplet	ion o	f the	cours	se, st	udent	ts wil	l be a	ble to						
CO1	Ac	quire	know	ledge	e to ac	dopt g	reen	comp	uting	practi	ces to	minimi	ze neg	gative im	pacts on	the
	en	viron	ment.													
CO2	En	hanc	e the	skill ir	n ene	rgy sa	aving	practi	ces in	their	use of	hardw	are.			
CO3	Εv	aluat	e tecł	nolog	gy too	ls tha	t can	reduc	e pap	er wa	ste an	d carb	on foo	tprint by	the	
	sta	akehc	lders													
CO4	Un	nderst	tand t	he wa	ys to	minin	nize e	quipn	nent c	lispos	al requ	iiremei	nts .			
CO5	Le	arn a	bout	/ariou	s cas	e stud	dies									
					Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S			
COs					PR	OGR/		UTCC	OMES	(POs	5)				RAM SP	
	>	РО 1	PO 2	PO 3	РО 4	PO 5	PO 6	PO 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	1	3	3	3	1	1	1	1	1	2	1	1	2	3	2	2
CO2	2	3	3	3	1	1	1	1	1	2	1	1	2	3	2	2

ML1612	GAME PROGRAMMING L P	
OBJECTIVES	3       0       0         oncepts of Game design and development.       ses, mechanics and issues in Game Design.       6         a Core architectures of Game Programming.       e programming platforms, frame works and engines.       games. <b>BRAPHICS FOR GAME PROGRAMMING</b> aternions, 3D Modeling And Rendering, Ray Tracing, Shader , Texturing, Camera And Projections, Culling And Clipping, ysics-Based Simulation, Scene Graphs. <b>ME ENGINE DESIGN</b> re, Engine Support Systems, Resources And File Systems, me Simulation, Human Interface Devices, Collision And Rigid Profiling. <b>ME PROGRAMMING</b> I Logic, Game Views, Managing Memory, Controlling The Main Ching Game Data, User Interface Management, Game Event <b>MING PLATFORMS AND FRAMEWORKS</b> Iopment Using Flash, DirectX Or Python – Isometric And Tile ames, Single Player Games, Multi Player Games. <b>TOTAL : 45 PERIC</b> y And David Graham, "Game Coding Complete", Fourth Edit g, PTR, 2012.       Game Engine Design, Second Edition: A Practical Approach T uter Graphics" 2nd Editions, Morgan Kaufmann, 2006.	0 3
3       0       0       3         OBJECTIVES       Inderstand the concepts of Game design and development.       Inderstand the concepts of Game design and development.       Inderstand the concepts of Game architectures of Game Programming.         Image: Be exposed to the Core architectures of Game Programming.       Know about Game programming platforms, frame works and engines.       Image: Be exposed to the Core architectures of Game Programming.         Image: Image: Be exposed to the Core architectures of Game Programming.       Know about Game programming platforms, frame works and engines.       Image: Be exposed to the Core architectures of Game Programming.         Image: Image: Be exposed to the Core architecture, Engine Support Systems, Resources, Culling And Clipping, Character Animation, Physics-Based Simulation, Scene Graphs.       Image: Be exposed to the Core architecture, Engine Support Systems, Resources And File Systems, Game Loop And Real-Time Simulation, Human Interface Devices, Collision And Rigid Body Dynamics, Game Profiling.       B         Image:		
OBJECTIVES       3       0       0       3         • Understand the concepts of Game design and development.       • Learn the processes, mechanics and issues in Game Design.       • Be exposed to the Core architectures of Game Programming.       • Know about Game programming platforms, frame works and engines.       • Learn to develop games.         UNIT I       3D GRAPHICS FOR GAME PROGRAMMING       8         3D Transformations, Quaternions, 3D Modeling And Rendering, Ray Tracing, Shader Models, Lighting, Color, Texturing, Camera And Projections, Culling And Clipping, Character Animation, Physics-Based Simulation, Scene Graphs.       CO         UNIT II       GAME ENGINE DESIGN       8         Game Loop And Real-Time Simulation, Human Interface Devices, Collision And Rigid Body Dynamics, Game Profiling.       CO         UNIT III       GAME PROGRAMMING       8         Application Layer, Game Logic, Game Views, Managing Memory, Controlling The Main Loop, Loading And Caching Game Data, User Interface Management, Game Event Management.       CO         UNIT V       GAMING PLATFORMS AND FRAMEWORKS       8         2D And 3D Game Development Using Flash, DirectX Or Python – Isometric And Tile So Explored And 3D Interactive Games Using DirectX Or Python – Isometric And Tile Based Games, Puzzle Games, Single Player Games, Multi Player Games.       5         TOTAL : 45 PERIODS         REFERENCE BOOKS         1. Mike Mc Shaffrfy And David Graham, "Game Coding Complete", Fourth Edition		
	evelop games.	
UNIT I	3D GRAPHICS FOR GAME PROGRAMMING	8
3D Transformation	ns, Quaternions, 3D Modeling And Rendering, Ray Tracing, Shader	
Models, Lighting,	Color, Texturing, Camera And Projections, Culling And Clipping,	
Character Animati	on, Physics-Based Simulation, Scene Graphs.	1
		8
OBJECTIVES       • Understand the concepts of Game design and development.         • Learn the processes, mechanics and issues in Game Design.       • Be exposed to the Core architectures of Game Programming.         • Know about Game programming platforms, frame works and engines.       • Learn to develop games.         UNIT I       3D GRAPHICS FOR GAME PROGRAMMING       8         3D Transformations, Quaternions, 3D Modeling And Rendering, Ray Tracing, Shader Models, Lighting, Color, Texturing, Camera And Projections, Culling And Clipping, Character Animation, Physics-Based Simulation, Scene Graphs.       Co         UNIT II       GAME ENGINE DESIGN       8         Game Engine Architecture, Engine Support Systems, Resources And File Systems, Game Loop And Real-Time Simulation, Human Interface Devices, Collision And Rigid Body Dynamics, Game Profiling.       8         UNIT III       GAME PROGRAMMING       8         Application Layer, Game Logic, Game Views, Managing Memory, Controlling The Main Loop, Loading And Caching Game Data, User Interface Management, Game Engines – CO       Co         UNIT IV       GAMING PLATFORMS AND FRAMEWORKS       8         2D And 3D Game Development Using Flash, DirectX, Java, Python, Game Engines – CO       CO         DX Studio, Unity       4       UNIT V       GAME DEVELOPMENT         Based Games, Puzzle Games, Single Player Games, Multi Player Games.       5         TOTAL : 45 PERIODS         REFERENC		
	-	
		8
Application Layer,	Game Logic, Game Views, Managing Memory, Controlling The Main	<b> </b>
		3
	GAMING PLATFORMS AND FRAMEWORKS	8
2D And 3D Game	Development Using Flash, DirectX, Java, Python, Game Engines –	СО
DX Studio, Unity		4
UNIT V	GAME DEVELOPMENT	8
Developing 2D An	d 3D Interactive Games Using DirectX Or Python – Isometric And Tile	СО
		5
	TOTAL : 45 PERI	ODS
REFERENCE BO	OKS	
1. Mike Mc	Shaffrfy And David Graham, "Game Coding Complete", Fourth Ed	ition,
Cengage L	earning, PTR, 2012.	
2. Jason Gre	gory, "Game Engine Architecture", CRC Press / A K Peters, 2009	
<b>3.</b> David H. E	berly, "3D Game Engine Design, Second Edition: A Practical Approach	То
Real-Time	Computer Graphics" 2nd Editions, Morgan Kaufmann, 2006.	
4. Ernest Ada	ams And Andrew Rollings, "Fundamentals Of Game Design", 2nd Edition	n

- Eric Lengyel, "Mathematics For 3D Game Programming And Computer Graphics", 3rd Edition, Course Technology PTR, 2011.
- Jesse Schell, The Art Of Game Design: A Book Of Lenses, 1st Edition, CRC Press, 2008.

COURSE O	UTC	CON	IES													
Upon comp	oletio	on d	of the	e co	urse	, stu	dent	s wil	l be a	able	to					
CO1	Dis	scus	s the	e con	cept	s of (	Gam	e des	sign a	and d	levelo	pmen	ıt.			
CO2	De	sigr	n the	proc	esse	s, ar	nd us	e me	char	ics f	or gar	ne de	velop	ment.		
CO3	Ex	plair	n the	Cor	e arc	hitec	tures	s of G	Game	Pro	gramr	ning				
CO4	Us	e G	ame	prog	ramr	ning	platf	orms	, frar	ne w	orks a	and er	ngine	S		
CO5	Cre	eate	inte	ractiv	ve Ga	ames	S.									
	I			MA	PPIN	IG O	F CC	Ds W	ITH I	POs	AND	PSOs	6			
				F	PRO	GRA	MO	UTC	OME	S (P(	Os)			S	ROGRA	С
COs		PO	PO	PO	PO	PO	РО	РО	РО	PO	РО	РО	PO	0	UCOME	:5
		1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
CO1		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

ML1613	GAME THEORY L T	Ρ	С
DBJECTIVES       To impart knowledge on         To understand the sequential moves         To familiarize with Simultaneous moves         To solve strategic games between two and more agents in non - coo scenario         To solve both simultaneous and sequential move games         To learn different methods to solve games         UNIT I       INTRODUCTION AND GENERAL PRINCIPLES         Basic Ideas and Examples- Decisions versus Games- Classifying games terminology and background assumptionsthe uses of game theory- Games with sequential moves         • game trees solving games by using trees adding more players -Evidence concerning rollback-Strategies in the survivor game         UNIT II       SIMULTANEOUS-MOVE GAMES         Games with Simultaneous-Move Games with Pure Strategies : Nash Equilibrium – Dominance-Best-Response Analysis - The Minimax Method For Zero-Sum Games - Three Players - Multiple Equilibria In Pure Strategies –No Equilibrium In Pure Strategies-Discrete Strategies- Simultaneous-Move Games with Pure Strategies – Continuous Strategies Pure Strategies That Are Continuous Variables Requirements of Rationality for Nash Equilibrium - Rationalizability         UNIT III       BROAD CLASSES OF GAMES AND STRATEGIES         Jncertainty and Information -Imperfect Information: Dealing With Risk-Asymmetric information: Basic Ideas-Direct Communication-Adverse Selection, Signaling and Screening -Equilibria In Signaling Games -The Prisoners' Dilemma And Repeated Games -The Basic Game - Solutions -Repetition -Penalties And Rewards -	0	3	
OBJECTIVES         To impart knowledge on         To understand the sequential moves         To familiarize with Simultaneous moves         To solve strategic games between two and more agents in non - cooperat scenario         To solve both simultaneous and sequential move games         To learn different methods to solve games         UNIT I       INTRODUCTION AND GENERAL PRINCIPLES       9         Basic Ideas and Examples- Decisions versus Games- Classifying games terminology and background assumptionsthe uses of game theory- Games with sequential moves       9         Games trees solving games by using trees adding more players -Evidence concerning rollback-Strategies in the survivor game       9         Games with Simultaneous-Move Games with Pure Strategies : Nash Equilibrium – Dominance-Best-Response Analysis - The Minimax Method For Zero-Sum Games - Three Players - Multiple Equilibria In Pure Strategies –No Equilibrium In Pure Strategies-Discrete Strategies- Simultaneous-Move Games with Pure Strategies – Continuous Strategies Pure Strategies That Are Continuous Variables Requirements of Rationality for Nash Equilibrium - Rationalizability       CO2			
	o solve strategic games between two and more agents in non - co	opera	ativ
scer	nario		
	o solve both simultaneous and sequential move games		
	b learn different methods to solve games		
UNIT I	INTRODUCTION AND GENERAL PRINCIPLES	9	
Basic Ideas	and Examples- Decisions versus Games- Classifying games terminology		
and backgro	ound assumptionsthe uses of game theory- Games with sequential moves	0	1
- game tre	ees solving games by using trees adding more players -Evidence		
concerning	rollback-Strategies in the survivor game		
UNIT II	SIMULTANEOUS-MOVE GAMES	9	
Games with	Simultaneous-Move Games with Pure Strategies : Nash Equilibrium –		
Dominance	-Best-Response Analysis - The Minimax Method For Zero-Sum Games -		
Three Play	ers - Multiple Equilibria In Pure Strategies –No Equilibrium In Pure		_
Strategies-I	Discrete Strategies- Simultaneous-Move Games with Pure Strategies –	CO	2
Continuous	Strategies Pure Strategies That Are Continuous Variables Requirements		
		9	
Uncertainty	and Information -Imperfect Information: Dealing With Risk-Asymmetric		
•			
		co	3
•			-
•	· ·	9	
•	•		
-		СО	4
•	minated Actions- Iterated Elimination of Weakly Dominated Actions-		
Dominance			
UNIT V	APPLICATION	9	
	ng Rules, Paradoxes, Strategic Manipulation –Bidding strategy and	1	

Auction Design -Bargaining: Nash Bargaining Solution, Ultimatum game, Alternatingoffers game, Threat Points, Bargaining Shares

## TOTAL : 45 PERIODS

## TEXT BOOKS

- 1. Avinash K. Dixit , David H. Reiley Jr. , Susan Skeath "Games of Strategy" , W. W. Norton & Company, Fourth International Student Edition, 2015.
- 2. Martin J. Osborne, "An Introduction to Game Theory", Oxford University Press, Illustrated Reprint, 2003

### **REFERENCE BOOKS**

- 1. Martin J. Osborne and Ariel Rubinstein, "A course in game theory", MIT Press, 1994.
- 2. Joel Watson , "Strategy: An Introduction to Game Theory"Hardcover, W. W. Norton & Company, Third Edition, 2013.

### **COURSE OUTCOMES**

Upon completion of the course, students will be able to

CO1	Create game tree for any application.
CO2	Use different strategies for simultaneous-move games
CO3	Analyze strategic games between two and more agents in non - cooperative scenario
CO4	Apply Equilibrium and Rationalizability for games
CO5	Deploy game strategy in various applications

													Р	ROGRAM	
			F	PROC	GRAN	N OU	тсо	MES	(PO	5)			5	SPECIFIC	
COs													C	UCOMES	
	PO1	PO	PO	РО	PO	PO	РО	PO	PO	P01	P01	P01	PSO1	PSO2	PS
	101	2	3	4	5	6	7	8	9	0	1	2	1001	1002	O3
CO1	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

ML1614			P	T	C
OBJECTI		3	0	0	3
• To	explore the features of Parallel Programming Platforms				
	learn the concepts of CUDA programming Model				
	provide knowledge about Analytical Modeling Of Parallel Programs				
	know about dense matrix algorithms				
	explore different search algorithms				
	PARALLEL PROGRAMMING PLATFORMS:				8
		4			0
	n: Scope, issues, applications and challenges of Parallel and Distributed				
Computing					
	essor Architectures, Dichotomy of Parallel Computing Platforms, Physica			004	
•	on, Communication Costs in Parallel Machines, Routing Mechanisms fo	or	(	CO1	
	ction Networks, GPU, co-processing.				
-	of Parallel Algorithm Design: Decomposition Techniques, Characteristics o	DT			
	Interactions, Mapping Techniques for Load Balancing.				
UNIT II	CUDA PROGRAMMING MODEL				8
	of CUDA, Isolating data to be used by parallelized code, API function to				
	emory on parallel computing device, to transfer data, Concepts of Threads,				
-	ids, Developing a kernel function to be executed by individual threads,		(	CO2	
	of kernel function by parallel threads, transferring data back to host processor	r			
with API fu					
UNIT III	ANALYTICAL MODELING OF PARALLEL PROGRAMS				8
	f Overhead in Parallel Programs, Performance Metrics for Parallel Systems				
The Effect	of Granularity on Performance, Scalability of Parallel Systems, Minimum	n	(	CO3	
Execution	Time and Minimum Cost-Optimal Execution Time				
UNIT IV	DENSE MATRIX ALGORITHMS				8
Matrix-Vec	tor Multiplication, Matrix-Matrix Multiplication, Issues in Sorting on Paralle	el			
Computers	s, Bubble Sort and Variants, Quick Sort, Other Sorting Algorithms Graph	h			
Algorithms	: Minimum Spanning Tree: Prim's Algorithm, Single-Source Shortest Paths	S:	(	CO4	
Dijkstra's	Algorithm, All-Pairs Shortest Paths, Transitive Closure, Connected	d			
Componer	ts, Algorithms for Sparse Graph				
UNIT V	SEARCH ALGORITHMS FOR DISCRETE OPTIMIZATION PROBLEMS				8
	Search Algorithms, Parallel Depth-First Search, Parallel Best-First Search,			C05	
Sequentia	nomalies in Parallel Search Algorithms			000	

1.	A	Grama.	AGur	ora. G	Karvo	ois. V I	Kuma	r. Intro	oductio	on to Pa	arallel	Compu	tina (2r	nd ed.). A	Addison
		esley, 2	•	, -	- 71	- ,							5.	,	
2.	СГ	_in, L S	nyder	. Princ	ples	of Par	allel P	rogra	mming	g. USA:	Addis	on-We	sley Pu	blishing	
	Co	mpany	, 2008												
3.	JJ	effers,	J Reir	nders.	Intel >	Keon F	Phi Co	proce	ssor H	ligh-Pe	erforma	nce Pr	ogramn	ning. Mo	rgan
	Ka	ufmanr	n Publi	ishing	and E	Isevie	er, 201	3							
4.	ΤN	/lattson	i, B Sa	anders	, В Ма	assing	jill. Pa	tterns	for Pa	arallel F	Program	nming.	Addiso	n-Wesle	у
l	Pro	ofessio	nal, 20	04.											
COU	RSE	OUTC	OMES	;											
Upon	con	npletio	n of tl	he co	urse,	stude	nts w	ill be	able t	0					
C	D1	Explore	e the f	eature	es of F	Paralle	l Prog	Iramm	ing Pl	atforms	6				
C	D2	Unders	stand t	he co	ncept	s of Cl	JDA p	orogra	mming	g Mode					
C	D3	Analyz	e abo	ut Ana	lytical	Mode	eling C	Of Para	allel P	rogram	S				
C	D4	Explore	e den	se ma	trix al	gorithi	ns								
C	D5	Explore	e diffe	rent s	earch	algor	ithms	for op	timiza	tion pro	oblems				
						GRAM C				Ds ANE	1-208		PRO	GRAM SPI	
COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	OUCOME PSO2	S PSO3
CO1	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

	CASE BASED REASONING	L	Т	Ρ	С
	0	3			
	1				
•	understand the basic elements of case based reasoning				
•	•				
	•				
•		sou	rces	3	
Case-Based	⊥ Reasoning- Experiences and Cases -Parts of a Case -Problems - S	Solu	ition	<u> </u>	
					01
					•
				9	
Representatio	Lavers - Completeness and Efficiency -Flat Attribute	-V	alue	<u>.</u>	
Representation Measures - V Representation Similarities-	on-Complex Representations in General. Similarity and ons -Types of Similarity Measures –The Local-Global Principle for Sir Virtual Attributes- Similarity Measure to Use. Complex Similarities: ons and Graph Similarities- Largest Common Subgraphs Taxo Similarities for Object-Oriented Representations- Many-Y	mila Gr onc	arity aph omic		02
				<b>a</b>	
		-:14-0		-	
Nearest Neighbours - Trees Integra Indexing Usir	Geometric Approximation - Geometric Filtering-Index-Based Retrieva tion with Decision Trees. Case Indexing- Traditional Indexing Method ng a Bayesian Model, Prototype-Based Neural Network and Three-La	al - d-C	kd- Case	c	03
	OAGE ADADTATION AND GAGE DAGE DEVELODAENT			9	
	CASE ADAPTATION AND CASE-BASE DEVELOPMENT				
Rules - Adap Adaptations I Container. C Preprocessin Systematic D	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB	apta g D aine	ation ata, ers -		04
Rules - Adap Adaptations I Container. C Preprocessin Systematic D Other Technic	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB ques-Maintenance COMPLEX KNOWLEDGE SOURCES AND KNOWL	apta g D aine 3R	ation lata, ers - with		-
Rules - Adap Adaptations I Container. C Preprocessing Systematic D <u>Other Technic</u> UNIT V Textual CBR Management	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB ques-Maintenance COMPLEX KNOWLEDGE SOURCES AND KNOWL MANAGEMENT - Images- Sensor Data and Speech - Conversational CBR.Know	apta g D aine 3R _ED wle	ation Data, Ders - with DGE	9	
Rules - Adap Adaptations I Container. C Preprocessin Systematic D Other Technic UNIT V Textual CBR Management KM Cycles.	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB ques-Maintenance COMPLEX KNOWLEDGE SOURCES AND KNOWL MANAGEMENT - Images- Sensor Data and Speech - Conversational CBR.Know Case-Based Reasoning and Knowledge Management- CBR Implem	apta g D aine 3R _ED wle	ation Data, Ders - with DGE	9	
Rules - Adap Adaptations I Container. C Preprocessin Systematic D Other Technic UNIT V Textual CBR Management KM Cycles.	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB ques-Maintenance COMPLEX KNOWLEDGE SOURCES AND KNOWL MANAGEMENT - Images- Sensor Data and Speech - Conversational CBR.Know Case-Based Reasoning and Knowledge Management- CBR Implem	apta g D aine 3R _ED wle	ation Data, Ders - with DGE	9	
Rules - Adap Adaptations I Container. C Preprocessin Systematic D Other Technic UNIT V Textual CBR Management KM Cycles. TOTAL : 45 F TEXT BOOK	tation Types -The Adaptation Process - Adaptation Using Several Ca Jsing the Solution Process - Quality Issues - Knowledge in the Ada ase Based Development-Problem Formulation -Finding and Getting g - Case AcquisitionPrototypes and Evaluation The Knowledge Conta evelopment of CBR SystemsImplementation Aspects -Combining CB ques-Maintenance COMPLEX KNOWLEDGE SOURCES AND KNOWL MANAGEMENT - Images- Sensor Data and Speech - Conversational CBR.Know Case-Based Reasoning and Knowledge Management- CBR Implement <b>PERIODS</b>	apta g D aine 3R _ED _wle men	ation pata, ers - with DGE edge	9 9	0

REFE	RENCE	BOOKS	
		r, —Case-Based Reasoning, San Mateo, CA: Morgan Kaufmann I	-
		Applying Case-Based Reasoning: Techniques for Enterprise Syste	ems. San
Franc	sisco, C/	A: Morgan Kaufmann Inc. 1997.	
0.011		7001150	
		ITCOMES etion of the course, students will be able to	
-	· ·		
CO1	Knowl	edge the basic elements of case based reasoning	
CO2	Knowl	edge the case representation and similarity measures.	
CO3	Ability	to apply case retrieval, indexing and adaptation process	
CO4	Ability	to develop case based reasoning systems.	
CO5	Ability	to implement case based reasoning for managing complex knowled	edge sources
		MAPPING OF COS WITH POS AND PSOS	
	-	PROGRAM OUTCOMES (POs)	PROGRAM SPECIFIC

COs		PROGRAM OUTCOMES (POs)													SPECIFIC OUCOMES				
	РО 1	PO 2	PO 3	РО 4	РО 5	PO 6	РО 7	PO 8	РО 9	PO1 0	PO1 1	PO1 2	PSO1	PSO 2	PS O3				
CO1	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2				
CO2	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2				
CO3	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2				
CO4	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2				
CO5	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2				

# PROFESSIONAL ELECTIVE – III (SEMESTER VII)

ML1711	AI for CLINICAL INFORMATION SYSTEM	L	Т	Ρ	С
		3	0	0	
OBJECTIVES					
1.The	objective of this course is to gain insight and situational experience	ce v	with	cl	inical
informa	ation systems.				
2. To e	examine the effective use of data and information technology to assist i	in th	ie m	nigr	ation
away fr	rom paper-based systems				
3. To E	xplain the principles of health care data exchange and standards				
4.To ur	nderstand Human interaction system in Health care				
5. To	gain insights and understanding of the impacts placed on patients a	and	hea	lth	care
provide	ers.				
UNIT I	Introduction to clinical information system			9	)
Introduction to	clinical information systems – contemporary issues in healthcare – workf	low	and	1	
related tools f	or workflow design - electronic health records databases - Healthca	re l	Т&	(	201
portable techn	ology				
UNIT II	Artificial intelligence in health care			9	)
Artificial intellig	gence in health care: Use of AI, The healthcare industry, Electronic	med	lical	+	
records,Clinica	al decision support systems			(	02
	Machine learning in health care system			9	)
Machine lear	ning for natural language, Machine learning for vision, Human-co	ompi	uter		
interaction				0	03
UNIT IV	Bioethics and Challenges			9	)
Bioethics and	challenges to deployment, Grand challenges in clinical decision support			(	204
UNIT V	Big data analytics in health care			9	
Data mining	in health care, Big data analytics in health care, IBM Watson, Is	sues	s in	+	
-	ind interoperability				CO5
TOTAL : 45 P	· · ·				
TEXT BOOKS					
	Ash, Clinical Information Systems – Overcoming Adverse Conseque	nce	<u>s</u> .l	lon	es 8
•	Learning Publishers, 2009.		2, 0	•	
	H. Shortliffe; Leslie E. Perreault, Medical Informatics – Computer	Apr	olica	tior	ns i
	e and Biomedicine, Springer-Verlag New York Inc.Publishers, 2014. 3.	,	nea		

# **REFERENCE BOOKS**

- 1. Arnold, M. (2016). Digital health news update: Machine learning meets health search. Decision Resources Group
- Blenner, S. R., Köllmer, M., Rouse, A. J., Daneshvar, N., Williams, C., Andrews, L. B. (2016) Privacy Policies of Android Diabetes Apps and Sharing of Health Information. JAMA, 315(10), 1051

COURSE OUTCOMES																
Upon completion of the course, students will be able to																
CO1	To understand the basics of clinical information systems.															
CO2	To learn how to apply information technology and related tools in workflow design.															
CO3	To explore the "benefits and barriers" associated with electronic health records.															
CO4	Explain strategies to minimize major barriers to the adoption of electronic health records.															
CO5	Capacity for applying Artificial Intelligence techniques in technological and industrial															
	environments to improve quality and productivity															
MAPF								•		-						
			000		. 00		100	0						DDOO		
		PROGRAM OUTCOMES (POs) PROGRAM SPECIFIC OUTCOMES (PSOs)														
COs	ŀ									30s)						
		PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3
CO1		3	3	3	3	2	-	-	-	-	2	2	2	2	2	1
CO2	<b>O2</b> 3 3 3 3 2 2 2 2 2 2 1													1		
CO3		3	3	3	3	2	-	-	-	-	2	2	2	2	2	1
CO4		3	3	3	3	2	-	-	-	-	2	2	2	2	2	1
CO5		3	3	3	3	2	-	-	-	-	2	2	2	2	2	1

ML1712	AI IN HEALTHCARE	L	Р	т	С
	-	3	0	0	3
<ul> <li>To deserve</li> </ul>	uss the role of data analytics in quality and performance improvement eff cribe the tools and techniques used for data analytics in health care orga utify techniques for summarization and visualization of data				
<ul> <li>To und</li> </ul>	erstand various data analysis tools and Techniques				
	y regression and non-regression techniques for predictive analysis.				
UNIT I	INTRODUCTION TO QUALITY IMPROVEMENT AND DATA ANALYT				9
drivers for hea institution- He performance in of data analytic	ata analytics – Definition - How analytics can help transform health of th care transformation -Business value of data to an organization eg he alth care quality and value- The background and evolution of qua nprovement - The quality improvement frameworks that utilize analytics as techniques and their strengths and weaknesses.	ealth ality	care and	c	:01
	DATA PROCESSING AND REPORTING TECHNIQUES			<u> </u>	9
quality and saf Key Performar information, ki data analytics- and technique care issue.	Cycle- Data sources and data structures – examples from healthcare- Me ety of care- Various measures, metrics, and indicators -Defining and De nee Indicators- The purpose and use of Key Performance Indicators (KPI nowledge and wisdom hierarchy- Organizational approach for effective The role of data governance-The DMAIC problem-solving model and to s used in each step of the process - Apply the DMAIC methodology to	velo 's) - e us the t	ping Data e of tools	c	:02
UNIT III	DATA SUMMARY AND VISUALIZATION TECHNIQUES				9
relevance to to distributions in standard devia scatterplots- D techniques (fo	types -The information value chain - The importance of data control ousiness processes - Basic statistical terms - Recognize common part statistics -Distributions using numerical measures such as mean, mediation - Graphical representations of data including histograms, bar ch ata summary techniques (for measurement and categorical data)- Visue or measurement and categorical data)- Interactive visualization tech ses of data visualization.	ttern dian arts ıaliza	is or and and ation	c	:03
UNIT IV	DATA ANALYTICS TOOLS AND TECHNIQUES				9
The role of the data effectively	terms - The process steps of data analytics and the tools used in eace e data analyst - Tools and techniques used to analyse and interpret he y - Various types of databases and how they are structured -Data wa erprise data architecture in health care organizations.	alth	care	6	:04
UNIT V	PREDICTIVE ANALYTICS INVOLVING REGRESSION AND NON- REGRESSION TECHNIQUES				9
Simple linear r variables – M predictor varia analytics- Bay predicting hea	redictive analytics-Predicting one outcome variable from a predictor va egression-Predicting one measurement outcome variable from several p ultiple linear regression-Predicting one binary outcome variable from bles – Multiple logistic regression- Misuses of regression techniques in p esian techniques in predictive analytics- Application of Bayesian techn alth screening outcomes- Principles of Survival Analysis- Support luster analysis- Strategic applications of Sentiment Analysis in Healthcar	pred sev oredi nique t Ve re.	lictor veral ctive es in ector	C	:05
	TOTAL	.:4	5 PE	RIC	DS
Pramod Ku 2. Editors: Ch 3. Chandan K	naya, Ajith Abraham, Patrick Siarry, Mengjie Zhang, FazleBaki, Ana mar Singh," Big Data Analytics in Healthcare", 2019 andan K. Reddy, Charu C. Aggarwal," Healthcare Data Analytics", 2015. Reddy and Charu C. Aggarwal," Healthcare Data Analytics", First Editi Press 2015.				
REFERENCE	BOOKS				
1. Ross M. N Edition, T&	Aullner Edward M. Rafalski, "Healthcare Analytics – Foundations and F/Routledge, 2020. Iristo, Ali-Hassan, Hossam ," Analytics in Healthcare",springer 2019	Fro	ntier	s" l	-irst

COUR	_			-			_									
Upon	cor	nplet	ion o	f the	cours	se, st	udent	ts wil	l be a	ble to	)					
CO1	Ur	nderst	tand r	ole of	data	analy	tics ir	n quali	ity and	d perf	orman	ce imp	rovem	ent effor	ts in hea	thcare
	ins	stitutio	ons.													
CO2	Ur	nderst	tand t	he too	ols an	d tech	nnique	es use	ed for	data a	analyti	cs in h	ealth c	are orga	nizations	j.
CO3	Su	ımma	rize a	nd Vi	sualiz	e Dat	a.									
CO4	Ар	ply D	ata A	nalyti	cs To	ols ar	nd Teo	chniqu	Jes.							
CO5	Pr	edict	health	n scre	ening	outco	omes.	, Surv	ival A	nalysi	is and	sentim	ent an	alysis in	Healthca	are.
					0											
					Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	s			
					PR	OGR			MES	(POs	4			PROG	RAM SP	ECIFIC
COs				-	1			-	-	(1 03	-			C		S
003	,	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO1	PSO2	PSO3
		1	2	3	4	5	6	7	8	9	10	11	12		1002	1000
CO1		2	2	2	2	2	-	-	-	-	2	2	2	2	3	2
CO2	2	3	3	3	3	3	-	-	-	-	2	2	2	2	3	2
CO3	•	3	3	3	3	3	-	-	-	-	2	2	2	2	3	2
CO4		3	3	3	3	3	-	-	-	-	2	2	2	2	3	2
CO5		2	2	2	2	2	_	-	-	-	2	2	2	2	3	2

			Т	<b>P</b> (	
		3 (	0	0	3
OBJECTIVE	S				
•	Recognize the process of formulating business obje				lata
	selection/collection, preparation and process to successfully				
	evaluate and implement predictive models for a vario	bus	bu	sin	ess
	application.				
•	Compare and contrast the underlying predictive modelling tech	•			
•	Select appropriate predictive modelling approaches to iden	itity	ра	rtic	uia
	Cases.	۳d	مابية	-+	rine
•	Appreciate the nuances of Support Vector Machines an techniques.	na	ciu	ster	nng
•	Apply predictive modelling approaches using a suitable pack	kaac		ich	20
•	SPSS Modeler	naye	5 30	JUII	a
	DATA UNDERSTANDING & PREPARATION			9	
-	usiness objectives, translating business objectives to data mining	doa	als	5	
	a from various sources – Database/ Excel/ Text/others,				
Ų	- tabular & graphic, distributions and summary statistics			С	01
	Reclassify data.	,			
UNIT II	DATA TRANSFORMATIONS			9	
Data quality	issues, Data Audit, anomalies, relationships among variables, Ex	tent	of		
	a, Segmentation, Outlier detection, Variable transformations, Va				
	ariable selection, Automated Data Preparation, combining data			С	02
	cturing, Aggregation, Duplicates removal, Sampling cases,	Da	ata		
	rtitioning data, Missing Value replacement.				
				9	
	The Data - Training, Validation & Testing, Model selection,			6	03
	t techniques - Linear regression, Logistic regression, Discrii yesian networks, Neural networks, Rule Induction.	1111110	ant		03
UNIT IV	MODELING TECHNIQUES – II			9	
-	tor machines, Cox regression, Time series analysis, Decision			-	
		tree	es.		-
Clusterina. A				С	04
0	ssociation Rules, Sequence Detection, Which Technique to use w			С 9	04
UNIT V	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT	whei	n.		04
UNIT V Model Valic	ssociation Rules, Sequence Detection, Which Technique to use w	wher CHAI	n. ID,		04
UNIT V Model Valic Automating	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C	wher CHAI inuo	n. ID, ous	9	
UNIT V Model Valic Automating Targets, Co Comparison	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for Using Propensity Scores, Meta-Level Modeling, Error Mode	Wher CHAI inuo Moc delir	n. ID, bus del ng,	9	04
UNIT V Model Valic Automating Targets, Co Comparison Deploying I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perform	Wher CHAI inuo Moc delir	n. ID, bus del ng,	9	
UNIT V Model Valic Automating Targets, Co Comparison Deploying I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perform Model.	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perform	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perforn Model.	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perforn Model.	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I	Association Rules, Sequence Detection, Which Technique to use w MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Conti omparing and Combining Models, Evaluation Charts for Using Propensity Scores, Meta-Level Modeling, Error Mod Model, Exporting Model Results, Assessing Model Perforn Model.	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining	Association Rules, Sequence Detection, Which Technique to use weight MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using Comparing and Combining Models, Evaluation Charts for bomparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : S & Predictive Modeling (IBM ICE Publications).	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining	Association Rules, Sequence Detection, Which Technique to use weight MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using Comparing and Combining Models, Evaluation Charts for bomparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : S & Predictive Modeling (IBM ICE Publications).	wher CHAI inuo Moc delir nanc	n. ID, bus del ng, ce,	9 C	05
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining	Association Rules, Sequence Detection, Which Technique to use weight MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Contribution of the Comparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : & Predictive Modeling (IBM ICE Publications). E BOOKS	when CHAI inuo Moo delir nanc <b>45</b> I	n. ID, bus del ng, ce, <b>PEI</b>		
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining REFERENC 1. D	Association Rules, Sequence Detection, Which Technique to use we MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using Comparing and Combining Models, Evaluation Charts for bomparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model, Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : S & Predictive Modeling (IBM ICE Publications). EBOOKS eata Mining and Predictive Analytics (Wiley Series on Methods and	when CHAI inuo Moo delir nanc <b>45</b> I	n. ID, bus del ng, ce, <b>PEI</b>		
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining REFERENC 1. D	Association Rules, Sequence Detection, Which Technique to use weight MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using C Models for Categorical Targets, Automating Models for Contribution of the Comparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : & Predictive Modeling (IBM ICE Publications). E BOOKS	when CHAI inuo Moo delir nanc <b>45</b> I	n. ID, bus del ng, ce, <b>PEI</b>		
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining REFERENC 1. D	Association Rules, Sequence Detection, Which Technique to use we MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using Comparing and Combining Models, Evaluation Charts for bomparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model, Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : S & Predictive Modeling (IBM ICE Publications). EBOOKS eata Mining and Predictive Analytics (Wiley Series on Methods and	when CHAI inuo Moo delir nanc <b>45</b> I	n. ID, bus del ng, ce, <b>PEI</b>		
UNIT V Model Valic Automating Targets, Co Comparison Deploying I Updating A I TEXT BOOP Data Mining REFERENC 1. D	Association Rules, Sequence Detection, Which Technique to use we MODEL EVALUATION & DEPLOYMENT ation, Determining Model Accuracy, Rule Induction Using Comparing and Combining Models, Evaluation Charts for bomparing and Combining Models, Evaluation Charts for , Using Propensity Scores, Meta-Level Modeling, Error Model, Model, Exporting Model Results, Assessing Model Perform Model. TOTAL : S & Predictive Modeling (IBM ICE Publications). EBOOKS eata Mining and Predictive Analytics (Wiley Series on Methods and	when CHAI inuo Moo delir nanc <b>45</b> I	n. ID, bus del ng, ce, <b>PEI</b>		

COURS	E Ol	лтсс	MES	\$											
Upon co	ompl	etior	n of t	he co	ourse	ə, stı	Ident	ts wil	l be	able t	0				
CO1	s		ion/c	ollec	tion,	• •	arati	on a	nd p		s to		s obje ssfully usiness	0	
CO2	0	Comp	are a	and c	ontra	ist the	e und	lerlyir	ng pro	edictiv	/e mo	deling	technic	lues.	
CO3	5	Selec	t app	ropria	ate p	redic	tive n	nodel	ling a	pproa	ches	to ide	ntify par	ticular o	cases.
CO4	ŀ	۱ppre	ciate	the i	nuan	ces c	of Sup	oport	Vect	or Ma	chine	s and	clusterii	ng techr	niques.
CO5		Apply Mode	•							ising a			ackage	such as	SPSS
COs				PRO	GRA	MO	UTCO	OME	S (PC	Ds)			S	ROGRA PECIFI JTCOM (PSOs)	C ES
	P 0 1	P 0 2	P 0 3	P 0 4	P 0 5	P 0 6	P 0 7	P 0 8	P 0 9	PO 10	РО 11	PO 12	PSO 1	PSO 2	PSO 3
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CO1	3	3	3	3	2	-	2	-	-	2	2	2	2	2	1
CO1 CO2	3 3	3 3	3 3	3	2 2	-	2	-	-	2	2	2	2	2 2	1 1

CO4

CO5

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CS1712	VIRTUALIZATION TECHNIQUES L	•	Т	Ρ	С
	3	(	0	0	3
OBJECTIVES					
	lerstand the concept of virtualization.				
	lerstand the various issues in virtualization.				
To be f	familiar with the virtualization of various components/functionalities.				
<ul> <li>To con</li> </ul>	npare and analyze various virtual machines products.				
To wor	k with virtualization platforms				
	INTRODUCTION				g
-	ectures – Virtual Machine Basics – Process Virtual Machines – System V	∕irt	ual		-
Interpretation	Taxonomy of Virtual Machines – Emulation: Basic Interpretation – Thre – Pre-Coded & Direct Interpretation – Binary Translation – Full and – Types of Hypervisor – Types of Virtualization				01
	SERVER VIRTUALIZATION				
-	j SERVER VIRIUALIZATION zation – Partitioning Techniques – Hardware Virtualization – Virtual Hardw	/ar4	ρ		9
Types of Service	ver Virtualization – Business Cases for Sever Virtualization – Uses of V lidation – Selecting Server Virtualization Platform				02
UNIT III	NETWORK VIRTUALIZATION				9
Scalability 7	WAN virtualization – Virtual Enterprise Transport Virtualization – VLANs	00			
Layer 2 – VFIs Layer 2: 802. Paths – Cont	Theory Network Device Virtualization Layer 2 – VLANs Layer 3 VRF Insta s Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing – ting	zat itch	ion 1ed	С	03
Layer 2 – VFIs Layer 2: 802. Paths – Cont Topology Rou	s Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing – ting	zat itch	ion 1ed	С	
Layer 2 – VFIs Layer 2: 802. Paths – Cont Topology Rou UNIT IV Hardware Dev Fiber Channe iSCSI SAN Ba Storage Mode	s Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing –	zati itch Mu nne cur hai	ion ned ulti- ulti- el – ing red	C	9
Layer 2 – VFIs Layer 2: 802. Paths – Cont Topology Rou UNIT IV Hardware Dev Fiber Channe iSCSI SAN Ba Storage Mode Architecture –	s Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing – ting STORAGE VIRTUALIZATION vices – SCSI – SCSI Communication – Using SCSI Buses – Fiber Chan I Cables – Fiber Channel Hardware Devices – iSCSI Architecture – Sec ackup & Recovery Techniques – RAID – Classic Storage Model – SNIA Si el Host based Architecture – Storage based architecture – Network b Fault tolerance to SAN – Performing Backups – Virtual Tape Libraries	zati itch Mu nne cur hai	ion ned ulti- ulti- el – ing red	C	O3
Layer 2 – VFIs Layer 2: 802. Paths – Cont Topology Rou UNIT IV Hardware Dev Fiber Channe iSCSI SAN Ba Storage Mode Architecture – UNIT V Comparison o Level – Shar Microsoft Virtu with Server V Desktop Virtu	s Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing – ting <b>STORAGE VIRTUALIZATION</b> vices – SCSI – SCSI Communication – Using SCSI Buses – Fiber Channel I Cables – Fiber Channel Hardware Devices – iSCSI Architecture – Sec ackup & Recovery Techniques – RAID – Classic Storage Model – SNIA Sl el Host based Architecture – Storage based architecture – Network the Fault tolerance to SAN – Performing Backups – Virtual Tape Libraries <b>APPLYING VIRTUALIZATION</b> f Virtualization Technologies: Guest OS, Host OS, Hypervisor, Emulation, K ed Kernel – Enterprise Solutions: Vmware Server, ESXi, Citrix Xen Sec virtualization, Adjusting & Tuning Virtual Servers, VM Backup and Migrata alization: Terminal Services, Hosted Desktop, Web Based Solutions, Loca sktop – Network and Storage Virtualization: VPN, VLAN, SAN and VSAN, N	zati itch Mu nne cur hau bas Kern Serv tior aliz	ion ned ulti- ing red sed nel ver, ver n – zed	C C	04 9 05
Layer 2 – VFIs Layer 2: 802. Paths – Cont Topology Rou UNIT IV Hardware Dev Fiber Channe iSCSI SAN Ba Storage Mode Architecture – UNIT V Comparison o Level – Shar Microsoft Virtu with Server V Desktop Virtu	S Virtual Firewall Contexts Network Device Virtualization – Datapath Virtualiz 1q – Trunking Generic Routing Encapsulation – IPSec L2TPv3 Label Swi trol-Plane Virtualization – Routing Protocols – VRF- Aware Routing – ting STORAGE VIRTUALIZATION vices – SCSI – SCSI Communication – Using SCSI Buses – Fiber Chan I Cables – Fiber Channel Hardware Devices – iSCSI Architecture – Sec ackup & Recovery Techniques – RAID – Classic Storage Model – SNIA Sl el Host based Architecture – Storage based architecture – Network b Fault tolerance to SAN – Performing Backups – Virtual Tape Libraries APPLYING VIRTUALIZATION f Virtualization Technologies: Guest OS, Host OS, Hypervisor, Emulation, K ed Kernel – Enterprise Solutions: Vmware Server, ESXi, Citrix Xen Se virtualization, Adjusting & Tuning Virtual Servers, VM Backup and Migrat alization: Terminal Services, Hosted Desktop, Web Based Solutions, Loca sktop – Network and Storage Virtualization: VPN, VLAN, SAN and VSAN, N TOTAL : 4	zati itch Mu nne cur hau bas Kern Serv tior aliz	ion ned ulti- ing red sed nel ver, ver n – zed	C C	04 9 05

#### **REFERENCE BOOKS** William von Hagen, "Professional Xen Virtualization", Wrox Publications, January, 2008. 1. Kumar Reddy, Victor Moreno, "Network virtualization", Cisco Press, July, 2006. 2. Amy Newman, Kenneth Hess, "Practical Virtualization Solutions: Virtualization from the 3. Trenches", Prentice Hall, October 2009 **COURSE OUTCOMES** Upon completion of the course, students will be able to CO1 Create a virtual machine and extend it to a virtual network. CO2 Perform server virtualization. CO3 Explain the concept of network virtualization. CO4 Discuss various tasks in storage virtualization. CO5 Compile all types of virtualization techniques and utilize them in design of virtual machines MAPPING OF COs WITH POs AND PSOs **PROGRAM SPECIFIC PROGRAM OUTCOMES (POs)** OUTCOMES (PSOs) COs PO4 PO1 PO2 PO3 PO5 **PO6** PO7 PO8 PO9 PO10 PO11 PO12 PSO1 PSO2 PSO3 CO1 3 3 3 3 2 -\_ --1 2 2 2 3 3 CO<sub>2</sub> 3 3 3 2 2 3 3 2 1 ---2 2 -CO3 3 3 3 3 2 ---2 2 2 3 3 2 -**CO4** 3 3 2 2 2 3 3 2 3 3 ---1 -CO5 3 3 2 2 1 1 2 2 3 3 2 -\_

IT1715	AUGMENTED & VIRTUAL REALITY	L	Р	т	С
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OBJECTIVES		-	-	-	
demon econor • To und engine	oduce the relevance of this course to the existing technology through strations, case studies and applications with a futuristic vision along nic impact and issues lerstand virtual reality, augmented reality and using them to build Bio ering applications w the intricacies of these platform to develop PDA applications with b lity	with mec	dical		
UNIT I	VIRTUAL REALITY AND VIRTUAL ENVIRONMENTS				8
computer grap of Virtual real	development of VR: Scientific landmarks Computer Graphics, Robics, Flight simulation, Virtual environments, Requirements for VR, ity. HARDWARE TECHNOLOGIES FOR 3D USER INTERFACES itory Displays, Haptic Displays, Choosing Output Devices for 3	ben : Vi	efits sual	С	01
UNIT II	3D USER INTERFACE INPUT HARDWARE				8
Purpose Input	haracteristics, Desktop input devices, Tracking Devices, 3D Mice, Sp Devices, Direct Human Input, Home - Brewed Input Devices, Choos for 3D Interfaces		al	с	02
UNIT III	SOFTWARE TECHNOLOGIES				8
Position / Ori Environment - Cameras, Scr Panel, 2D Co	/orld Space, World Coordinate, World Environment, Objects - Ge entation, Hierarchy, Bounding Volume, Scripts and other attribut VR Database, Tessellated Data, LODs, Cullers and Occluders, Lig ripts, Interaction - Simple, Feedback, Graphical User Interface, ontrols, Hardware Controls, Room / Stage / Area Descriptions Playback, VR toolkits, Available software in the market	tes, ihts Coi	VR and ntrol	С	О3
UNIT IV	3D INTERACTION TECHNIQUES			1	8
Techniques fo Design Guidel Support, Envir Guidelines - S Commands, T Study: Mixing Techniques, E DEVELOPING Guidelines a Architecture, E	tion tasks, Manipulation Techniques and Input Devices, Inter r 3D Manipulation, Deign Guidelines - 3D Travel Tasks, Travel Tech lines - Theoretical Foundations of Wayfinding, User Centered War ronment Centered Wayfinding Support, Evaluating Wayfinding Aids, ystem Control, Classification, Graphical Menus, Voice Commands, C Fools, Mutimodal System Control Techniques, Design Guidelines g System Control Methods, Symbolic Input Tasks, symbolic Design Guidelines, Beyond Text and Number entry . DESIGNIN G 3D USER INTERFACES: Strategies for Designing and Dev and Evaluation. VIRTUAL REALITY APPLICATIONS: Engine Education, Medicine, Entertainment, Science, Training.	nniq yfin Gest Gest C li G A yelop	ues, ding sign trual case nput \ND ping	с	04
UNIT V					8
difference betw Augmented re displays in edu	nd Mixed Reality, Taxonomy, technology and features of augmented ween AR and VR, Challenges with AR, AR systems and functionality ality methods, visualization techniques for augmented reality, wireles ucational augmented reality applications, mobile projection interfaces acking for augmented reality, enhancing interactivity in AR environme systems.	, iS i,	•	c	05
	TOTAL	: 45	PE	RIO	DS

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4.	0	Dliver	Bimb	er an	d Rar	nesh	Rask	ar, "S	Spatia	al Aug	mente	ed Rea	ality: N	leging R	leal and	Virtual
	W	Vorlds	", 20	05.						-			-			
5.					C an	d Phi	lippe	Coiff	et. "V	irtual	Realit	v Tec	hnoloc	gy", Wile	v Inters	cience.
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8.									-			-	-	ual Rea	•	
	A	Application and Design (The Morgan Kaufmann Series in Computer Graphics)". Morgan Kaufmann Publishers, San Francisco, CA, 2002														
	K	Kaufmann Publishers, San Francisco, CA, 2002														
9.	A	Alan B. Craig, Understanding Augmented Reality, Concepts and Applications, Morgan														
	K	aufm	ann,	2013	. A	Gram	na, A	Gupr	a, G	Kary	∕pis, ∖	/ Kun	nar. Iı	ntroducti	on to F	Parallel
	Kaufmann, 2013. A Grama, AGupra, G Karypis, V Kumar. Introduction to Parallel Computing (2nd ed.). Addison Wesley, 2003.															
COU	RSF			IES												
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	er	nginee	ering	const	raints	6.										
CO2	Id	ontifu	nroh	loma	tator	onto	and f	uncti	00.00	2 mc	mbor	of an	onging	oring de	cian too	m
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CO3	U	tilize t	echn	ical re	esour	ces										
CO4	Pr	ropos	e tecl	nnica	docu	umen	ts rela	ated t	o des	ign m	nini pro	oject re	esults.			
CO5	G	ive te	chnic	al ora	l pres	senta	tions	relate	ed to	desig	n mini	projec	ct resu	lts.		
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CO1 CO2	1 2 3	0 1 2 2	<b>0</b> 2 2	<b>O</b> 3 2 2	<b>P</b> <b>O</b> <b>4</b> 2 2	<b>P</b> <b>O</b> <b>5</b> 1	P 0 6 -	P 0 7 -	<b>P</b> <b>O</b> <b>8</b> 1	<b>P</b> <b>O</b> <b>9</b> 1	PO 10 1	<b>11</b> 1 1	<b>12</b> 1 1 1	0 PSO 1 2 2	UCOME PSO 2 2 2	<b>PSO</b> 3 2 2
CO1 CO2 CO3	1 2 3 4	0 1 2 2 2	0 2 2 2 2	0 3 2 2 2	<b>P</b> <b>O</b> <b>4</b> 2 2 2	<b>P</b> <b>O</b> <b>5</b> 1 1 1	P 0 6 - -	P 0 7 -	<b>P</b> <b>O</b> 8 1 1	<b>P</b> <b>O</b> <b>9</b> 1 1 1	PO 10 1 1 1	11 1 1 1	12 1 1 1	0 PSO 1 2 2 2	UCOME PSO 2 2 2 2	<b>PSO</b> 3 2 2 2 2

# PROFESSIONAL ELECTIVE – IV (SEMESTER VII)

ML1721	GENETIC ALGORITHM	L	Т	PC
OBJECTIVES		3	0	03
UNIT I Introduction: simple genetic Genetic Algor prediction, evo	<ol> <li>To understand the concepts of Genetic algorithm scientific models</li> <li>To build and implement a computer implementation of genetic algorith</li> <li>To survey of the many aspects of evolutionary algorithms (EAs), in page, ES, technique</li> <li>To known about Advance operators and techniques in genetic Search</li> <li>To understand data mining using genetic algorithm dearch in industriation</li> <li>Introduction to Genetic Algorithms in Scientific models</li> <li>A brief history of evolutionary computation, Elements of Genetic Algorithm algorithm, Applications of genetic algorithms</li> <li>rithms in Scientific models: Evolving computer programs, data analysis alving neural networks, Modelling interaction between learning and evolutional selection, measuring evolutionary activity.</li> </ol>	articu ch al ap ms, A s and		
UNIT II	Theoretical Foundation of genetic algorithm:			9
royal roads, ex Approaches. Computer Imp mutation, map	undation of genetic algorithm: Schemas and Two-Armed and k-armed pro act mathematical models of simple genetic algorithms, Statistical- Mecha lementation of Genetic Algorithm: Data structures, Reproduction, crossov ping objective functions to fitness form, fitness scaling, coding, a multipara point coding, discretization and constraints	anics ver ar	nd	CO2
UNIT III	Applications of genetic algorithms			9
	ions of genetic algorithms: The risk of genetic algorithms, De Jong and fu mprovement in basic techniques, current application of genetic algorithms		'n	CO3
UNIT IV	Advanced operators and techniques in genetic search:			9
inversion and o	rators and techniques in genetic search: Dominance, duplicity, and abeya other reordering operators. Other micro operators, Niche and speciation, optimization, knowledge based techniques, genetic algorithms and paralle	·	,	CO4
UNIT V	Industrial Application Of Genetic Algorithms			9
	ication Of Genetic Algorithms: Data mining using genetic Algorithms Se enetic algorithms for game playing eg TIC TAC TOE			CO5
TEXT BOOKS		4(	J 7 C	-11003
	, c algorithms in search, optimization and Machine Learning by David E. Go	oldhe	era	
	n Education	2.000	- <del>J</del> ,	

- 1. An introduction to genetic algorithms by Melanle Mitchell, PHI.
- 2. The simple genetic algorithm foundations and theory by Michael D. Vose, PHI

# COURSE OUTCOMES

Upon completion of the course, students will be able to

CO1 Discuss about basic of Genetic algorithm	n
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CO2 Apply Evolutionary Computation Methods to find solutions to complex problems

CO3 Analyze and experiment with parameter choices in the use of Evolutionary Computation

CO4 Summarize current research in Genetic Algorithms and Evolutionary Computing

CO5 Explain Industrial application of Genetic algorithm

## MAPPING OF COS WITH POS AND PSOS

COs				PR	OGR/		UTCC	MES	(POs	)			PROGRAM SPECIFIC OUTCOMES (PSOs)			
	PO1	PO2	PO3	PSO1	PSO2	PSO3										
CO1	3	3	3	3	2	-	-	2	-	2	2	2	2	2	1	
CO2	3	3	3	3	2	-	-	2	-	2	2	2	2	2	1	
CO3	3	3	3	3	2	-	-	2	-	2	2	2	2	2	1	
CO4	3	3	3	3	2	-	-	2	-	2	2	2	2	2	1	
CO5	3	3	3	3	2	-	-	2	-	2	2	2	2	2	1	

ML1722	SPEECH PROCESSING	L	P	T	C
OBJECTIVE	ES	3	0	0	3
	nderstand the fundamentals of the speech processing				
	pre the various speech models				
	er knowledge about the phonetics and pronunciation processing				
	orm wavelet analysis of speech				
	nderstand the concepts of speech recognition				
UNIT I	INTRODUCTION				9
Introduction	<ul> <li>knowledge in speech and language processing – ambiguity – mod</li> </ul>	lels	and		<u> </u>
algorithms -	- language – thought – understanding – regular expression and automata	– w	ords	C	:01
& transduce	rs – N grams				
UNIT II	SPEECH MODELLING				9
Word classe	es and part of speech tagging – hidden markov model – computing likeliho	ood	: the		<u> </u>
forward algo	prithm – training hidden markov model – maximum entropy model – transfo	rma	tion-		$\cdot \cap 2$
based taggi	ng - evaluation and error analysis - issues in part of speech tagging	– r	noisy		:02
channel mod	del for spelling				
UNIT III	SPEECH PRONUNCIATION AND SIGNAL PROCESSING			1	9
Phonetics -	speech sounds and phonetic transcription - articulatory phonetics - phor	nolo	gical		<u> </u>
categories a	nd pronunciation variation – acoustic phonetics and signals – phonetic reso	ourc	es –	C	:03
articulatory a	and gestural phonology				
UNIT IV	SPEECH IDENTIFICATION				9
Speech syn	thesis - text normalization - phonetic analysis - prosodic analysis -	dipł	none	C	:04
waveform sy	nthesis – unit selection waveform synthesis – evaluation				
UNIT V	SPEECH RECOGNITION				9
Automatic s	speech recognition - architecture - applying hidden markov model -	fea	ature		
extraction: n	nfcc vectors - computing acoustic likelihoods - search and decoding - em	nbed	dded		
training - r	nultipass decoding: n-best lists and lattices- a* (_stack') decoding -	con	text-	C	:05
dependent	acoustic models: triphones – discriminative training – speech recogn	itior	ר by		
humans					
	TOTAL	: 4	5 PE	RIC	DS
REFERENC					
	el Jurafsky and James H. Martin, — Speech and Language Processing: An				i to
	ral Language Processing, Computational Linguistics and Speech Recognition	on,	Pers	on	
	ation,2013.	<u> </u>			<u>.</u>
	Fu Lee, —Automatic Speech Recognition, The Springer International Series	in E	ngir	neer	ing
and	Computer Science, 1999.				

3.	Hi	mans	hu Cł	naura	siya, -	-Soft	Com	puting	g Impl	lemen	itation	of Auto	omatic	Speech	Recogni	tion,
	LA	AP La	mbert	Acad	lemic	Publi	shing	2010	).							
4.	CI	audio	Becc	hetti,	Kluci	o Prin	a Ric	otti, —	-Spee	ech Re	ecogni	tion: T	neory a	and C++		
	im	plem	entati	on.Wi	lev pu	ublicat	tions 2	2008.								
5.		•								eech l	Recoa	nition	Wilev	oublicatio	ons , 201	1
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COUR			COM	Ee												
Upon	con	npletio	on of t	the co	ourse,	stude	ents w	ill be	able t	0						
CO1	Cr	eate	new a	lgorit	nms v	vith sp	beech	proce	essing	3						
CO2	De	erive r	new s	peecł	n mod	els										
CO3	Pe	erform	vario	ous la	nguag	e pho	onetic	analy	/sis							
CO4	Cr	eate	a new		ch ide	entific	ation	svste	m							
CO5				-				-								
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COs	5	РО	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO1	PSO2	PSO3
		1	2	3	4	5	6	7	8	9	10	11	12	F301	F302	F303
C01		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	\$	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5	5	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

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OBJECTI	VES												0	U	U	0
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2. Sir	ngiresu S	Rao, "	Engin	eerin	g Opti	mizat	ion", \	Niley,	1998.							
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TEXT BC           1. Pradip           2018           REFERE           1. P           2. IT           C           3. S           4. N           COURSE           Upon co           CO1 A           CO2 P           CO3 P           CO4 A           CO5 M           CO5 CO1	DOKS         DOKS         D Kuma         D Kuma         Paolo B         Paolo B         Paolo B         Chen, J         Sussma         Nationa         Chen, J         Sussma         Nationa         Chen, J         Sussma         Nationa         Poll         1         1	ar Sar <b>BOOK</b> aggar d Boc ohn M an, J. N al ITS <b>COME</b> ion of ion of	kar, kar, kar, so, "Ir ok 20 liles. M., Pe Archi ictive affic sues Po3 2 2	Amit Intellig 000: I erspe itectu s type e ATI route data a arisin M PR( PO4 2 2	Kuma ent tra Recor ctive of re Doo se, stu es of t S. guida and al ng out APPI OGR/ PO5 1	r Jair anspo nmen on ITS cume udent raffic ance s ole to t of in NG O	n, "Into ort System dation S, Arte ntatio and s system sugge troduce <b>F CO</b>	elliger stems ns for ech H n, US l be a ugges m est su ction c s WIT DMES PO8 1 1	ouse Depa ble to sting I itable of ITS <b>H PC</b> (POs 1 1	nsport d pract d ract d Roa Publisi artmen TS. TS. DS ANI S) PO10 1 1	ices to ad Ass hers, 2 t of Tra t of Tra D PSO	ms", P standa sociatio 005. ansport s s P012 1 1	ards",CR on (PIAF ation, 20 PROG PSO1 2 2		ress, by K 1 SP DME 2 2	20 an EC	16. Pau
TEXT BC         1. Pradip         2018         REFERE         1. P         2. IT         CO         3. S         4. N         COURSE         Upon co         CO1         CO2         P         CO3         P         CO4         A         CO5         M         CO5         CO1         CO2         CO3         CO4         A         CO5         CO1         CO3         CO3         CO3         CO3         CO3         CO3         CO3         CO3         CO3         CO3	ENCE E Paolo B FSHan Chen, J Sussma Nationa E OUT Malyze Pan and lan the nalyze lan and lan the nalyze lan age	ar Sar aggar d Boc ohn M an, J. N al ITS COME ion of the va d desir predi the tr the tr the tr the tr the is Po2 2 2 2 2	kar, kar, kar, so, "Ir ok 20 Archi ariou: gn th ctive affic ssues Pos 2 2 2	Amit I Intellig 000: I erspe itectul cours s type e ATI route data a arisin M PR( PO4 2 2 2	Kuma ent tra Recor ctive o re Doo se, str e guida and al ng out APPI OGRA PO5 1 1 1	r Jair anspo nmen on ITS cume udent raffic ance s ole to t of in NG O	n, "Into ort System dation S, Arte ntatio and s system sugge troduce <b>F CO</b>	elliger stems ns for ech H n, US l be a ugges m est su ction c s WIT DMES PO8 1 1 1	Good Good Wor ouse Depa ble to sting I itable of ITS <b>H PC</b> (POs PO9 1 1 1	nsport d pract d Roa Publisl artmen TS. DS ANI 5) Po10 1 1 1	ices to ad Ass hers, 2 t of Tra of Tra DPSO PO11 1 1 1	ms", P standa sociatio 005. ansport s P012 1 1 1 1	ards",CR on (PIAF tation, 20 PROG PROG 0 PSO1 2 2 2	2C pi RC)k 007	ress, oy K 1 SP DME 602 2 2 2	20 an EC	16. Pau
TEXT BC         1. Pradip         2018         REFERE         1. P         2. IT         C         3. S         4. N         COURSE         Upon co         CO1       A         CO2       P         CO3       P         CO4       A         CO5       M         CO3       CO5         CO5       M         CO5       CO1	DOKS         DOKS         D Kuma         D Kuma         Paolo B         Paolo B         Paolo B         Chen, J         Sussma         Nationa         Chen, J         Sussma         Nationa         Chen, J         Sussma         Nationa         Poll         1         1	ar Sar <b>BOOK</b> aggar d Boc ohn M an, J. N al ITS <b>COME</b> ion of ion of	kar, kar, kar, so, "Ir ok 20 liles. M., Pe Archi ictive affic sues Po3 2 2	Amit Intellig 000: I erspe itectu s type e ATI route data a arisin M PR( PO4 2 2	Kuma ent tra Recor ctive of re Doo se, stu es of t S. guida and al ng out APPI OGR/ PO5 1	r Jair anspo nmen on ITS cume udent raffic ance s ole to t of in NG O	n, "Into ort System dation S, Arten ntatio System suggetroduce F CO UTCC P07 - -	elliger stems ns for ech H n, US l be a ugges m est su ction c s WIT DMES PO8 1 1	ouse Depa ble to sting I itable of ITS <b>H PC</b> (POs 1 1	nsport d pract d ract d Roa Publisi artmen TS. TS. DS ANI S) PO10 1 1	ices to ad Ass hers, 2 t of Tra t of Tra D PSO	ms", P standa sociatio 005. ansport s s P012 1 1	ards",CR on (PIAF ation, 20 PROG PSO1 2 2	2C pi RC)k 007	ress, by K 1 SP DME 2 2	20 an EC	16. Pau

ML1725	ADVANCED BIO-INSPIRED ARTIFICIAL INTELLIGENCE TECHNIQUES	L	Т	Ρ	C
		3	0	0	3
OBJECTIVES					
-	knowledge on				
	eciate the use of biological aspects in building intelligent systems				
	erstand the algorithms, programming and applications of Evolutionary	and	gen	etic	
	s and neural and fuzzy systems				
	eciate the adaptation of cellular and developmental systems	_			
	s on the understanding of artificial immune systems and its application	IS			
	erstand issues in developing collective and behavioral systems				
	VOLUTIONARY SYSTEMS	a:+: a		2	)
	prithm, components of evolutionary algorithm representation (define				
	uation function (Fitness function), Population, parent selection Mecors, Survivor Selection Mechanism (Replacement), Initialization, Terr				
	onary algorithm case study Cellular systems, cellular automata, mode				CO1
	other cellular systems, computation with cellular systems, artifi				
-	nesis of cellular systems.	ciai	me.		
	EURAL AND DEVELOPMENTAL AND IMMUNE SYSTEMS			ç	
	s systems, artificial neural networks, neuron models, architecture	s ci	anal	_	•
	tic plasticity, unsupervised learning, supervised learning, reinfo				
	of neural networks, hybrid neural systems, Rewriting system, syn			:	
	stem, evolutionary rewriting systems, evolutionary developmental pr				CO2
	e systems, lessons for artificial immune systems, algorithms and appl				
	ative selection algorithm, clonal selection algorithm. case study.		,		
	EHAVIORAL SYŠTEMS			Ģ	)
Behavior is cognit	tive science, behavior in AI, behavior based robotics, biological inspir	atio	n for	·	
	biological models, robot learning, evolution of behavioral systems, lea				
behavioral system	ns, co-evolution of body and control, towards self-reproduction, simula	tion	and		CO3
reality					
UNIT IV G	ENETIC AND MEMETIC ALGORITHMS			g	)
-	Individuals, Mutation, Recombination, Population Models, Parent Sel	ectio	on.		
	n, Example Application: Solving a Job Shop Scheduling Problem. Intro				
	Lamarckianism and the Baldwin Effect, Structure of a Memetic Al				
-	elligent Initialization, Hybridization within Variation Operators: Ir	•	-		CO4
	Mutation, Local Search Acting on the output from Variation O				
,Hybridization Du	iring the Genotype to Phenotype Mapping, Design Issues for I	Men	netic	;	
Algorithms.					
	OLLECTIVE SYSTEMS			Ş	•
	anization, Particle Swarm Optimization (PSO), ant colony optimizatior				
	co-evolutionary dynamics, artificial evolution of competing systems,	arti	ficia		CO5
	eration, case study.				
TOTAL : 45 PER	ODS				
TEXT BOOKS					
	d C. Mattiussi, "Bio-Inspired Artificial Intelligence", MIT Press, 2008.				
	Zheng, Mou Ling Dennis Wong, Xun Wang, "Bio-Inspired Compu	iting	IVIO	del	s and
	: 978-981-3143-19-7, world scientific, 2019				al the alim
	d C. Witt, "Bioinspired Computation in combinatorial optimization: Alg	oritr	ims	ano	a their
	nplexity", Springer, 2010.				
REFERENCE BO	OKS				
	dberg, "Genetic algorithms in search, optimization, and machine lea	arnir	ıg",	Ad	dison-
Wesley, 1			<u> </u>		
	Haykin, "Neural Networks and Learning Machines", Third Edition, Prei	ntice	e Ha	II, 2	2008.
	and T. Stutzle, "Ant Colony Optimization", A Bradford Book, 2004.				
4. R. C. Ebel	hart, "Swarm Intelligence", Morgan Kaufmann, 2001.				

5. Xin-She Yang,Zhihua Cui Renbin Xiao Amir HosseinGandomi Mehmet Karamanoglu "Swarm Intelligence and Bio-Inspired Computation", 1st Edition, Elsevier, 2013.

COUR	-			-												
Upon	con	nplet	tion o	f the	cours	se, sti	udent	ts wil	l be a	ble to	)					
CO1	Us	e exi	sting	open	sourc	e tool	s to b	uild a	n app	licatio	on usin	g gene	etic ap	proaches		
CO2	Ide	entify	differ	ent ap	oplica	tions s	suitab	le for	differ	ent ty	pes of	neural	netwo	orks givin	g justific	ations
CO3	Cri	iticall	y ana	lyze tl	he us	e of ce	ellular	· syste	ems							
CO4	Dif	ferer	, ntiate	the di	fferen	t mod	els of	immu	une sv	vstem	S					
CO5										/		thms	within	a fram	ework a	nd build
		plicat								,						
					Ν	ΙΑΡΡ							<b>)</b> _			
								JF UU	JS VVI		US AN	DFOU	JS			
												DF3C	5	PROG		PECIFIC
	_									(POs		DFSC	78			
COs	5	PO	PO	PO								PO	PO	(		ES
COs	5	P0 1	PO 2	PO 3	PR	OGRA	AM O	UTCC	MES	(POs	5)	1				
COs CO1		<b>PO</b> 1 2		-	PR PO	OGRA PO	AM O PO	UTCC	MES PO	(POs PO	5)   PO	PO	РО	(		ES
		1	2	3	PR PO 4	OGRA PO	AM O PO	UTCC	PO 8	(POs PO 9	5)   PO	PO	РО	PSO1	DUCOMI PSO2	ES PSO3
C01	2	1 2	<b>2</b>	<b>3</b> 2	<b>PR</b> <b>PO</b> <b>4</b> 2	OGRA PO	AM O PO	UTCC	<b>PO</b> 8	(POs PO 9 1	5)   PO	PO	РО	<b>PSO1</b>	PSO2	<b>PSO3</b>
C01 C02	 2 3	1 2 2	<b>2</b> 2 2	<b>3</b> 2 2	PR PO 4 2 2	OGRA PO	AM O PO	UTCC	<b>PO</b> 8 1	(POs 9 1	5)   PO	PO	РО	<b>PSO1</b> 2 2	PSO2	<b>PSO3</b> 2 2 2

# PROFESSIONAL ELECTIVE – V (SEMESTER VIII)

ML1811	VIDEO ANALYTICS L T	PC
OBJECTIVE	<u> </u>	03
	part knowledge on	
	know the fundamental concepts of big data and analytics	
	learn various techniques for mining data streams	
	acquire the knowledge of extracting information from surveillance videos.	
	learn Event Modelling for different applications.	
	understand the models used for recognition of objects in videos	
UNITI	INTRODUCTION TO BIG DATA & DATA ANALYSIS	9
	to Big Data Platform – Challenges of Conventional systems – Web data- Evolution	
•	scalability- analytic processes and tools- Analysis Vs Reporting- Modern data	C01
analytic tools	Data Analysis: Regression Modeling- Bayesian Modeling- Rule induction	
UNIT II	MINING DATA STREAMS	9
Introduction	to Stream concepts- Stream data model and architecture - Stream Computing-	
Sampling da	ata in a Stream- Filtering Streams- Counting distinct elements in a Stream-	000
Estimating n	nomentsCounting oneness in a window- Decaying window- Real time Analytics	CO2
platform(RTA	AP) applicationscase studies.	
UNIT III	VIDEO ANALYTICS	9
Introduction-	Video Basics - Fundamentals for Video Surveillance- Scene Artifacts- Object	
Detection an	d Tracking: Adaptive Background Modelling and Subtraction- Pedestrian Detection	
and Tracking	gVehicle Detection and Tracking- Articulated Human Motion Tracking in Low-	CO3
Dimensional	Latent Spaces.	
UNIT IV	BEHAVIOURAL ANALYSIS & ACTIVITY RECOGNITION	9
Event Mode	elling- Behavioural Analysis- Human Activity Recognition-Complex Activity	
Recognition/	Activity modelling using 3D shape, Video summarization, shape based activity	CO4
models- Sus	picious Activity Detection.	
	HUMAN FACE RECOGNITION & GAIT ANALYSIS	9
	Overview of Recognition algorithms – Human Recognition using Face: Face	
	from still images, Face Recognition from video, Evaluation of Face Recognition	
•	s- Human Recognition using gait: HMM Framework for Gait Recognition, View	CO5
•	t Recognition, Role of Shape and Dynamics in Gait Recognition	
TOTAL : 45		
TEXT BOOK		
	d Rajaraman and Jeffrey David Ullman, Mining of Massive Datasets, Cambridge	
	ersity Press, 2012.	
بالصا ا		

2. Michael Berthold, David J.Hand, Intelligent Data Analysis, Springer, 2007.

# **REFERENCE BOOKS**

- 1. Rama Chellappa, Amit K.Roy-Chowdhury, Kevin Zhou.S, "Recognition of Humans and their Activities using Video", Morgan&Claypool Publishers, 2005.
- 2. Yunqian Ma, Gang Qian, "Intelligent Video Surveillance: Systems and Technology", CRC Press (Taylor and Francis Group), 2009.

COUF	RSE	OUT	COM	ES												
Upon	COI	mplet	ion o	f the	cours	se, sti	udent	ts will	l be a	ble to	)					
CO1	W	ork w	ith big	g data	platfo	orm ai	nd its	analy	sis te	chniq	ues					
CO2	De	esign	efficie	ent alg	gorithr	ns for	<sup>.</sup> minir	ng the	e data	from	large v	olume	s.			
CO3	W	ork w	ith su	rveilla	nce v	ideos	for a	nalytic	cs.							
CO4	De	esign	of opt	timiza	tion a	lgorith	nms fo	or bet	ter an	alysis	and re	ecognit	tion of	objects i	n a scen	e.
CO5	M	odel a	fram	ework	k for ⊦	lumar	n Acti	vity R	ecogr	nition				-		
					Μ	APPI	NG O	F CO	s WI1	ГН РС	)s ANI	D PSO	s			
					DD				MES		•)			PROG	RAM SP	ECIFIC
COs					FK	UGRA				(FUS	•)			0	UCOME	S
	2	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO1	PSO2	PSO3
		1	2	3	4	5	6	7	8	9	10	11	12	F301	F 302	F303
CO1	1	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2	2	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	3	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4	4	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
COS	5	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2

	BLOCKCHAIN ARCHITECTURE DESIGN	T	
OBJECTIVES	3 0	0	) 3
• To und	erstand Blockchain's fundamental components, and examine decentralization u	sing	]
blockch	ain.	-	
<ul> <li>To exp</li> </ul>	lain how cryptocurrency works, from when a transaction is created to when it• i	S	
conside	ered part of the Blockchain.		
<ul> <li>To expl</li> </ul>	ain the components of Ethereum and Programming Languages for Ethereum.		
To stu	idy the basics of Hyperledger and Web		
	w about alternative Blockchains and Blockchain projects in different domains.		
UNIT I	Introduction to Blockchain		
Digital Money	to Distributed Ledgers , Design Primitives: Protocols, Security, Consensu	S,	
Permissions,	Privacy. Blockchain Architecture and Design: Basic crypto primitives: Has	n,	CO
Signature,) Ha	shchain to Blockchain, Basic consensus mechanisms		
UNIT II	Consensus		
Requirements	for the consensus protocols, Proof of Work (PoW), Scalability aspects of	Τ	
Blockchain cor	nsensus protocols		CO
Permissioned	Blockchains:Design goals, Consensus protocols for Permissioned Blockchains		
UNIT III	Hyperledger Fabric		1
Hyperledger	Fabric (A): Decomposing the consensus process , Hyperledger fab	ic	
components,	Chaincode Design and Implementation Hyperledger Fabric (B): Beyor	d	CO:
•	Chaincode Design and Implementation Hyperledger Fabric (B): Beyor pric SDK and Front End (b) Hyperledger composer tool	d	CO:
•		d	
Chaincode: fat			
Chaincode: fat UNIT IV Use case 1 : B	pric SDK and Front End (b) Hyperledger composer tool	ii)	
Chaincode: fat UNIT IV Use case 1 : B Capital market	oric SDK and Front End (b) Hyperledger composer tool	ii)	
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B	oric SDK and Front End (b) Hyperledger composer tool	ii)	
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp	ii)	
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance,	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp	ii)	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3:	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp	ii) ly	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3: Blockchain for	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp invoice management discounting, etc	ii) ly	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3: Blockchain for between gover	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp invoice management discounting, etc	ii) ly	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3: Blockchain for between gover	bric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp invoice management discounting, etc Government: (i) Digital identity, land records and other kinds of record keeping mment entities, (ii) public distribution system social welfare systems Blockchain	ii) ly	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3: Blockchain for between gover	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp invoice management discounting, etc Government: (i) Digital identity, land records and other kinds of record keeping ment entities, (ii) public distribution system social welfare systems Blockchain Privacy and Security on Blockchain <b>TOTAL : 45 F</b>	ii) ly	CO4
Chaincode: fat UNIT IV Use case 1 : B Capital market Use case 2: B chain finance, UNIT V Use case 3: Blockchain for between gover Cryptography,	oric SDK and Front End (b) Hyperledger composer tool lockchain in Financial Software and Systems (FSS): (i) Settlements, (ii) KYC, (i s, (iv) Insurance lockchain in trade/supply chain: (i) Provenance of goods, visibility, trade/supp invoice management discounting, etc Government: (i) Digital identity, land records and other kinds of record keeping ment entities, (ii) public distribution system social welfare systems Blockchain Privacy and Security on Blockchain <b>TOTAL : 45 F</b>	ii) ly	CO4

- **3.** Hyperledger Fabric https://www.hyperledger.org/projects/fabric
- 4. Zero to Blockchain An IBM Redbooks course, by Bob Dill, David Smits -

https://www.redbooks.ibm.com/Redbooks.nsf/RedbookAbstracts/crse0401.html

# COURSE OUTCOMES

Upon completion of the course, students will be able to

CO1 Understand the technology components of Blockchain and how it works behind the scenes.

CO2 | Identify different approaches to developing decentralized applications.

CO3 Understand Bitcoin and its limitations by comparing with other alternative coins.

CO4 Understand and use Hyperledger and its development framework

CO5 | Track alternative Blockchains and emerging trends in Blockchain.

				M	APPI	NG O	F CO	s WI	TH PC	)s AN[	D PSO	S			
COs				PR	OGRA				RAM SP						
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	2	2	2	2	1	-	-	1	2	2	1	1	2	2	2
CO2	2	2	2	2	1	-	-	1	2	2	1	1	2	2	2
CO3	2	2	2	2	1	-	-	1	2	2	1	1	2	2	2
CO4	2	2	2	2	1	-	-	1	2	2	1	1	2	2	2
CO5	2	2	2	2	1	-	-	1	2	2	1	1	2	2	2

	MICROSOFT BOTS FRAMEWORK	, .	Т	С
	3 0	-	0	3
OBJECTIVES				
Devel	op various real-world intelligent BOTs from scratch using Microsoft Bot Frame	wor	ĸ.	
Unde	rstand the components of Bot Architecture			
Build	Bots to parse the text and voice			
Create	e intelligent Bots using APIs			
<ul> <li>Integra</li> </ul>	ate BOTSs with most popular conversation platforms			
UNIT I	BOT INTRODUCTION & BUILDING CONVERSATION			8
Overview –E>	<pre>cploring BOT framework architecture –BOT chat benefits –Visualizing chatbo</pre>	ts		
,connector –	overview of channels -Bot connector services-characteristics of chatbo	ot-		
chatbot comm	nunication-steps to build c hatbotcreating Bot framework project -examinir	ng	С	<b>م</b>
default code	-iinitial testing with Emulator -Publishing and registering chatbot-Game Bo	ot-		
conversation	state Management -participating in conversations-using custom message	je		
activity – fine	tuning chat bot –Handling activities –Advanced conversation messages			
UNIT II	BOT BUILDER			5
Building dialo	gs -Introducing wine Bot -implementing dialog class -dialog c onversation	fl		
ow- dialog p	rompt options -calling dialog using Form Flow- basic form flow chat	-	С	02
enhancing for	m flow conversati ons – a dvanced templates and patterns -customizing For	m	-	
•	ing property –message method and common parameters .			
UNIT III	NATURAL LANGUAGE PROCESSING WITH LUIS			8
Learning es	sential LUIS concepts -creating models -building intents -introducir	ng		
	handling entities – Managing advanced conversation –managing dialog stack		C	03
	a the shell all and the second state and the shell of the shell she shell all all she to the shell she she she	m		
navigating to	other dialogs-managing c onversations with chaining –wine bot chain progra			
navigating to –LINQ to dialo	og –formatting text output			8
navigating to –LINQ to diale <b>UNIT IV</b>	og –formatting text output CHANNELS AND GUI			
navigating to –LINQ to diale <b>UNIT IV</b> Attaching care	og –formatting text output CHANNELS AND GUI ds –Music chat BOT overview –building blocks-working wi th a ttac hments –	di		
navigating to –LINQ to diale <b>UNIT IV</b> Attaching care splaying c are	og –formatting text output          CHANNELS AND GUI         ds –Music chat BOT overview –building blocks-working wi th a ttac hments –         ds – adaptive cards –layout with containers –using controls –handling actions	di	C	04
navigating to –LINQ to dialo <b>UNIT IV</b> Attaching card splaying c ard configuring ch	og –formatting text output CHANNELS AND GUI ds –Music chat BOT overview –building blocks-working wi th a ttac hments – ds – adaptive cards –layout with containers –using controls –handling actions hannels –creating email , SMS and Web Bots	di	C	
navigating to –LINQ to dialo <b>UNIT IV</b> Attaching card splaying c ard configuring ch	og –formatting text output         CHANNELS AND GUI         ds –Music chat BOT overview –building blocks-working wi th a ttac hments –         ds – adaptive cards –layout with containers –using controls –handling actions         nannels –creating email , SMS and Web Bots         APIS INTEGRATION AND VOICE	di –	C	
navigating to –LINQ to diale <b>UNIT IV</b> Attaching care splaying c are configuring ch <b>UNIT V</b> Coding custo	og -formatting text output         CHANNELS AND GUI         ds -Music chat BOT overview -building blocks-working wi th a ttac hments -         ds - adaptive cards -layout with containers -using controls -handling actions         hannels -creating email , SMS and Web Bots         APIS INTEGRATION AND VOICE         m channels - overview of console channel -starting conversation - sendir	di —	C	
navigating to –LINQ to diale <b>UNIT IV</b> Attaching care splaying c are configuring ch <b>UNIT V</b> Coding custo activities - e	og -formatting text output         CHANNELS AND GUI         ds -Music chat BOT overview -building blocks-working wi th a ttac hments -         ds - adaptive cards -layout with containers -using controls -handling actions         hannels -creating email , SMS and Web Bots         APIS INTEGRATION AND VOICE         m channels - overview of console channel -starting conversation - sendir         nding conversation - integrating cognitive services -searching with Bin	di – ng g-		04 
navigating to –LINQ to diale <b>UNIT IV</b> Attaching care splaying c are configuring ch <b>UNIT V</b> Coding custo activities - e interpreting ir	og -formatting text output         CHANNELS AND GUI         ds -Music chat BOT overview -building blocks-working wi th a ttac hments -         ds - adaptive cards -layout with containers -using controls -handling actions         hannels -creating email , SMS and Web Bots         APIS INTEGRATION AND VOICE         m channels - overview of console channel -starting conversation - sendir	di – ng g-		8

TEXT	BOO	эк														
1.	Joe	Ма	ayo,"F	Progra	immir	ng the	e Mici	rosoft	BOT	S fra	mewor	k : A	multip	le Appro	ach to b	ouilding
	cha	tbot	:s" ,P€	ea rso	on Ed	ucatio	on Inc	.,201	8							
REFE	REN	CE	BOO	KS												
		-		_												
						-									Publishir	ig Ltd
				-				-	•					amework		
Cre	eate	Inte	elligen	t Bot	s usin	g MS	Bot F	Frame	ework	and /	Azure	Cognit	ive Se	rvices",A	A Press,2	2017
COUR	SE C	τυς		IES												
Upon	com	plet	tion o	of the	cour	'se, s	tuder	nts w	ill be	able	to					
CO1	Und	lerst	tand t	he ar	chited	cture (	of Bot	and	build	the co	onvers	ation				
CO2	Build	d di	alogs	and	form f	low										
CO3	Iden	ntify	the ir	ntent	of a te	ext wi	th the	help	of LU	IIS						
CO4	Ana	lyze	e the i	ssue	s of cl	hanne	els an	d crea	ate Ei	mail ,	SMS a	and W	eb Bot			
CO5	Und	lerst	tand t	he Al	Pls ar	nd inte	egrate	e cogr	nitive	servio	es &v	oice se	ervices	;		
					M	APPII	NG O	F CO	s WI	ГН РС	)s AN	D PSC	s			
														Р	ROGRA	М
					PRC	OGRA		UTCC	MES	(POs	5)				SPECIFI	
COs										•				О	UCOME	S
	F	ю	РО	РО	РО	РО	РО	РО	РО	РО	PO1	PO1	PO1	PSO	PSO2	
		1	2	3	4	5	6	7	8	9	0	1	2	1	F302	PSO3
CO1		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5		2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

ML1814	BUSINESS INTELLIGENCE	L	Т	Ρ	С
		3	0		3
DBJECTIVES		-		-	-
То					
•	Be exposed with the basic rudiments of business intelligence system				
•	understand the modeling aspects behind Business Intelligence				
•	understand of the business intelligence life cycle and the techniques use	d in	it		
•	Be exposed with different data analysis tools and techniques				
	Business intelligence			g	)
	ligence: Effective and timely decisions, Data, information and knowled	ae.	The		
	ematical models, Business intelligence architectures, Ethics and b				
ntelligence					
•	port systems: Definition of system, Representation of the decision	-ma	kina		CO1
	ition of information systems, Definition of decision support system, Deve		-		
	upport system	iopi			
JNIT II	Mathematical models for decision making			9	)
	models for decision making: Structure of mathematical models, Developm	nent	of a	_	
nodel, Classe					
,	Definition of data mining, Representation of input data, Data mining r	oroc	ess.		CO2
Analysis meth			,		
	on: Data validation, Data transformation, Data reduction				
	Classification			Ģ	)
	Classification problems, Evaluation of classification models, Bayesian m	neth	ods.		
	sion, Neural networks, Support vector machines.		,		
	lustering methods, Partition methods, Hierarchical methods, Evalua	atior	n of		CO3
clustering mod	•				
	Business intelligence applications			Ģ	)
Business inte	lligence applications: Marketing models: Relational marketing, Sale	s f	orce		
management					
	roduction models: Supply chain optimization, Optimization models for	logi	stics		~~ 4
	enue management systems.	U			CO4
Data envelop	ment analysis: Efficiency measures, Efficient frontier, The CCR	mo	odel,		
	f good operating practices				
UNIT V	Knowledge Management			Ģ	)
Knowledge M	anagement: Introduction to Knowledge Management, Organizational L	ear	ning		
	mation, Knowledge Management Activities, Approaches to Knowledge				
			edge		
	Systems Implementation, Roles of People in Knowledge Management.		-		<u>م</u>
	gence and Expert Systems: Concepts and Definitions of Artificial Intel	llige	nce,		CO5
	igence Versus Natural Intelligence, Basic Concepts of Expert S				
Applications	of Expert Systems, Structure of Expert Systems, Knowledge Engi	nee	ring,		
Development	of Expert Systems				
TOTAL : 45 P	ERIODS				
TEXT BOOKS					
1. Carlo \	/ercellis ,Business Intelligence: Data Mining and Optimization for Decisior	n Ma	aking	g, V	Viley
-4					
1 <sup>st</sup> ,2009					
REFERENCE					
1. Efraim	Turban, Ramesh Sharda, Dursun Delen ,Decision support and Busin	ess	Inte	ellig	jenc
System	ns, Pearson,Edition 9 <sup>th</sup> ,2011				
-	nann W, Rinderle-Ma, Fundamental of Business Intelligence, Springer, Edi	tion		1 <sup>s</sup>	t_
2015				•	,
2015					

COURSE		COM	FS														
Upon co			-	cours	se. st	udent	ts will	l be a	ble to	)							
	xplain									-							
	•							<u> </u>		oly var	ious m	odeling	g technic	ues			
	xplain																
							ls to v	arious	s situa	ations.							
CO5 D	ecide	on ap	propr					c \//IT			D PSO	<u> </u>					
COs											5-30	5	PROG		1 SPE OME		IC
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	P011	PO12	PSO1	PS	602	PS	03
CO1	1	2	2	2	1	-	-	1	1	1	1	1	2		2	2	2
CO2	1	2	2	2	1	-	-	1	1	1	1	1	2		2	2	
CO3	1	2	2	2	1	-	-	1	1	1	1	1	2		2	2	
CO4																	
CO5	1	2	2	2	1	-	-	1	1	1	1	1	2		2	2	2
MG1815					SL	JPPL'	Y CH			GEME	NT			L	Ρ	т	С
		l												3	0	0	3
UNIT I Supply ( Enablers Performa UNIT II Distribut sales an influenci	s & C ance N ion Ne d distr	– Fu Drivers Aeasu <b>SUF</b> etwork	ndam s of ires. PPLY c Desion net	Suppl CHA ign – work,	s, Evo y Ch IN NE Role Distri	ain F <b>TWO</b> in sup ibutio	Perforr RK oply c n Stra	hain,	e; Su Influe s; Net	pply of ncing	factors Design	strateg s, desig in sup	y; Supp n optior ply chai	ly () ns, c n – 1	Chain Inline Role,	c	0 <sup>2</sup>
UNIT III		PLA	NNIN	IG DE	EMAN	D, IN	VENT	ORY	AND	SUPP	ĽΥ						
Managin , Analyzi for short Revenue	ng im life-cy	oact c vcle pr	of sup roduc ent	ply ch ts, mi	ain re	edesig	n on	the in	vento	ry, Ris	k Pool	ing, Ma	anaging	inve	ntory	C	03
UNIT IV		LOC	GISTI	CS													9
Transpo	rtation	– Ro	le, Mo	odes a	and th	eir ch	naract	eristic	s, infr	astruc	ture ar	nd polic	cies, tran	spo	rt		
	ntation	, des	ign o	ptions	s, trac	le-off	s in tr	anspo	ortatio	n des	ign, in	termod	al trans	porta	ation.		
docume					to ho	nofite	valu	e pror	oositic	on. 3Pl	4PI	5PI (	DI · Into	rnat	lanal		
docume Logistics	outso	ourcin	g – ca	atalys	is, be	nemo	, vaiu				_,	JI L, V	DFL, IIIte	ma	lonal	-	~
Logistics			•	•				• •									04
	obje		•	•				• •									04

UNIT	V		SUP	PLY	CHAI	N INN	IOVA <sup>.</sup>	TION	S							9
Suppl	y Cl	hain I	ntegra	ation,	SC p	roces	s resti	ructur	ing, I	Γ in S	upply (	Chain;	Agile S	Supply C	hains,	
Legibl	le si	upply	chain	, Gree	en Su	pply (	Chain,	Reve	erse S	Supply	, chain	; Supp	ly chai	in techno	logy	CO5
trends	s – A	AI, Ad	lvance	ed ana	alytics	s, Inte	rnet o	f Thin	igs, In	tellige	ent thin	ngs, co	nversa	ational sy	stems,	005
roboti	c pr	ocess	s auto	matio	n, imr	nersiv	/e tec	hnolo	gies,	Block	chain.					
														TOTAL	. : 45 PE	RIODS
REFE	RE		BOOI	KS												
1.	Su	unil Cl	hopra	, Pete	er Mei	ndl ar	nd Dha	aram	√irKal	ra, Su	ipply C	Chain N	/lanage	ement-St	rategy P	lanning
	ar	nd Op	eratio	n, Pe	arson	Educ	ation,	Sixth	n Editi	on, 20	016.					
2.	Ja	anat S	hah,	Suppl	y Cha	ain Ma	inagei	ment	– Tex	t and	Cases	s, Pear	son Ec	ducation,	2009	
3.	Ba	allou F	Ronal	d H, E	Busine	ess Lo	gistic	s and	Supp	ly Ch	ain Ma	nagen	nent, F	Pearson E	Educatio	٦,
	5t	hEditi	on, 20	007.												
4.	Da	avid	Simc	hi-Lev	ri, Pł	nilip l	Kamir	nsky,	Edith	n Sin	nchi-Le	evi, D	esignii	ng and	Managi	ng the
	Su	upply	Chain	: Con	cepts,	Strat	egies	, and	Case	s, Tat	a McG	iraw-H	ill, 200	5.		
5.	Pi	erre D	David,	Inter	natior	al Lo	gistics	s, Bizt	antra,	, 2011	•					
COUF	RSE	OUT	СОМ	ES												
Upon	COI	mplet	tion o	of the	cours	se, st	udent	s will	l be a	ble to	)					
CO1	Ur	nderst	tandir	ng of s	supply	chair	n fund	lamer	ntals							
CO2	At	oility to	o des	ign su	ipply o	chain	netwo	orks to	o enha	ance s	supply	chain	perforr	nance		
CO3	At	oility to	o plar	n dem	and b	ased	on inv	/entor	y and	l supp	ly					
CO4	Ur	nderst	tandir	ng the	role o	of logi	stics i	n sup	ply ch	nain p	erform	ance				
CO5	Av	waren	ess o	f inno	vatior	ns for	susta	inable	e supp	oly cha	ains					
					Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S			
										(DO-	、			PROG	RAM SP	ECIFIC
00					PR	UGRA	AIVI OU			(POs	5)			0	UCOME	S
COs	5	РО	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO		DEOD	DCO2
		1	2	3	4	5	6	7	8	9	10	11	12	PSO1	PSO2	PSO3
CO1	1	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
	•					1		ļ		<u> </u>		1	1			
CO2		1	2	2	2	1	-	-	1	1	1	I		2	2	2
	2	1	2 2	2 2	2 2	1 1	-	-	1 1	1	1	1	1	2 2	2 2	2 2
CO2	2 3	-				-				-	•					

# PROFESSIONAL ELECTIVE - VI (SEMESTER VIII)

r					
ML1821	INTERNET OF EVERYTHING	L	Т	Ρ	С
		3	0	0	3
OBJECTIVES	the fundamental concerns and configure of the T				
	the fundamental concepts and applications of IoT				
	nerate the enabling technologies for IoT				
	<ul> <li>analyze and design evolving standards of IoT</li> <li>bre IpV6 technologies for IoT</li> </ul>				
-					
	python programming for designing IoT applications IOT INTRODUCTION AND APPLICATIONS				9
	Motivations - IPv6 Role - IoT Definitions - Observations - ITU-T Views -		king	1	9
	Frameworks - Basic Nodal Capabilities – Physical Design of IoT -				
	- Applications Examples -Smart Metering/Advanced Metering Infrastru				
	rea Networks - City Automation - Automotive Applications - Home Auto			С	01
	-Tracking (Following and Monitoring Mobile Objects) - Over-The-Ai				
	ng of Steel -Control Application Examples	n uu	0110		
our follarioo, ra					
UNIT II	FUNDAMENTAL MECHANISMS AND KEY TECHNOLOGIES				9
	of IoT Objects and Services -Structural Aspects of the IoT - Env	ironr	nent		
	- Traffic Characteristics – Scalability – Interoperability -Security and I				
	ure - Key IoT Technologies - Device Intelligence -Communication Capa			С	02
Mobility Supp	prt - Device Power - Sensor Technology - RFID Technology -	Sate	ellite	-	
	oT Enabling Technologies	•••••	••		
UNIT III	EVOLVING IOT STANDARDS				9
IETF IPv6 Ro	uting Protocol for RPL Roll – Constrained Application Protocol (C	CoAF	- (C		
	al State Transfer (REST) – ETSI M2M – Third-Generation Partnership				
	rements for Machine-Type Communications - CENELAC – IETF IP			С	<b>O</b> 3
	AN (6LoWPAN) – ZigBee IP (ZIP) – IP in Small Objects (IPSO)				
	or IoT/M2M -Cellular and Mobile Network Technologies for IoT/M2M				
UNIT IV	IPV6 TECHNOLOGIES FOR THE IOT				9
	Address Capabilities -IPv6 Protocol Overview -IPv6 Tunneling - IPsec				
Header Compi	ession Schemes - Quality of Service in IPv6 - Migration Strategies t	o IP	'v6 -		
Protocol Detail	s - Generic Mechanisms - New IPv6 Protocol - Message Types - De	stina	ation		
Option - Modif	ications to IPv6 Neighbor Discovery - Requirements for Various IPv6	Nod	les -	С	04
	Node Operation - HA Node Operation - Mobile Node Operation Relation				
	v4 (MIP) - IPv6 Over Low-Power WPAN – Goals - Transmission of IPv6	Pac	kets		
Over IEEE 802	.15.4				
UNIT V	IPV6 DESIGN METHODOLOGY			1	9
	equirements Specification - Process Specification - Domain Model Spe				
	lodel Specification - Service Specifications - IoT Level Specification - Fu				
	ation - Operational View Specification - Device & Component Integ				
	velopment - Case Study on IoT System for Weather Monitoring – Logica				
	Python Packages of Interest for IoT - IoT Physical Devices and End			С	05
	Linux on Raspberry Pi - Raspberry Pi Interfaces - Programming Rasp				
	WAMP : AutoBahn for IoT - Xively Cloud for IoT - Python Web Ap				
	ango) - Designing a RESTful Web API - Amazon Web Services for IoT	- Sky	yNet		
IoT Messaging					<u> </u>
TEXT BOOKS	ΤΟΤΑΙ	<u>.:4</u> ;	D PE	RIO	05
	Minoli, Building the Internet of Things with IPv6 and MIPv6: The Evolving	1 \// ~	rld of	• • •	>\/
	inications, Wiley Publications, First Edition, 2013.	, ,,,,		1712	.171

- 1. ArshdeepBagha, Vijay Madisetti, Internet of Things: A Hands on Approach, Elsevier Publications, 2014
- Jean-Philippe Vasseur, Adam Dunkels, Interconnecting Smart Objects with IP: The Next Internet, Elsevier Publications, 2010
- 3. Adrian McEwen, Hakim Cassimally, Designing the Internet of Things, Wiley Publications, First Edition, 2013

## **COURSE OUTCOMES**

#### Upon completion of the course, students will be able to

CO1 Identify the applications of IoT

CO2 Apply key technologies for IoT objects and services

CO3 Interpret various IoT standards

CO4 Assemble IpV6 technologies that suits IoT applications

CO5 Design IoT applications using Python

### MAPPING OF COs WITH POS AND PSOS

COs				PR	OGR		UTCC	MES	(POs	;)			PROGRAM SPECIFIC OUTCOMES (PSOs)				
COS	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3		
CO1	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2		
CO2	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2		
CO3	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2		
CO4	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2		
CO5	3	3	3	3	2	-	-	-	-	2	2	2	3	3	2		

DS1821		P	C
OBJECTIVE		0	3
	ovide an understanding of the central challenges in realizing aspects of human cogr	nitio	n.
	ovide a basic exposition to the goals and methods of human cognition.		
•	velop algorithms that use AI and machine learning along with human interactio	n a	an
	ack to help humans make choices/decisions.		
	pport human reasoning by evaluating data in context and presenting relevant fir	ndir	ng
	with the evidence that justifies the answers.		Ű
Ū			
UNIT I	INTRODUCTION TO COGNITIVE SCIENCE		1
Understandin	g Cognition, IBM's Watson, Design for Human Cognition, Augmented Intelligence,		
Cognition Ma	deling Paradigms: Declarative/ logic-based computational cognitive modeling,		_
connectionist	models of cognition, Bayesian models of cognition, a dynamical systems	С	0,
approach to c	ognition.		
		<u> </u>	
UNIT II	MODELS		
Cognitive Mo	dels of memory and language, computational models of episodic and semantic	с	<u> </u>
memory, moo	leling psycholinguistics.		U.
		1	
UNIT III	COGNITIVE MODELING		9
modeling the	interaction of language, memory and learning, Modeling select aspects of	С	<b>^</b>
cognition clas	sical models of rationality, symbolic reasoning and decision making.		0.
		•	
UNIT IV	INDUCTIVE GENERALIZATION		9
Formal mode	Is of inductive generalization, causality, categorization and similarity, the role of		
	oblem solving, Cognitive Development Child concept acquisition. Cognition and	с	04
	nitive architectures such as ACT-R, SOAR, OpenCog, CopyCat, Memory		-
Artificial cog			
Networks.			
Networks.	APPLICATION		
Networks. <b>UNIT V</b> DeepQA Arcl	hitecture, Unstructured Information Management Architecture (UIMA), Structured		
Networks. <b>UNIT V</b> DeepQA Arcl Knowledge, I	hitecture, Unstructured Information Management Architecture (UIMA), Structured Business Implications, Building Cognitive Applications, Application of Cognitive	с	0
Networks. <b>UNIT V</b> DeepQA Arcl Knowledge, I	hitecture, Unstructured Information Management Architecture (UIMA), Structured Business Implications, Building Cognitive Applications, Application of Cognitive and Systems		
Networks. <b>UNIT V</b> DeepQA Arcl Knowledge, I Computing ar	hitecture, Unstructured Information Management Architecture (UIMA), Structured Business Implications, Building Cognitive Applications, Application of Cognitive and Systems TOTAL : 45 PEF		
Networks. <b>UNIT V</b> DeepQA Arcl Knowledge, I Computing ar	hitecture, Unstructured Information Management Architecture (UIMA), Structured Business Implications, Building Cognitive Applications, Application of Cognitive and Systems TOTAL : 45 PEF	RIO	D
Networks. UNIT V DeepQA Arcl Knowledge, I Computing ar REFERENCE 1. Forma	hitecture, Unstructured Information Management Architecture (UIMA), Structured Business Implications, Building Cognitive Applications, Application of Cognitive and Systems TOTAL : 45 PEF	RIO	D

- Cognition, Brain and Consciousness: Introduction to Cognitive Neuroscience by Bernard J. Bears, Nicole M. Gage, Academic Press, 2013.
- 3. Cognitive Computing and Big Data Analytics by Hurwitz, Kaufman, and Bowles, Wiley, 2012.
- 4. The Cambridge Handbook of Computational Psychology by Ron Sun (ed.), Cambridge University Press,2008.

## **COURSE OUTCOMES**

### Upon completion of the course, students will be able to

CO1	Understand what cognitive computing and it's models
CO2	Understand how it differs from traditional approaches.
CO3	Plan and use the primary tools associated with cognitive computing.
CO4	Plan and execute a project that leverages cognitive computing.
CO5	Understand and develop the business implications of cognitive computing.

#### **PROGRAM SPECIFIC PROGRAM OUTCOMES (POs) OUTCOMES (PSOs)** COs PO3 PO4 PO5 **PO6 PO7** PO8 PO10 PO11 PO1 PO2 PO9 PO12 PSO1 PSO2 PSO3 CO1 3 3 3 2 2 2 2 2 2 3 2 ----2 CO2 3 3 3 2 2 2 2 3 2 --2 -CO3 3 3 3 2 2 ----2 2 2 2 2 3 2 CO4 3 3 3 2 2 2 2 2 2 ----3 CO5 2 3 3 3 2 2 2 2 3 2 2 ----

# MAPPING OF COs WITH POs AND PSOs

		PC
	Ţ.	03
OBJECTIVES • • • •	To Understand the fundamental concepts of robots, sensors and hardware syste To have in depth understanding of various sensors, its elements and characteristic To Understand the integration of robot working in the real world into programming languages To Understand the theoretical aspects of robotics from the basics to adv applications	CS.
UNIT I		9
Robotics res	To Robotics - Robot features, sensors, manipulators - Application areas - State of earch and adoption - Robotic hardware systems - Kinematics and inverse Sensors, sensor data interpretation and sensor fusion - Path planning - spaces.	CO1
UNIT II	ROBOT SENSING	9
Lighting Appr effect sensor sensors: Bina	g - Categories of sensors in robots - Range sensing: Triangulation, Structured oach, Time-of-Flight Range Finders -Proximity Sensing: Inductive sensors, Hall- s, Capacitive sensors, Ultrasonic sensors, Optical Proximity sensors -Touch ary sensors, Analog sensors - Force and Torque sensing: Elements of wrist ving forces and moments - Sensor calibration	CO2
UNIT III	ROBOT VISION	9
	- Imaging geometry - Perspective transformations - Camera model - Camera	
Enhancement	Stereo imaging - Basic relationship between pixels - Preprocessing - Smoothing - t - Edge detection - Thresholding - Segmentation - Use of motion -Description -	CO3
Enhancement Recognition.		CO3 9
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic	t - Edge detection - Thresholding - Segmentation - Use of motion -Description -	
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic synthesis	Edge detection - Thresholding - Segmentation - Use of motion -Description -     ROBOT PROGRAMMING LANGUAGES     amming Languages - Characteristics of robot-level languages: Position     Motion specification, Sensing and flow of control, Programming support -	9
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic synthesis UNIT V Human-Robo - Intelligent in	Edge detection - Thresholding - Segmentation - Use of motion -Description -     ROBOT PROGRAMMING LANGUAGES     amming Languages - Characteristics of robot-level languages: Position     Motion specification, Sensing and flow of control, Programming support -     s of taskLevel languages: World modeling, Task specification, Robot program     HUMAN-ROBOT INTERACTION     t Interaction - Basics - Implicit vs Explicit interaction - HRI experimentation design     teraction - Multi-agent systems Applications.	9 CO4
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic synthesis UNIT V Human-Robor - Intelligent in TOTAL : 45 F	Edge detection - Thresholding - Segmentation - Use of motion -Description -     ROBOT PROGRAMMING LANGUAGES     amming Languages - Characteristics of robot-level languages: Position     Motion specification, Sensing and flow of control, Programming support -     s of taskLevel languages: World modeling, Task specification, Robot program     HUMAN-ROBOT INTERACTION     t Interaction - Basics - Implicit vs Explicit interaction - HRI experimentation design     teraction - Multi-agent systems Applications.     PERIODS	9 CO4 9
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic synthesis UNIT V Human-Robor - Intelligent in TOTAL : 45 F TEXT BOOKS 1. K.S.Fu, R.C McGraw Hill,	Edge detection - Thresholding - Segmentation - Use of motion -Description -     ROBOT PROGRAMMING LANGUAGES     amming Languages - Characteristics of robot-level languages: Position     Motion specification, Sensing and flow of control, Programming support -     s of taskLevel languages: World modeling, Task specification, Robot program     HUMAN-ROBOT INTERACTION     t Interaction - Basics - Implicit vs Explicit interaction - HRI experimentation design     teraction - Multi-agent systems Applications.     PERIODS	9 CO4 9
Enhancement Recognition. UNIT IV Robot Progr specification, Characteristic synthesis UNIT V Human-Robor - Intelligent in TOTAL : 45 F TEXT BOOKS 1. K.S.Fu, R.C McGraw Hill,	Edge detection - Thresholding - Segmentation - Use of motion -Description -     ROBOT PROGRAMMING LANGUAGES     amming Languages - Characteristics of robot-level languages: Position     Motion specification, Sensing and flow of control, Programming support -     s of taskLevel languages: World modeling, Task specification, Robot program     HUMAN-ROBOT INTERACTION     t Interaction - Basics - Implicit vs Explicit interaction - HRI experimentation design     teraction - Multi-agent systems Applications.     PERIODS     S     C.Gonzalez, C.S.G.Lee, "Robotics - Control, Sensing, Vision and Intelligence", Tata     Second Edition,2008     I.JNagrath, "Robotics and Control", Tata McGraw Hill, Second Edition, 2007	9 CO4 9

COUF			COM	<u> </u>												
Upon					cours	se, sti	uden	ts will	l be a	ble to	)					
CO1	1	_										ors and	l hardv	vare syst	ems	
CO2												nd chai				
CO3		nderst		ng the	integ	ration	of ro	bot wo	orking	in the	e real v	world in	nto pro	grammir	ng	
CO4	Understanding the theoretical aspects of robotics from the basics to advanced applications															
CO5	Тс	Build	d a rea	al tim	e Rob	ots										
	1				Μ	APPI	NG C	F CO	s WI		)s ANI	D PSO	s			
<b>C</b> O		MAPPING OF COS WITH POS AND PSOS PROGRAM OUTCOMES (POS) PROGRAM SPECIFIC OUCOMES														
COs	5	PO 1	PO 2	PO 3	РО 4	PO 5	PO 6	РО 7	PO 8	РО 9	PO 10	PO 11	PO 12	PSO1	PSO2	PSO3
CO1	1	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2	2	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	3	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4	1	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2
COS	5	1	2	2	2	1	-	-	1	1	1	1	1	2	2	2

ML1823		Т	С
OBJECTIVE		0	3
	ovide students with a theoretical as well as practical understanding of agile software		
•	opment practices and how small teams can apply them to create high-quality softwa		
	ovide a good understanding of software design and a set of software technologies a		
APIs.		nu	
	a detailed examination and demonstration of Agile development and testing technic		~
		Jue	э.
	nderstand the benefits and pitfalls of working in an Agile team.		
• Iour	nderstand Agile development and testing.		
UNIT I	AGILE METHODOLOGY		8
Theories for	Agile Management – Agile Software Development – Traditional Model vs. Agile		
Model – Cla	assification of Agile Methods – Agile Manifesto and Principles – Agile Project		~4
Managemen	t – Agile Team Interactions – Ethics in Agile Teams – Agility in Design, Testing –	C	01
Agile Docum	entations – Agile Drivers, Capabilities and Values		
UNIT II	AGILE PROCESSES		8
Lean Produ	ction – SCRUM, Crystal, Feature Driven Development- Adaptive Software		
Developmen	t – Extreme Programming: Method Overview – Lifecycle – Work Products, Roles	С	02
and Practice	S.		
UNIT III	AGILITY AND KNOWLEDGE MANAGEMENT		8
Agile Inform	ation Systems – Agile Decision Making – Earl_S Schools of KM – Institutional		
Knowledge E	Evolution Cycle – Development, Acquisition, Refinement, Distribution, Deployment,		
Leveraging -	- KM in Software Engineering - Managing Software Knowledge - Challenges of	С	03
Migrating to	Agile Methodologies - Agile Knowledge Sharing - Role of Story-Cards - Story-		
Card Maturit	y Model (SMM).		
UNIT IV	AGILITY AND REQUIREMENTS ENGINEERING		8
Impact of Ag	ile Processes in RE-Current Agile Practices - Variance - Overview of RE Using		
Agile – Man	aging Unstable Requirements – Requirements Elicitation – Agile Requirements		
Abstraction	Model – Requirements Management in Agile Environment, Agile Requirements	С	04
Prioritization	- Agile Requirements Modeling and Generation - Concurrency in Agile		
Requiremen	ts Generation.		
UNIT V	AGILITY AND QUALITY ASSURANCE		8
Agile Produc	t Development – Agile Metrics – Feature Driven Development (FDD) – Financial		
and Producti	on Metrics in FDD – Agile Approach to Quality Assurance – Test Driven	С	05
Developmen	t – Agile Approach in Global Software Development.		
	TOTAL : 45 PEF	SIO	DS

- **1.** David J. Anderson and Eli Schragenheim, "Agile Management for Software Engineering: Applying the Theory of Constraints for Business Results", Prentice Hall, 2003.
- 2. Hazza and Dubinsky, "Agile Software Engineering, Series: Undergraduate Topics in Computer Science", Springer, 2009.
- 3. Craig Larman, "Agile and Iterative Development: A Managers Guide", Addison-Wesley, 2004.
- **4.** Kevin C. Desouza, "Agile Information Systems: Conceptualization, Construction, and Management", ButterworthHeinemann, 2007.

COURSE															
Upon co															
			•				-	n busi	ness	stakeh	olders	in dete	ermining	the	
	quirer														
CO2 Pe	erform	n itera	tive so	oftwar	re dev	/elopr	nent p	proces	sses:	how to	plan t	nem, h	now to ex	ecute the	em.
CO3 De	evelop	b tech	nique	s and	tools	for in	nprovi	ing tea	am co	llabora	ation a	nd soft	tware qu	ality.	
CO4 Pe	erform	n Softv	ware p	oroce	ss imp	prove	ment	as an	ongo	ing tas	k for d	evelop	ment tea	ams.	
CO5 Sł	now h	ow ag	jile ap	proad	ches c	an be	e scal	ed up	to the	enter	prise le	evel.			
				Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S			
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COs									(1 03	<b>'</b>			0	UCOME	S
003	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO1	PSO2	PSO3
	1	2	3	4	5	6	7	8	9	10	11	12	1 301	1 302	1 303
CO1	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO2	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO5	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2

			<b>C</b> 3
OBJECTIV		0	3
<ul> <li>Unc</li> </ul>	lerstand the basic concepts of brain computer interface		
• Stu	dy the various signal acquisition methods		
• Lea	rn about the signal processing methods used in BCI		
• Und	lerstand the various machine learning methods of BCI.		
• Lea	rn the various applications of BCI		
			8
	n - Brain structure and function, Brain Computer Interface Types -		
	us and Asynchronous -Invasive BCI -Partially Invasive BCI - Non Invasive BCI,	СС	<b>D1</b>
•	f BCI System, BCI Monitoring Hardware, EEG, ECoG, MEG, fMRI.		
	BRAIN ACTIVATION	L	
	ation patterns – Spikes, Oscillatory potential and ERD, Slow cortical potentials,		
	related potentials-Mu rhythms, motor imagery, Stimulus related potentials –		
	ked Potentials – P300 and Auditory Evoked Potentials, Potentials related to	CC	22
cognitive ta			
	FEATURE EXTRACTION METHODS		
	essing – Spike sorting, Frequency domain analysis, Wavelet analysis, Time		
	alysis, Spatial filtering -Principal Component Analysis (PCA), Independent	СС	03
•	t Analysis (ICA), Artefacts reduction, Feature Extraction – Phase		
SVDCDDDDZ	ation and coherence	<u> </u>	
<u> </u>			
UNIT IV	MACHINE LEARNING METHODS FOR BCI		6
UNIT IV Classificatio	on techniques –Binary classification, Ensemble classification, Multiclass		
UNIT IV Classificatio	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial,	CC	
UNIT IV Classificatio Classificatio RBF's, Pe	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, prceptron's, Multilayer neural networks, Support vector machine, Graph	СС	
UNIT IV Classificatio Classificatio RBF's, Pe	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial,	co	
UNIT IV Classificatio Classificatio RBF's, Pe theoretical	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, prceptron's, Multilayer neural networks, Support vector machine, Graph	C	24
UNIT IV Classificatio Classificatio RBF's, Pe theoretical UNIT V	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, prceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis.	c	، ک
UNIT IV Classificatio Classificatio RBF's, Pe theoretical UNIT V Case Stud	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis.	c	24
UNIT IV Classificatio Classificatio RBF's, Pe theoretical UNIT V Case Stud prosthetic	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis. APPLICATIONS OF BCI ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling		<b>.</b>
UNIT IV Classification Classification RBF's, Pertheoretical UNIT V Case Studn prosthetic electrode a	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis. APPLICATIONS OF BCI ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling devices such as orthotic hands, Cursor and robotic control using multi		54
UNIT IV Classification Classification RBF's, Pertheoretical UNIT V Case Studn prosthetic electrode a Noninvasiv	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis. APPLICATIONS OF BCI ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling devices such as orthotic hands, Cursor and robotic control using multi array implant, Cortical control of muscles via functional electrical stimulation.		<b>.</b>
UNIT IV Classification Classification RBF's, Pertheoretical UNIT V Case Studn prosthetic electrode a Noninvasiv	<ul> <li>bin techniques –Binary classification, Ensemble classification, Multiclass</li> <li>bin, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis.</li> <li>APPLICATIONS OF BCI</li> <li>ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling devices such as orthotic hands, Cursor and robotic control using multi array implant, Cortical control of muscles via functional electrical stimulation.</li> <li>e BCIs:P300 Mind Speller, Visual cognitive BCI, Emotion detection. Ethics of</li> </ul>	co	ے د ک
UNIT IV Classification Classification RBF's, Pertheoretical UNIT V Case Stude prosthetic electrode at Noninvasiv Brain Comp	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis. APPLICATIONS OF BCI ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling devices such as orthotic hands, Cursor and robotic control using multi array implant, Cortical control of muscles via functional electrical stimulation. e BCIs:P300 Mind Speller, Visual cognitive BCI, Emotion detection. Ethics of puter Interfacing.	co	55
UNIT IV Classification Classification RBF's, Pertheoretical UNIT V Case Stude prosthetic electrode at Noninvasive Brain Comp	on techniques –Binary classification, Ensemble classification, Multiclass on, Evaluation of classification performance, Regression - Linear, Polynomial, erceptron's, Multilayer neural networks, Support vector machine, Graph functional connectivity analysis. APPLICATIONS OF BCI ies – Invasive BCIs: decoding and tracking arm (hand) position, controlling devices such as orthotic hands, Cursor and robotic control using multi array implant, Cortical control of muscles via functional electrical stimulation. e BCIs:P300 Mind Speller, Visual cognitive BCI, Emotion detection. Ethics of puter Interfacing. TOTAL : 45 PER	CC	24 

	practice				ity Pr	ess, l	JSA, E	Editio	n 1, Ja	anuary	2012.				
	REFER	ENC	E BO	OKS											
1.	Ella Ha	issian	ien, A	A &Az	zar.A.	T (Ed	litors)	, Brai	n-Cor	nputer	Interf	aces (	Current 1	Frends	s and
	Applica	tions,	Sprin	nger, 2	2015.										
2.	Bernha	rd G	raima	nn, E	Brenda	an A	llison,	Ger	tPfurt	schelle	er, "Br	ain-Co	mputer	Interf	aces
	Revolut	ionizi	ng Hu	ıman-	Comp	outer	Intera	ction"	, Sprir	nger, 2	010				
3.	Ali Bas	hasha	ati, M	ehrda	dFato	ourect	ni, Ra	ibab I	K Wa	rd, Ga	ary E	Birch,	A surve	y of s	signa
	Proces	sing a	algorit	thms	in br	ain-co	omput	er in	terfac	es ba	sed o	n elec	trical bra	ain si	gnal
	Journal	of Ne	eural E	Engin	eering	, Vol.	4, 200	07, PF	P.32-5	57					
4.	Arnon	Koher	n, Bio	media	cal Si	gnal	Proce	ssing	, Vol	I and	II, CR	C Pre	ss Inc, I	Boca	Rato
	Florida.														
5.	Bishop	С.М.,	Neur	al net	works	s for F	Patterr	n Rec	ognitio	on, Ox	ford, C	larend	on Press	s, 199	5.
6.	Andrew	/ Web	b, Sta	atistica	al Pat	tern R	Recog	nition,	Wiley	/ Interi	nationa	al, Sec	ond Editi	ion, 20	)02.
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	RSE OUT	СОМ	ES												
Upon	complet	tion o	of the	cours	se, st	uden	ts wil	l be a	ble to	)					
CO1	-										nis cou	irse in	the pres	ent	
	Comprehend and appreciate the significance and role of this course in the present contemporary world.														
CO2	contemporary world. Evaluate concept of BCI.														
CO3	Assign					/ to th	e hun	nan a	nd to t	the ma	chine				
CO4	Select a														
CO5	Use ma		-												
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	PING OF	<u>COc</u>		POc		PSO	<u> </u>								
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							ITCO	MES	(POs)					ECIFI	
COs				FIC			5100		(FUS)				_		-
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CO2		2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO3		2	2	2	1	-	-	1	1	1	1	1	2	2	2
	2	2	2	2	1	-	-	1	1	1	1	1	2	2	2
CO4 CO5	2		2	2	1	-	1 _	1	1	1	1	1	2	2	2

OBT101	INDUSTRIAL BIOTECHNOLOGY L T	Ρ	С
	3 0	0	3
OBJECTIVE			
biotec and a envirc	ptivate students to excel in research and to practice the technologies in the field of Inchnology. To provide students with a solid understanding of Biotechnology fundar applications required to solve real life problems. To provide students with an accomment that is aware of professional excellence and leadership through interactions isolal bodies	nen adei	tals mic
UNIT I	OVERVIEW OF THE CELL		9
function of in	e and properties, prokaryotic and eukaryotic cells, structural organization and tracellular organelles; Cell wall, Nucleus, Mitochondria, Golgi bodies, Lysosomes, reticulum, Peroxisomes and Chloroplast.	C	01
UNIT II	MICROBIAL GROWTH: PURE CULTURE TECHNIQUES		9
Growth curve Media formu media, factor	c microorganisms. The definition of growth, mathematical expression of growth, a vailability of oxygen, culture collection and maintenance of cultures. lation: principles of microbial nutrition, formulation of culture medium, selective s influencing the choice of various carbon and nitrogen sources, vitamins, minerals, and antifoam agents. Importance of pH.		
UNIT III	MANAGEMENT OF WASTE		9
•	of Contaminated land, lake sediments and Solid Waste, Anaerobic digestion, n, Bioaugmentation, Phytoremediation, Natural attenuation, Vermicomposting	C	03
UNIT IV	BIOREMEDIATION		9
situ biorem	nstraints and priorities of Bioremediation, Types of bioremediation, In-situ and Ex- ediation techniques, Factors affecting bioremediation. Bioremediation of s. Lignocellulosic Compounds.	C	04
UNIT V	BIOENERGY AND BIOMINING		9
	Energy and Biomass Production from wastes, biofuels, bio hydrogen and biomass. oleaching, monitoring of pollutants, microbially enhanced oil recovery, microbial fuel	C	05
	TOTAL : 45 PE	RIO	DS
Inc.	ular Biology of cell, Alberts. B et al. Developmental Biology, SF Gilbert, Sinauer Ass Swamy, Industrial Pollution Control Engineering, 2006, Galgotia Publication,	ocia	ates
REEEDENIC			
REFERENCE	onmental Biotechnology - Allan Stagg.		

COUR	RSE (	ουτ	СОМ	ES												
Upon	com	plet	ion o	f the	cours	se, st	udent	s will	l be a	ble to	)					
CO1					(perin gineei					erpret	data fo	or inve	stigating	complex	problem	ns in
CO2	Dec	cide	and a	pply a	appro	priate	tools	and t	echni	ques	in biote	echnolo	ogical ma	anipulatic	on.	
CO3	Jus	tify s	societ	al, he	alth, s	afety	and I	egal i	ssues							
CO4	Und	Iustify societal, health, safety and legal issues Jnderstand his responsibilities in biotechnological engineering practices														
CO5		Understand his responsibilities in biotechnological engineering practices Understand the need and impact of biotechnological solutions on environment and societal context keeping in view need for sustainable solution.														
					Ν	IAPP	'ING (	OF CO	Os Wl	TH P	Os AN	D PSC	)s			
COs	5				PF	ROGR	AM C	DUTC	OME	S (PO	s)			S	ROGRA PECIFIC OMES (I	
	1	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		1	1	2	1	1	2	2	4	2	1	1	1	2	1	1
CO2		2	1	1	2	2	1	2	1	3	4	1	2	1	1	2
CO3		3	3	2	1	1	2	4	3	1	2	4	5	1	2	2
CO4		3	3	2	4	2	1	1	1	2	1	3	2	1	2	2
CO5		2	1	4	5	2	4	3	2	1	2	3	1	1	2	2

OBT1	04	BIOSENSORS	L	Т	Ρ	С
			3	0	0	3
OBJE	CTIVE					
*	Unders	tand protein based biosensors and their enzyme reactivity, stability and the	eir ap	oplica	atior	۱
UNIT		PROTEIN BASED BIOSENSORS				9
Nano	structure	for enzyme stabilization - Single enzyme nano particles - Nanotubes mic	ropo	orus	СС	<b>D1</b>
silica -	· Protein	based nanocrystalline Diamond thin film for processing				
UNIT	II	DNA BASED BIOSENSOR				9
Heavy bioser		omplexing with DNA and its determination water and food samples - DN	A zy	/mo	CC	02
UNIT		ELECTRO CHEMICAL APPLICATION				9
Detect	tion in bi	osensors - Flurorescence - Absorption - Electrochemical. Integration of	vari	ous	СС	)3
techni	ques - Fi	bre optic biosensors				
UNIT	IV	FABRICATION OF BIOSENSORS				9
Techn	iques us	ed for microfabrication - Microfabrication of electrodes - On chip analysis			СС	)4
UNIT	V	BIOSENSORS IN RESEARCH				9
Future	e directio	n in biosensor research - Designed protein pores-as components of biose	enso	ors -	CC	05
		gn -Bionanotechnology for cellular biosensing - Biosensors for drug disc	cove	ry -		
Nanos	scale bios					
		TOTAL	.:4	5 PE	rio	DS
TEXT	BOOKS					
1.	Biosens	sors: A Practical Approach, J. Cooper & C. Tass, Oxford University Press,	2004	1		
REFE	RENCE	BOOKS				
1.	Nanom	aterials for Biosensors, Cs. Kumar, Willey - VCH, 2007				
2.	Smart E	Biosensor Technology, G.K. Knoff, A.S. Bassi, CRC Press, 2006.				
COUR	RSE OUT	COMES				
Upon	complet	ion of the course, students will be able to				
CO1		udents will able to understand protein based biosensors and their ena and their application in protein based nano crystalline thin film processing	zyme	e rea	activ	rity,
CO2	The stu	dents will able to describe DNA based biosensors to study the presence	of he	eavy	met	als
	in the fo	ood products				
CO3	The stubiosens	idents will able to understand fluorescence, UV-Vis and electrochemical cors	app	olicat	ions	s of
CO4	The stu	udents will able to study about the fabrication of biosensors and its	app	olicat	ion	as
	nanoch	ipanalyzer				
CO5	To unde	erstand the Future direction in biosensor research				
	L					

				ľ	MAPF	PING	OF CO	Os W	ITH P	Os AN	ID PSC	Ds			
COs		PROGRAM OUTCOMES (POs)  PROGRAM SPECIFIC OUTCOMES (PSOs)													
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
C01	2	1	3	2	1	2	2	4	2	1	1	1	2	1	1
CO2	3	2	1	2	2	1	2	1	3	4	1	2	1	1	2
CO3	1	2	4	3	1	2	4	3	1	2	4	5	1	2	2
CO4	1	2	2	4	2	1	1	1	2	1	3	2	1	2	2
CO5	2	1	3	1	2	4	3	2	1	2	3	1	1	2	2

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OBT105	INTRODUCTION TO NANOSCIENCE AND NANOTECHNOLOGY	L	Т	Ρ	С
		3	0	0	3
OBJECTIVE					
	tand the principles of processing, manufacturing and characterization o nostructures.	f nai	noma	ateri	als
UNIT I	BASICS OF NANOTECHNOLOGY				9
and size dependence dependence dependence dependence dependence dependence dependence dependence dependence de and subsect de subse	Time and length scale in structures -Definition of a nanosystem -Dimen- ndent phenomena -Surface to volume ratio -Fraction of surface atoms - face stress- surface defects-Effect of nanoscale on various properties - St anical, magnetic, optical and electronic properties.	Surf	ace	CC	01
UNIT II	DIFFERENT CLASSES OF NANOMATERIALS				9
materials (bucl	based on dimensionality-Quantum Dots,Wells and Wires- Carbon base (yballs, nanotubes, grapheme)- Metal based nanomaterials (nanogold, na es) - Nanocomposites-Nanopolymers - Nano ceramics -Biological nanoma	inosi	lver	CC	)2
UNIT III	SYNTHESIS OF NANOMATERIALS				9
Synthesis-Pho Chemical Vapo	hods:Metal Nanocrystals by Reduction -Sol - gel processing -Solve tochemical Synthesis - Chemical Vapor Deposition(CVD) - Metal ( or Deposition (MOCVD).Physical Methods:Ball Milling - Electrodeposition RF Magnetron Sputtering - Molecular Beam Epitaxy (MBE).	Oxid	e -	CC	03
UNIT IV	CHARACTERIZATION OF NANOSTRUCTURES				9
angle X-ray sc analysis (EDA (STM)-Atomic	tructural characterization, X-ray diffraction (XRD-Powder/Single crystal) attering (SAXS), Scanning Electron Microscopy (SEM) - Energy Dispersiv X)- Transmission Electron Microscope (TEM) - Scanning Tunneling Mic Force Microscopy (AFM), UV-vis spectroscopy (liquid and solid state) - X-ray Photoelectron Spectroscopy (XPS) - Auger Electron spectroscopy (/	/e X- rosco Rar	-ray ope nan	CC	94
UNIT V	APPLICATIONS				9
Nanoelectronic in displays and	conversion and catalysis - Molecular electronics and printed electronics and printed electronics - Polymers with a special architecture - Liquid crystalline systems - App other devices -Nanomaterials for data storage -Photonics, Plasmonics- C -Nanomedicine and Nanobiotechnology	licati	ons	СС	05
	TOTAL	.:45	5 PE	RIO	DS
TEXT BOOKS					
Geoff S 2. A Text Pvt.Ltd. 3. Nanost 4. Introduc 5. Textboo	echnology: Basic Science and Emerging Technologies, Mick Wilson, Kam mith Overseas Press (2005) book of Nanoscience and Nanotechnology,Pradeep T., Tata McGrav , 2012. ructured Materials and Nanotechnology,Hari Singh Nalwa,Academic Press ction to Nanotechnology, Charles P.Poole, FrankJ.Owens, Wiley Interscier ok of Nanoscience and Nanotechnology, B.S. Murty, P. Shankar, Baldev Murday, Springer Science & Business Media, 2013.	wHill 5, 200 nce (2	Edu 02. 2003	ucati	ion

REFE	RENCE	BOOI	۲S												
1.	Nanote Ratne,		0,	•					next I	Big ide	a, Mar	k A.Ratr	er, Dani	el Ratne	r, Mark
2.									erials	Ed D.	Fioran	, G.Sber	veglier,	World So	cientific
3.	Nanoso Verlag						nd Na	anoph	ysics,	Dupa	s C., ⊦	loudy P.	, Lahma	ni M., Sp	oringer-
COUR	SE OUT	СОМ	ES												
Upon	comple	tion o	f the	cours	se, st	udent	s will	l be a	ble to	)					
CO1	Demon	strate	the u	nders	tandir	ng of I	length	scale	es cor	ncepts	nanos	structures	s and nai	notechno	ology
CO2	Unders	Demonstrate the understanding of length scales concepts, nanostructures and nanotechnology Inderstand the different classes of nanomaterials.													
CO3	Identify	entify the CVD, MOCVD													
CO4	Outline	utline the applications of nanotechnology and													
CO5	Develo	evelop an ability to critically evaluate the promise of a nanotechnology device.													
				Γ	/APP	ING (	OF CO	) Ss Wl	TH P	Os AN		)s			
COs	;			PF	ROGR	AM C	оитс	OME	S (PO	s)				RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3
CO1	2	1	3	2	1	2	2	4	2	1	1	1	2	1	1
CO2	3	2	1	2	2	1	2	1	3	4	1	2	1	1	2
CO3	1	2	4	3	1	2	4	3	1	2	4	5	1	2	2
CO4	1	2	2	4	2	1	1	1	2	1	3	2	1	2	2
CO5	2	1	3	1	2	4	3	2	1	2	3	1	1	2	1

	INTRODUCTION TO GEOGRAPHIC INFORMATION SYSTEM	Т	С
	3 0	0	3
OBJECTIVE	5	I	
<ul> <li>To int</li> </ul>	oduce the fundamentals and components of Geographic Information System		
<ul> <li>To pro</li> </ul>	vide details of spatial data models.		
🛠 To kn	ow the details of data input and topology		
🛠 To kn	ow the knowledge on data management and output processes		
🛠 To kn	ow the data quality and standards		
UNIT I	FUNDAMENTALS OF GIS		9
Systems – D People, Meth	o GIS - Basic spatial concepts - Coordinate Systems - GIS and Information efinitions – History of GIS - Components of a GIS – Hardware, Software, Data, ods – Proprietary and open-source Software - Types of data – Spatial, Attribute attributes – scales/ levels of measurements.	C	D1
UNIT II	SPATIAL DATAMODELS		9
conceptual, I	uctures – Relational, Object Oriented – Entities – ER diagram - data models - ogical and physical models - spatial data models – Raster Data Structures – Compression - Vector Data Structures - Raster vs Vector Models- TIN and GRID	C	02
UNIT III	DATA INPUTANDTOPOLOGY		9
Input –Digitis Adjacency, c	aster Data Input – Raster Data File Formats – Georeferencing – Vector Data er – Datum Projection and reprojection -Coordinate Transformation – Topology - onnectivity and containment – Topological Consistency – Non topological file bute Data linking – Linking External Databases – GPS Data Integration	C	03
	DATA QUALITYANDSTANDARDS		9
<b>UNIT IV</b> Data quality temporal ac		C	9 04
<b>UNIT IV</b> Data quality temporal ac Interoperabili	DATA QUALITY ANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards –	C	
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion -	DATA QUALITY ANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure		D4
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion -	DATA QUALITY ANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure         DATA MANAGEMENTANDOUTPUT         - Data Management functions- Raster to Vector and Vector to Raster Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs.	C	04 9 05
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion - Desktop GIS-	DATA QUALITY ANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure         DATA MANAGEMENTANDOUTPUT         - Data Management functions- Raster to Vector and Vector to Raster Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs. distributed GIS.         TOTAL : 45 PE	C	04 9 05
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion - Desktop GIS- TEXT BOOK 1. Kang	DATA QUALITY ANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure         DATA MANAGEMENTANDOUTPUT         - Data Management functions- Raster to Vector and Vector to Raster Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs. distributed GIS.         TOTAL : 45 PE	C	04 9 05 DS
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion - Desktop GIS- TEXT BOOK 1. Kang 2nd E 2. Ian	DATA QUALITYANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure         DATA MANAGEMENTANDOUTPUT         - Data Management functions- Raster to Vector and Vector to Raster Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs. distributed GIS.         TOTAL : 45 PE         S         - TsungChang, Introduction to Geographic Information Systems, McGraw Hill Public	C( RIC	04 9 05 DS
UNIT IV Data quality temporal acc Interoperabili UNIT V Import/Export Conversion - Desktop GIS- TEXT BOOK 1. Kang 2nd E 2. Ian	DATA QUALITYANDSTANDARDS         - Basic aspects - completeness, logical consistency, positional accuracy, curacy, thematic accuracy and lineage – Metadata – GIS Standards – y - OGC - Spatial Data Infrastructure         DATA MANAGEMENTANDOUTPUT         - Data Management functions- Raster to Vector and Vector to Raster Data Output - Map Compilation – Chart/Graphs – Multimedia – Enterprise Vs. distributed GIS.         TOTAL : 45 PE         S         - TsungChang, Introduction to Geographic Information Systems, McGraw Hill Put dition, 2011.         Heywood, Sarah Cornelius, SteveCarver,Srinivasa Raju, "An Intro aphical Information Systems, Pearson Education, 2ndEdition, 2007.	C( RIC	04 9 05 DS

COURS	RSE OUTCOMES n completion of the course, students will be able to														
Upon o	comple	tion o	f the	cours	se, st	udent	ts wil	l be a	ble to						
CO1	Have	basic	idea a	about	the fu	undam	nental	ls of G	SIS.						
CO2	Under	rstand	the ty	ypes o	of data	a moc	lels.								
CO3	Get ki	nowlee	dge a	bout o	data ir	nput a	nd to	polog	у.						
CO4	Gain I	knowle	edge	on da	ta qua	ality a	nd sta	andaro	ds.						
CO5	Unde	Gain knowledge on data quality and standards. Understand data management functions and data output													
	MAPPING OF COs WITH POs AND PSOs														
COs				PRC	GRA	MOU	лсо	MES	(POs)					RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	1	2	-	1	-	-	-	-	2	2	2	1
CO2	2	2	1	1	2	-	1	-	-	-	-	2	2	2	2
CO3	2	2	1	1	2	-	1	-	-	-	-	2	2	2	1
CO4	2	2	1	1	2	-	1	-	-	-	-	2	2	2	1
CO5	2	2	1	1	2	-	1	-	-	-	-	2	2	2	2

Planning- Equipment Planning – Functional Planning         UNIT II       HUMAN RESOURCE MANAGEMENT IN HOSPITAL         Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory          – Manpower Planning.          UNIT III       RECRUITMENT AND TRAINING         Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.          UNIT IV       SUPPORTIVE SERVICES         Medical Records Department – Central Sterilization and Supply Department – Pharmacy –	C         3         9         CO1         9         CO2         9         CO3         9
OBJECTIVES <ul> <li>To understand the fundamentals of hospital administration and management.</li> <li>To know the market related research process and its HRM</li> <li>To understand the recruitment and training processes in hospitals</li> <li>To explore various information management systems and relative supportive services.</li> <li>To learn the quality and safety aspects in hospital.</li> </ul> UNIT I         OVERVIEW OF HOSPITAL ADMINISTRATION           Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning         HUMAN RESOURCE MANAGEMENT IN HOSPITAL           VINIT II         HUMAN RESOURCE MANAGEMENT IN HOSPITAL           Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.         C           UNIT III         RECRUITMENT AND TRAINING         C           Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.         C           UNIT IV         SUPPORTIVE SERVICES         C           Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.         C	9 CO1 9 CO2 9 CO3
<ul> <li>To understand the fundamentals of hospital administration and management.</li> <li>To know the market related research process and its HRM</li> <li>To understand the recruitment and training processes in hospitals</li> <li>To explore various information management systems and relative supportive services.</li> <li>To learn the quality and safety aspects in hospital.</li> <li>UNIT I</li> <li>OVERVIEW OF HOSPITAL ADMINISTRATION</li> <li>Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning</li> <li>UNIT II</li> <li>HUMAN RESOURCE MANAGEMENT IN HOSPITAL</li> <li>Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.</li> <li>UNIT III</li> <li>RECRUITMENT AND TRAINING</li> <li>Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.</li> <li>UNIT IV</li> <li>SUPPORTIVE SERVICES</li> <li>Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services.</li> </ul>	CO1 9 CO2 9 CO3
<ul> <li>To know the market related research process and its HRM</li> <li>To understand the recruitment and training processes in hospitals</li> <li>To explore various information management systems and relative supportive services.</li> <li>To lear the quality and safety aspects in hospital.</li> <li>UNIT I</li> <li>OVERVIEW OF HOSPITAL ADMINISTRATION</li> <li>Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning</li> <li>UNIT II</li> <li>HUMAN RESOURCE MANAGEMENT IN HOSPITAL</li> <li>Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.</li> <li>UNIT III</li> <li>RECRUITMENT AND TRAINING</li> <li>Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Leadership grooming and Training, Promotion – Transfer.</li> <li>UNIT IV</li> <li>SUPPORTIVE SERVICES</li> <li>Medical Recoverses.</li> </ul>	CO1 9 CO2 9 CO3
<ul> <li>To understand the recruitment and training processes in hospitals</li> <li>To explore various information management systems and relative supportive services.</li> <li>To lear the quality and safety aspects in hospital.</li> <li>UNIT I</li> <li>OVERVIEW OF HOSPITAL ADMINISTRATION</li> <li>Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning</li> <li>UNIT II</li> <li>HUMAN RESOURCE MANAGEMENT IN HOSPITAL</li> <li>Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.</li> <li>UNIT III</li> <li>RECRUITMENT AND TRAINING</li> <li>Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evation of Training – Leadership grooming and Training, Promotion – Transfer.</li> <li>UNIT IV</li> <li>SUPPORTIVE SERVICES</li> <li>Medical Record Services.</li> </ul>	CO1 9 CO2 9 CO3
<ul> <li>To explore various information management systems and relative supportive services.</li> <li>To lear the quality and safety aspects in hospital.</li> <li>UNIT I</li> <li>OVERVIEW OF HOSPITAL ADMINISTRATION</li> <li>Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning</li> <li>UNIT II</li> <li>HUMAN RESOURCE MANAGEMENT IN HOSPITAL</li> <li>Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.</li> <li>UNIT II</li> <li>RECRUITMENT AND TRAINING</li> <li>Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.</li> <li>UNIT IV</li> <li>SUPPORTIVE SERVICES</li> <li>Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Kood Services.</li> </ul>	CO1 9 CO2 9 CO3
<ul> <li>To lear the quality and safety aspects in hospital.</li> <li>UNIT I OVERVIEW OF HOSPITAL ADMINISTRATION</li> <li>Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning</li> <li>UNIT II HUMAN RESOURCE MANAGEMENT IN HOSPITAL</li> <li>Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory – Manpower Planning.</li> <li>UNIT III RECRUITMENT AND TRAINING</li> <li>Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.</li> <li>UNIT IV SUPPORTIVE SERVICES</li> <li>Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.</li> </ul>	CO1 9 CO2 9 CO3
UNIT I       OVERVIEW OF HOSPITAL ADMINISTRATION         Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning       Image: Comparison of the state of th	CO1 9 CO2 9 CO3
Distinction between Hospital and Industry, Challenges in Hospital Administration – Hospital Planning- Equipment Planning – Functional Planning       Image: Comparison of the state of the	CO1 9 CO2 9 CO3
Planning- Equipment Planning – Functional Planning       Image: Comparison of the state of the	9 CO2 9 CO3
Principles of HRM – Functions of HRM – Profile of HRD Manager –Human Resource Inventory	CO2 9 CO3
-       Manpower Planning.       RECRUITMENT AND TRAINING         UNIT III       RECRUITMENT AND TRAINING       Image: Comparison of the spital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of training – Leadership grooming and Training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison of training – Leadership groom – Transfer.       Image: Comparison – Transfer.       Image: Comparison – Transfer.	9 CO3
-       Manpower Planning.       RECRUITMENT AND TRAINING         UNIT III       RECRUITMENT AND TRAINING       Image: Comparison of the spital of	9 CO3
Different Departments of Hospital, Recruitment, Selection, Training Guidelines – Methods of Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.       C         UNIT IV       SUPPORTIVE SERVICES         Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.       C	03
Training – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.       Image: Comparison of Training – Leadership grooming and Training, Promotion – Transfer.         UNIT IV       SUPPORTIVE SERVICES         Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.       Image: Comparison of Training – Leadership grooming and Training, Promotion – Transfer.	
Iraining – Evaluation of Training – Leadership grooming and Training, Promotion – Transfer.         UNIT IV       SUPPORTIVE SERVICES         Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.       C	
Medical Records Department – Central Sterilization and Supply Department – Pharmacy – Food Services - Laundry Services.	9
Food Services - Laundry Services.	
Food Services - Laundry Services.	204
	CO4
COMMUNICATION AND SAFETT ASPECTS IN HOSPITAL	9
Purposes – Planning of Communication, Modes of Communication – Telephone, ISDN, Public Address and Piped Music – CCTV.Security – Loss Prevention – Fire Safety – Alarm System – Safety Rules.	05
TOTAL : 45 PERIC	DDS
TEXT BOOKS	
<ol> <li>R.C.Goyal, "Hospital Administration and Human Resource Management", PHI – Fourth Edit 2006.</li> </ol>	tion,
<ol> <li>G.D.Kunders, "Hospitals – Facilities Planning and Management – TMH, New Delhi – I Reprint 2007.</li> </ol>	Fifth
REFERENCE BOOKS	
1. Cesar A.Caceres and Albert Zara, "The Practice of Clinical Engineering, Academic Press, I York, 1977.	New
<ol> <li>Norman Metzger, "Handbook of Health Care Human Resources Management", 2nd ed Aspen Publication Inc. Rockville, Maryland, USA, 1990.</li> </ol>	ition
3. Peter Berman "Health Sector Reform in Developing Countries" - Harvard University Press, 19	95.
4. William A. Reinke "Health Planning For Effective Management" - Oxford University Press.19	
5. Blane, David, Brunner, "Health and SOCIAL Organization: Towards a Health Policy for the	
Century", Eric Calrendon Press 2002.	
<ol> <li>Arnold D. Kalcizony&amp; Stephen M. Shortell, "Health Care Management", 6<sup>th</sup> Ed Cengage Learning, 2011.</li> </ol>	ition

COUR	SE OL	ітсоі	IES												
Upon	comp	etion	of the	cours	se, st	uden	ts wil	l be a	ble to	)					
CO1	Expla	in the	orincip	les of	Hosp	oital a	dminis	stratio	n.						
CO2	Identi	Identify the importance of Human resource management.													
CO3	List v	List various marketing research techniques.													
CO4	Identi	y Info	matio	n mar	agem	nent s	ystem	is and	l issue	es in su	upporti	ng dep	artment	s of hosp	oitals
CO5	Unde	Identify Information management systems and issues in supporting departments of hospitals Understand safety procedures followed in hospitals													
MAPPING OF COs WITH POs AND PSOs															
				DR	OGR			MES		•)			PROG	RAM SP	ECIFIC
COs	;			OUTC	OMES (	PSOs)									
	PO	1 PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO2	3	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO3	3	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO4	3	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO5	3	3	3	3	2			1		2	2	2	1	1	1

			1		
OEC103	BASICS OF EMBEDDED SYSTEMS AND IOT	L	Т	Ρ	С
		3	0	0	3
OBJECTIVES:					
	d the concepts of embedded system design and analysis				
	architecture and programming of ARM processor d to the basic concepts of embedded programming				
•	concepts of IOT				
C Lean the					
UNIT I	INTRODUCTION TO EMBEDDED SYSTEM				9
methodologies- D	s and microprocessors– Embedded system design besign flows - Requirement Analysis – Specifications-Sy n – Quality Assurance techniques–Design example: Model t	/ster	n ar	nalysis	s and
UNIT II	BASICS OF ARM ARCHITECTURE AND PERIPHEN	RAL			9
Features of the L	Versions – ARM Architecture – Instruction Set – Stacks PC 214X Family – Peripherals – The Timer Unit – Pulse W Diagram of ARM9 and ARM Cortex M3 MCU				
	EMBEDDED PROGRAMMING CONCEPTS				9
compilation tech optimization – Pr	embedded programs- Models of programs- Assembly, lin niques- Program level performance analysis – Sof rogram level energy and power analysis and optimizati ogram size- Program validation and testing	twar	e p	erforn	nance
	INTRODUCTION TO IOT				
domains - Differe	of an IoT system - Basics of Physical and logical design on the sensors - Difference between IoT - Passive and active sensors - Differend hardware Case Studies – Smart Parking, Air Pollution	rent	арр	licatio	
UNIT V	COMMUNICATION PROTOCOLS FOR EMBEDDED A	AND			9
protocols- RS485	orking: Introduction-Serial/Parallel Communication - Se - Synchronous Serial Protocols - Serial Peripheral Inte (I2C). IoT Infrastructure - 6LowPAN - IPv6 - Wi-Fi, Bluetoo	erfac	e (S	SPI) -	
	ТО	TAL	: 60	PERI	ODS
TEXT BOOKS:					
1. Marilyn Wo Designll, 1 (UNIT I, II,	olf, —Computers as Components - Principles of Embedded hird Edition —Morgan Kaufmann Publisher (An imprint fr III, IV) Bahga, Vijay Madisetti, "Internet of Things, A Hands-on-Ap	om	Elsev	/ier),	2012.
	s press Pvt. Ltd., India, 2015.	piùa	UT,	151 2	union,
3. Daniel Mir	noli, "Building the Internet of Things with IPv6 and MIPv6 ons", Inc, USA, 2013	6, 1s	st Ec	lition,	John
<b>REFERENCES:</b>					
1. Adrian Mo	Ewen and Hakim Cassimally, "Designing the Internet of <sup>-</sup> / & Sons Ltd, UK, 2014	Thing	gs", <sup>-</sup>	1st E	dition,
2. Peter Wah 3. Charles B Apress Pu	er, "Learning Internet of Things", 1st Edition, Packt Publishi ell, "Beginning Sensor Networks with Arduino and Raspbe blishers, USA, 2013.	rry F	۶j",	1st E	dition,
4. Raj Kamal	, Internet of Things, Architecture and Design Principles, McC	raw	/-HIII	, 201	1

COURS By the e				e, the	e stu	dent	shou	ld be	able	to:					
CO1	Unc	dersta	nd th	e Em	bedd	ed Sy	ystem	n Des	ign P	rocess	6				
CO2	Des	cribe	the a	rchite	ecture	e and	prog	ramm	ning o	f ARM	1 proce	essor			
CO3	Out	line th	ne co	ncept	s of e	embe	dded	syste	em pro	ogram	ming				
CO4		lain t						•	•	*					
CO5	Мо	del Ne	etwor	ked s	ysten	ns wi	th bas	sic pr	otoco	ls					
				M	<b>APPII</b>	NG O	F CO	s Wi	TH P	Os AN		Os			
COs	MAPPING OF COS WITH POS AND PSOS         PROGRAM OUTCOMES (POS)       PROGRAM SPECIFIC OUTCOMES (PSOs)														
	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PO	PSO	PSO	PSC
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	2	3	-	2	1	2	-	1	2	2	3	3	2
CO2	3	3	2	3	-	3	1	2	-	1	2	2	3	3	2
CO3	3	3	2	3	3	3	1	2	1	1	2	2	3	3	2
CO4	3	3	3	3	-	2	1	2	-	1	2	2	3	3	2
CO5	3	3	3	3	2	3	1	2	1	1	2	2	3	3	2

OEE101	BASIC CIRCUIT THEORY	• Т	С
	3 (		3
OBJECTIVES			
	troduce electric circuits and its analysis		
	part knowledge on solving circuit equations using network theorems		
	troduce the phenomenon of resonance in coupled circuits.		
	troduce Phasor diagrams and analysis of three phase circuits		
UNITI	BASIC CIRCUITS ANALYSIS		9
Resistive elem	ents - Resistors in series and parallel circuits; Ohm's Law; Kirchoffs laws –		
	alysis-Mesh current and node voltage.	CC	)1
UNIT II	NETWORK REDUCTION AND THEOREMS FOR DC CIRCUITS	<u></u>	9
conversion; Ne	ction-voltage and current division, source transformation, star delta etwork theorems- Thevenins and Norton Theorems, Superposition Theorem, er transfer theorem, Reciprocity Theorem, Millman's theorem.	cc	)2
UNIT III	ANALYSIS OF AC CIRCUITS		9
reductions- vol Network theore	tage and current division, source transformation; Mesh and node analysis; ems- Thevenins and Norton Theorems, Superposition Theorem, Maximum theorem, Reciprocity Theorem, Millman's theorem.	cc	)3
UNIT IV	THREE PHASE CIRCUITS		9
A.C. circuits –	Average and RMS value, Phasor Diagram, Power, Power Factor and Energy;		<u> </u>
•	ee phase 3-wire and 4-wire circuits with star and delta connected loads, balanced; phasor diagram of voltages and currents; power measurement in cuits.	cc	)4
UNIT V	RESONANCE AND COUPLED CIRCUITS		9
•	allel resonance – frequency response, Quality factor and Bandwidth; Self and nce; Coefficient of coupling; Tuned circuits – Single tuned circuits.	cc	)5
	TOTAL : 45 F	PERIC	DS
TEXT BOOKS			
McGrav 2. Charles	H. Hayt Jr, Jack E. Kemmerly and Steven M. Durbin, "Engineering Circuits A v Hill publishers, edition, New Delhi, 2013. K. Alexander, Mathew N.O. Sadiku, "Fundamentals of Electric Circuits McGraw Hill, 2013.	-	
	. Robbins, Wilhelm C. Miller, "Circuit Analysis Theory and Practice", Cengage L	.earni	ng

### **REFERENCE BOOKS** 1. Chakrabarti A, "Circuits Theory (Analysis and synthesis), Dhanpath Rai & Sons, New Delhi, 1999. 2. Jegatheesan, R., "Analysis of Electric Circuits," McGraw Hill, 2015. 3. Joseph A. Edminister, Mahmood Nahri, "Electric circuits", Schaum's series, McGraw- Hill, New Delhi, 2010. 4. M E Van Valkenburg, "Network Analysis", Prentice-Hall of India Pvt Ltd, New Delhi, 2015. 5. Mahadevan, K., Chitra, C., "Electric Circuits Analysis," Prentice-Hall of India Pvt Ltd., New Delhi, 2015. 6. Richard C. Dorf and James A. Svoboda, "Introduction to Electric Circuits", 7th Edition, John Wiley & Sons, Inc. 2015. 7. Sudhakar A and Shyam Mohan SP, "Circuits and Network Analysis and Synthesis", McGraw Hill, 2015. **COURSE OUTCOMES** Upon completion of the course, students will be able to Ability to introduce electric circuits and its analysis CO1 CO2 Ability to impart knowledge on solving circuit equations using network theorems CO3 Ability to introduce the phenomenon of resonance in coupled circuits. Ability to introduce Phasor diagrams and analysis of three phase circuits CO4 Ability to impart knowledge on resonance and coupled circuits CO<sub>5</sub> **MAPPING OF COs WITH POs AND PSOs PROGRAM SPECIFIC PROGRAM OUTCOMES (POs) OUTCOMES (PSOs)** COs

	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1	1	3	3	3	1	1	1	3	1	1	1
CO2	3	3	3	3	3	3	3	3	3	1	3	3	3	3	3
CO3	3	3	3	3	3	3	3	3	3	1	3	3	3	3	3
CO4	3	3	3	3	3	3	2	3	3	1	2	3	3	3	3
CO5	3	3	3	3	3	3	2	3	3	1	2	3	3	3	3

OEE103	INTRODUCTION TO RENEWABLE ENERGY SYSTEMS	L	Ρ	Т	С
		3	0	0	3
OBJECTIVES	· · · · · ·			1	I
<ul> <li>About t</li> </ul>	he stand alone and grid connected renewable energy systems.				
<ul> <li>Design</li> </ul>	of power converters for renewable energy applications.				
<ul> <li>Wind el</li> </ul>	ectrical generators and solar energy systems.				
Power of the second	converters used for renewable energy systems.				
UNIT I	INTRODUCTION				0,
generation on energy resourd	aspects of electric energy conversion: impacts of renewable en environment (cost-GHG Emission) - Qualitative study of different renew ces: Solar, wind, ocean, Biomass, Fuel cell, Hydrogen energy systems ble energy systems.	/abl	e	СС	)1
UNIT II	ELECTRICAL MACHINES FOR RENEWABLE ENERGY CONVERSIO	N			Ģ
Reference theo	bry fundamentals-principle of operation and analysis: IG and PMSG			CC	2
UNIT III	POWER CONVERTERS				ç
converters (inv	agram of solar photo voltaic system -Principle of operation: line commut ersion-mode) - Boost and buck-boost converters- selection of inverter, ba zing Wind: Three phase AC voltage controllers			CC	)3
UNIT IV	ANALYSIS OF WIND AND PV SYSTEMS				0,
-	eration of fixed and variability speed wind energy conversion systems Grid connection Issues -Grid integrated PMSG, SCIG Based WECS, r system			СС	94
UNIT V	HYBRID RENEWABLE ENERGY SYSTEMS				g
•	id Systems- Range and type of Hybrid systems- Case studies of Wind er Point Tracking (MPPT).	d-P'	V	СС	95
	TOTAL	: 45	5 PE	RIO	DS
TEXT BOOKS					
	nadra, D.Kastha, S.Banerjee, "Wind Electrical Systems", Oxford University an, "Non-conventional Energy Sources", Tata McGraw-hill Publishing C 017.				

			<u> </u>												
REFER	ENCE	BOO	٨S												
	Muham Heinem				d, "F	Power	Ele	ctroni	cs H	and	Book",	Third	Editio	n, Butte	erworth-
		-			Speed	Gen	erator	s", Se	econd	Editio	n, CRC	C Press	s, 2015.		
3.	Rai. G.I	D, "No	on- co	nvent	ional	Energ	y So	urces	', Kha	nna Pi	ublishe	ers, 200	)4.		
4.	Gray, L	. Johr	nson,	"Winc	l Ener	rgy Sy	/stem	s", Pr	entice	Hall, 2	2006.				
	Andrzej WileyIn		-			, "Inti	roduc	tion	to Mo	odern	Powe	r Elec	tronics",	Third	Edition,
COURS	SE OUT	сом	ES												
Upon c	omplet	tion o	f the	cours	se, st	udent	s wil	l be a	ble to	)					
CO1	Ability	to un	dersta	and a	nd an	alyze	powe	r syst	em op	peratio	n, stab	oility, co	ontrol an	d protec	tion.
CO2	Ability	to ha	ndle t	he en	ginee	ering a	spec	ts of e	electric	cal ene	ergy ge	neratio	on and u	tilization.	1
CO3	Ability	to un	dersta	and th	ie stai	nd alc	one ar	nd grio	d conr	nected	renew	able ei	nergy sy	stems.	
CO4	Ability	to de	sign d	of pow	/er co	nverte	ers fo	r rene	wable	energ	gy appl	ication	s.		
CO5	Ability	to ac	quire	know	ledge	on wi	ind el	ectrica	al gen	erator	s and s	solar er	nergy sy	stems.	
				Μ	APPI	NG O	F CO	s WI	гн рс	)s ANI	D PSO	s			
COs				PR	OGR/		UTCC	MES	(POs	)				RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1	1	3	3	3	1	1	1	3	1	1	1
CO2	3	3	3	3	3	3	3	3	3	1	3	3	3	3	3
CO3	3	3	3	3	3	3	3	3	3	1	3	3	3	3	3
CO4	3	3	3	3	3	3	2	3	3	1	2	3	3	3	3
CO5	3	3	3	3	3	3	2	3	3	1	2	3	3	3	3

OEI102	ROBOTICS	L	Т	Ρ	С
		3	0	0	3
OBJECTIVE					
<ul> <li>To under</li> </ul>	erstand the functions of the basic components of a Robot.				
<ul> <li>To stud</li> </ul>	y the use of various types of End of Effectors and Sensors				
•	art knowledge in Robot Kinematics and Programming				
<ul> <li>To learn</li> </ul>	n Robot safety issues and economics.				
UNIT I	FUNDAMENTALSOF ROBOT				9
Classification-	nition - Robot Anatomy - Coordinate Systems, Work Envelope Typ Specifications-Pitch, Yaw, Roll, Joint Notations, Speed of Motion, Pay ad their Functions-Need for Robots-Different Applications.			C	D1
UNIT II	ROBOT DRIVE SYSTEMS ANDEND EFFECTORS				9
Stepper Motors Drives, End I Magnetic Grip	ives-Hydraulic Drives-Mechanical Drives-Electrical Drives-D.C. Servo s, A.C. Servo Motors-Salient Features, Applications and Comparison of a Effectors-Grippers-Mechanical Grippers, Pneumatic and Hydraulic- G pers, Vacuum Grippers; Two Fingered and Three Fingered Grippers; External Grippers; Selection and Design Considerations.	all th iripp	ese ers,	C	02
UNIT III	SENSORS AND MACHINEVISION				9
sensors - Pie Sensors, Rang Flight, Range I Wrist Sensors Digitizing Ima Processing a	of a sensor, Principles and Applications of the following types of sensors- zo Electric Sensor, LVDT, Resolvers, Optical Encoders, pneumatic ge Sensors Triangulations Principles, Structured, Lighting Approach, Finders, Laser Range Meters, Touch Sensors ,binary Sensors., Analog S , Compliance Sensors, Slip Sensors, Camera, Frame Grabber, Sensi ge Data- Signal Conversion, Image Storage, Lighting Techniques, nd Analysis-Data Reduction, Segmentation, Feature Extraction, Other Algorithms, Applications- Inspection, Identification, Visual Servi	Posi Fime Sense Ing a Ima Ob	tion e of ors, and age ject	C	03
UNIT IV	ROBOT KINEMATICS AND ROBOTPROGRAMMING				9
Kinematics of Degrees of fre Trajectory Gen Programming,	natics, Inverse Kinematics and Difference; Forward Kinematics and F manipulators with Two, Three Degrees of Freedom (in 2 Dimension eedom (in 3 Dimension) Jacobians, Velocity and Forces-Manipulator Dy herator, Manipulator Mechanism Design-Derivations and problems. Lead Robot programming Languages-VAL Programming-Motion Commands, and Effector commands and simple Programs.	n), F nam thro	our ics, ugh	C	<b>D</b> 4
UNIT V	IMPLEMENTATION ANDROBOTECONOMICS				9
	nplementation of Robots in Industries-Various Steps; Safety Considerat	ions	for	C	<b>D</b> 5
	TOTAL	. : 45	5 PE	RIO	DS
TEXT BOOKS				_	
	R.D., Chmielewski T.A and Negin M., "Robotic Engineering - An Integra e Hall, 2003.	ated	Арр	roa	ch",

2. Groover M.P., "Industrial Robotics -Technology Programming and Applications", McGraw Hill, 2001.

#### REFERENCE BOOKS

- 1. Craig J.J., "Introduction to Robotics Mechanics and Control", Pearson Education, 2008.
- 2. Deb S.R., "Robotics Technology and Flexible Automation" Tata McGraw Hill Book Co., 1994.
- 3. Koren Y., "Robotics for Engineers", Mc Graw Hill Book Co., 1992.
- 4. Fu.K.S.,Gonzalz R.C. and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw Hill Book Co., 1987.
- 5. Janakiraman P.A., "Robotics and Image Processing", Tata McGraw Hill, 1995.
- 6. Rajput R.K., "Robotics and Industrial Automation", S.Chand and Company, 2008.
- 7. Surender Kumar, "Industrial Robots and Computer Integrated Manufacturing", Oxford and IBH Publishing Co. Pvt. Ltd.,1991.

### **COURSE OUTCOMES**

### Upon completion of the course, students will be able to

CO1 Understand the functions of the basic components of a Robot.

CO2 Study the use of various types of End of Effectors and Sensors

CO3 Understand Sensors and Machine Vision of Robot

CO4 Understand Robot Kinematics and Robot Programming

CO5 Understand the Implementation of Robots in Industries

### MAPPING OF COS WITH POS AND PSOS

COs				PF	ROGR	RAM C	оитс	OME	S (PO	s)				RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	2	1	2	2	-	-	-	-	2	2	3	2	1	2
CO2	3	3	1	2	2	-	-	-	-	2	2	3	3	2	2
CO3	3	3	1	2	2	-	-	-	-	2	2	3	3	2	2
CO4	3	2	1	2	2	-	-	-	-	2	2	3	3	2	2
CO5	2	2	1	2	2	-	-	-	-	2	2	3	2	2	2

UNIT IINTRODUQuality – vision, missionquality, Translating needservice quality. Cost of quality. Cost of quality.UNIT IIPRINCIPOverview of the contributTaguchi techniques – innoise ratio. Concepts of Quality.UNIT IIISTATIST	ty philosophies and tools in the managerial perspective. UCTION n and policy statements. Customer Focus – customer perception of ds into requirements, customer retention. Dimensions of product and	
<ul> <li>To learn the quality</li> <li>UNIT I</li> <li>INTRODIC</li> <li>Quality – vision, mission</li> <li>quality, Translating need</li> <li>service quality. Cost of quality. Cost of quality.</li> <li>UNIT II</li> <li>PRINCIP</li> <li>Overview of the contribut</li> <li>Taguchi techniques – in</li> <li>noise ratio. Concepts of Quality.</li> <li>UNIT III</li> <li>STATIST</li> </ul>	UCTION In and policy statements. Customer Focus – customer perception of Its into requirements, customer retention. Dimensions of product and uality. PLES AND PHILOSOPHIES OF QUALITY MANAGEMENT tions of Deming, Juran Crosby, Masaaki Imai, Feigenbaum, Ishikawa, atroduction, loss function, parameter and tolerance design, signal to	CO
UNIT IINTRODQuality – vision, missionquality, Translating needservice quality. Cost of quality. Cost of quality.UNIT IIPRINCIPOverview of the contributTaguchi techniques – innoise ratio. Concepts of Quality.UNIT IIISTATIST	UCTION In and policy statements. Customer Focus – customer perception of Its into requirements, customer retention. Dimensions of product and uality. PLES AND PHILOSOPHIES OF QUALITY MANAGEMENT tions of Deming, Juran Crosby, Masaaki Imai, Feigenbaum, Ishikawa, atroduction, loss function, parameter and tolerance design, signal to	CO
Quality – vision, missionquality, Translating needservice quality. Cost of quality. Cost of quality.UNIT IIPRINCIPOverview of the contributTaguchi techniques – innoise ratio. Concepts of Quality.UNIT IIISTATIST	n and policy statements. Customer Focus – customer perception of ds into requirements, customer retention. Dimensions of product and uality. PLES AND PHILOSOPHIES OF QUALITY MANAGEMENT tions of Deming, Juran Crosby, Masaaki Imai, Feigenbaum, Ishikawa, atroduction, loss function, parameter and tolerance design, signal to	CO
quality, Translating need service quality. Cost of quality. Cost of quality. Cost of quality.UNIT IIPRINCIPOverview of the contribut Taguchi techniques – in noise ratio. Concepts of Quality of Quality.UNIT IIISTATIST	As into requirements, customer retention. Dimensions of product and uality. PLES AND PHILOSOPHIES OF QUALITY MANAGEMENT tions of Deming, Juran Crosby, Masaaki Imai, Feigenbaum, Ishikawa, httroduction, loss function, parameter and tolerance design, signal to	
Overview of the contribut Taguchi techniques – in noise ratio. Concepts of C UNIT III STATIST	ions of Deming, Juran Crosby, Masaaki Imai, Feigenbaum, Ishikawa, atroduction, loss function, parameter and tolerance design, signal to	
Taguchi techniques – in noise ratio. Concepts of CUNIT IIISTATIST	troduction, loss function, parameter and tolerance design, signal to	<u> </u>
		CO
Maaning and significance	TICAL PROCESS CONTROL	
variables and attributed. sigma - concepts of proce parallel, product life	s process Improvement (BPI) – principles, applications, reengineering	CO
UNIT IV TOOLS /	AND TECHNIQUES FOR QUALITY MANAGEMENT	
House of quality (HOQ), requirements of reliabilit	oment (QFD) – Benefits, Voice of customer, information organization, building a HOQ, QFD process. Failure mode effect analysis (FMEA) – ty, failure rate, FMEA stages, design, process and documentation. . Bench marking and POKA YOKE.	CO
UNIT V QUALITY	Y SYSTEMS ORGANIZING AND IMPLEMENTATION	
improvements. Quality	04:2000 – quality management systems – guidelines for performance Audits. TQM culture, Leadership – quality council, employee empowerment, recognition and reward - TQM framework, benefits, s.	CO

TEXT	BO	OKS														
1.	Da	le H.	Beste	erfield	Carc	l Bes	terfiel	d – M	lichna	. Gler	H. Be	sterfie	ld. Ma	ry Bester	field –	
															nt, Revis	sed
				Pear									2	C		
2.	Sh	ridha	ira Bh	at K,	Total	Quali	ty Ma	nager	ment -	- Text	t and C	Cases,	Himala	aya Publ	ishing Ho	ouse,
	Fir	st Ed	lition 2	2002.												
REFE	REN		BOO	٨S												
1.		•		/lontgo y India	-				Statis	tical C	Quality	Contro	ol, Wile	ey Stude	nt Editior	n, 4th
2.				ans a nson,			M. Lir	ndsay	, The	Mana	gemer	nt and	Contro	l of Qua	lity, Sixth	l
3.		ornin					tal Qu	uality	Mana	geme	nt, Pea	arson I	Educat	ion, First	: Indian F	Reprint
4.					• •		•		ystem rds, N			es for	perforr	nance in	nprovem	ent
COUR	SE	OUT	СОМ	ES												
At the	enc	d of t	he co	ourse	, the	stude	nt sh	ould	be ab	ole:						
CO1			ly qu er deli	•	philos	ophie	es an	d too	ols to	facilit	tate co	ontinuc	ous im	proveme	ent and	ensure
CO2	То	unde	erstan	d the	princ	ples o	of bus	iness	proce	ess im	prove	ment				
CO3	То	unde	erstan	nd and	l appl	y the	conce	epts of	f statis	stical	proces	s cont	rol			
CO4	То	appl	y the	tools	and te	chnic	ques ι	used f	or qua	ality m	nanage	ement				
CO5	То	unde	erstan	d the	meth	ods ir	orga	nizing	g and	imple	mentat	tion of	quality	systems	6	
					Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	s			
COs					PR	OGRA		UTCC	MES	(POs	5)				RAM SP OMES (	
		PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1		3	2	3	3	3	-	-	-	-	2	2	2	1	1	1
CO2		3	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO3		3	3	2	3	3	-	-	-	-	2	2	2	1	1	1
CO4		2	3	3	3	2	-	-	-	-	2	2	2	1	1	1
CO5		3	3	2	3	2	-	-	-	-	2	2	2	1	1	1

OME104	INDUSTRIAL SAFETY ENGINEERING	Р	С
	3 0	0	3
OBJECTIVES			
•	ovide exposure to the students about safety and health provisions related to haze uses as laid out in Factories act 1948	ardo	ous
<ul> <li>To fan</li> </ul>	niliarize students with powers of inspectorate of factories		
<ul> <li>To hel</li> </ul>	p students to learn about Environment act 1986 and rules framed under the act.		
<ul> <li>To pro unit.</li> </ul>	vide wide exposure to the students about various legislations applicable to an inc	dustr	rial
<ul> <li>To pre</li> </ul>	pare onsite and offsite emergency plan.		
UNIT I	FACTORIES ACT – 1948	9	)
processes, w	horities – inspecting staff, health, safety, provisions relating to hazardous elfare, working hours, employment of young persons – special provisions – procedures-Tamil Nadu Factories Rules 1950 under Safety and health chapters ct 1948	co	D1
UNIT II	ENVIRONMENT ACT – 1986	g	)
environmenta pollution (Reg Rules) 2001- Act 1981 and pollution-powe	vers of the central government, prevention, control and abatement of I pollution-Biomedical waste (Management and handling Rules, 1989-The noise gulation and control) Rules, 2000-The Batteries (Management and Handling No Objection certificate from statutory authorities like pollution control board. Air Water Act 1974: Central and state boards for the prevention and control of air ers and functions of boards – prevention and control of air pollution and water	co	02
poliution – tur	d – accounts and audit, penalties and procedures.		
UNIT III		g	•
<b>UNIT III</b> Definitions – o – information	d – accounts and audit, penalties and procedures. MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL	e co	
Definitions – o – information toxic chemica	accounts and audit, penalties and procedures.         MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989         duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and		03
Definitions – o – information toxic chemica UNIT IV Indian Boiler mines act 19 wastes (mana	ad – accounts and audit, penalties and procedures.         MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989         duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and ls – safety reports – safety data sheets.         OTHER ACTS AND RULES         Act 1923, static and mobile pressure vessel rules (SMPV), motor vehicle rules, 52, workman compensation act, rules – electricity act and rules – hazardous agement and handling) rules, 1989, with amendments in 2000- the building and ction workers act 1996., Petroleum rules, Gas cyclinder rules-Explosives Act	co	03
UNIT III Definitions – o – information toxic chemica UNIT IV Indian Boiler mines act 19 wastes (mana other constru 1983-Pesticid	ad – accounts and audit, penalties and procedures.         MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989         duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and ls – safety reports – safety data sheets.         OTHER ACTS AND RULES         Act 1923, static and mobile pressure vessel rules (SMPV), motor vehicle rules, 52, workman compensation act, rules – electricity act and rules – hazardous agement and handling) rules, 1989, with amendments in 2000- the building and ction workers act 1996., Petroleum rules, Gas cyclinder rules-Explosives Act	CC	D3
UNIT III Definitions – o – information toxic chemica UNIT IV Indian Boiler mines act 19 wastes (mana other constru 1983-Pesticid UNIT V Occupational	<ul> <li>accounts and audit, penalties and procedures.</li> <li>MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989</li> <li>duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and ls – safety reports – safety data sheets.</li> <li>OTHER ACTS AND RULES</li> <li>Act 1923, static and mobile pressure vessel rules (SMPV), motor vehicle rules, 52, workman compensation act, rules – electricity act and rules – hazardous agement and handling) rules, 1989, with amendments in 2000- the building and ction workers act 1996., Petroleum rules, Gas cyclinder rules-Explosives Act es Act</li> <li>INTERNATIONAL ACTS AND STANDARDS</li> <li>Safety and Health act of USA (The Williames - Steiger Act of 1970) – Health and act (HASAWA 1974, UK) – OSHAS 18000 – ISO 14000 – American National</li> </ul>	cc 9 cc	D3
UNIT III Definitions – o – information toxic chemica UNIT IV Indian Boiler mines act 19 wastes (mana other constru 1983-Pesticid UNIT V Occupational safety work a	<ul> <li>accounts and audit, penalties and procedures.</li> <li>MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989</li> <li>duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and ls – safety reports – safety data sheets.</li> <li>OTHER ACTS AND RULES</li> <li>Act 1923, static and mobile pressure vessel rules (SMPV), motor vehicle rules, 52, workman compensation act, rules – electricity act and rules – hazardous agement and handling) rules, 1989, with amendments in 2000- the building and ction workers act 1996., Petroleum rules, Gas cyclinder rules-Explosives Act es Act</li> <li>INTERNATIONAL ACTS AND STANDARDS</li> <li>Safety and Health act of USA (The Williames - Steiger Act of 1970) – Health and act (HASAWA 1974, UK) – OSHAS 18000 – ISO 14000 – American National</li> </ul>		D3 D4 D5
UNIT III Definitions – o – information toxic chemica UNIT IV Indian Boiler mines act 19 wastes (mana other constru 1983-Pesticid UNIT V Occupational safety work a	accounts and audit, penalties and procedures.         MANUFACTURE, STORAGE AND IMPORT OF HAZARDOUS CHEMICAL RULES 1989         duties of authorities – responsibilities of occupier – notification of major accidents to be furnished – preparation of offsite and onsite plans – list of hazardous and ls – safety reports – safety data sheets.         OTHER ACTS AND RULES         Act 1923, static and mobile pressure vessel rules (SMPV), motor vehicle rules, 52, workman compensation act, rules – electricity act and rules – hazardous agement and handling) rules, 1989, with amendments in 2000- the building and ction workers act 1996., Petroleum rules, Gas cyclinder rules-Explosives Act es Act         INTERNATIONAL ACTS AND STANDARDS         Safety and Health act of USA (The Williames - Steiger Act of 1970) – Health and act (HASAWA 1974, UK) – OSHAS 18000 – ISO 14000 – American National titute (ANSI).		D3 D4 D5

2.	The Er Delhi.	nviron	ment	Act (	Prote	ction)	198	6, Co	mmei	rcial La	aw Pu	blisheı	rs (India	) Pvt.Lto	I., New
3.	Water Pvt.Ltd	•			cont	rol of	f polli	ution)	act	1974,	Comm	nercial	Law pu	ıblishers	(India)
REFEF	ENCE	BOOI	٢S												
1.	Air (Pre New De		on an	d con	trol of	f pollu	ition)	act 19	981, C	Comme	ercial L	.aw Pu	Iblishers	(India) F	vt.Ltd.,
2.	The Inc	lian b	oilers	act 19	923, C	Comm	ercial	Law	Publis	shers (	India)	Pvt.Ltd	I., Allaha	bad.	
3.	The ma Chenna		ture,	storaç	ge and	d impo	ort of	hazar	dous	chemi	cal rule	es 1989	9, Madra	is Book A	Agency,
COUR	SE OUT	сом	ES												
Upon o	complet	tion o	f the	cours	se, st	udent	ts will	l be a	ble to	)					
CO1	To li	st out	impoi	rtant l	egisla	tions	relate	ed to h	nealth,	, Safet	y and I	Enviror	nment.		
CO2	To li	st out	requi	remer	nts me	ention	ed in	factor	ries ad	ct for th	ne prev	vention	of accid	ents.	
CO3	To u	nders	tand t	he he	alth a	ind we	elfare	provi	sions	given i	n facto	ories a	ct.		
CO4	To u rene		tand t	he sta	atutor	y requ	uireme	ents fo	or an	Industr	y on re	egistrat	tion, licei	nse and	its
CO5	То р	repar	e onsi	te an	d offsi	te em	nerger	ncy pl	an.						
				Μ	APPI	NG O	F CO	s WI	ГН РС	)s AN[	) PSO	s			
COs				PR	OGR/		итсс	MES	(POs	;)				RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	2	1	-	-	1	2	2	2	2	1	2	2	1	1	1
CO2	2	1	-	-	1	2	2	2	2	1	2	2	1	1	1
CO3	2	1	-	-	1	2	2	2	2	1	2	2	1	1	1
CO4	2	1	-	-	1	2	2	2	2	1	2	2	1	1	1
CO5	2	2	-	-	1	2	2	2	2	2	2	2	1	1	1

# AUDIT COURSES

AD1001	CONSTITUTION OF INDIA	Ρ	С
	2 0	0	0
OBJECTIVE	S		
• Tead	ch history and philosophy of Indian Constitution.		
	cribe the premises informing the twin themes of liberty and freedom from a civil pective.	rig	ht
• Sum	marize powers and functions of Indian government.		
• Expl	ain emergency rule.		
• Expl	ain structure and functions of local administration.		
UNIT I	INTRODUCTION		ę
History of M	aking of the Indian Constitution-Drafting Committee- (Composition & Working) -		
-	f the Indian Constitution-Preamble-Salient Features	С	0
	CONTOURS OF CONSTITUTIONAL RIGHTS & DUTIES		!
	CONTOURS OF CONSTITUTIONAL RIGHTS & DUTIES		!
<b>UNIT II</b> Fundamenta Freedom of		С	
UNIT II Fundamenta Freedom of Directive Prir	CONTOURS OF CONSTITUTIONAL RIGHTS & DUTIES	С	
UNIT II Fundamenta Freedom of Directive Prir UNIT III Parliament-C President-Go	CONTOURS OF CONSTITUTIONAL RIGHTS & DUTIES	C	02
UNIT II Fundamenta Freedom of Directive Prir UNIT III Parliament-C President-Go	CONTOURS OF CONSTITUTIONAL RIGHTS & DUTIES         I Rights-Right to Equality-Right to Freedom-Right against Exploitation Right to Religion-Cultural and Educational Rights-Right to Constitutional Remedies inciples of State Policy-Fundamental Duties         ORGANS OF GOVERNANCE         Composition-Qualifications and Disqualifications-Powers and Functions-Executive overnor-Council of Ministers-Judiciary, Appointment and Transfer of Judges,		02

# UNIT V LOCAL ADMINISTRATION

District's Administration head- Role and Importance-Municipalities- Introduction- Mayor and role of Elected Representative-CEO of Municipal Corporation-Pachayati raj- Introduction- PRI-Zila Pachayat-Elected officials and their roles- CEO ZilaPachayat- Position and role-Block level Organizational Hierarchy (Different departments)-Village level- Role of Elected and Appointed officials-Importance of grass root democracy

TOTAL: 45 PERIODS

TEXT BOOKS

- 1. Basu D D, Introduction to the Constitution of India, Lexis Nexis, 2015.
- 2. Busi S N, Ambedkar B R framing of Indian Constitution, 1st Edition, 2015.
- 3. Jain M P, Indian Constitution Law, 7th Edn., Lexis Nexis, 2014.
- 4. The Constitution of India (Bare Act), Government Publication, 1950

### COURSE OUTCOMES

### Upon completion of the course, students will be able to

- CO1 Able to understand history and philosophy of Indian Constitution.
- CO2 Able to understand the premises informing the twin themes of liberty and freedom from a civil rights perspective.
- CO3 Able to understand powers and functions of Indian government.

CO4 Able to understand emergency rule.

CO5 Able to understand structure and functions of local administration.

# MAPPING OF COs WITH POs AND PSOs

COs				PRC	OGRA	MOL	JTCO	MES	(POs)	)				RAM SP OMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-
CO2	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-
CO3	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-
CO4	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-
CO5	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-

9

AD1002	VALUE EDUCATION L T	Ρ	С
	2 0	0	0
OBJECTIVE	S Contraction of the second		
• Dev	elop knowledge of self-development		
• Exp	ain the importance of Human values		
• Dev	elop the overall personality through value education		
• Ove	rcome the self-destructive habits with value education		
<ul> <li>Inter</li> </ul>	pret social empowerment with value education		
UNIT I	INTRODUCTION TO VALUE EDUCATION		9
Values and	self-development –Social values and individual attitudes, Work ethics, Indian vision		-
of humanisn	n, Moral and non- moral valuation, Standards and principles, Value judgments	C	01
UNIT II	IMPORTANCE OF VALUES	1	9
	IMPORTANCE OF VALUES		
Importance Concentration		с	
Concentratio	of cultivation of values, Sense of duty, Devotion, Self-reliance, Confidence, on, Truthfulness, Cleanliness. Honesty, Humanity, Power of faith, National Unity,	C	02
Importance of Concentration Patriotism, L UNIT III Personality Integrity and	of cultivation of values, Sense of duty, Devotion, Self-reliance, Confidence, on, Truthfulness, Cleanliness. Honesty, Humanity, Power of faith, National Unity, ove for nature, Discipline INFLUENCE OF VALUE EDUCATION and Behaviour development - Soul and Scientific attitude. Positive Thinking, discipline, Punctuality, Love and Kindness, Avoid fault Thinking, Free from anger, bour, Universal brotherhood and religious tolerance, True friendship Happiness Vs		02
Importance of Concentration Patriotism, L <b>UNIT III</b> Personality Integrity and Dignity of late	of cultivation of values, Sense of duty, Devotion, Self-reliance, Confidence, on, Truthfulness, Cleanliness. Honesty, Humanity, Power of faith, National Unity, ove for nature, Discipline INFLUENCE OF VALUE EDUCATION and Behaviour development - Soul and Scientific attitude. Positive Thinking, discipline, Punctuality, Love and Kindness, Avoid fault Thinking, Free from anger, bour, Universal brotherhood and religious tolerance, True friendship Happiness Vs		

UNIT V		VALU	JE ED	UCA	TION	IN SC	DCIAL	_ EMF	POWE	RMEN	IT					9	
Equality Mind, S									l relig	ions ai	nd san	ne mes	ssage, N	1ind your	со	•5	
				y, 5tu	aying	enec	lively						ΤΟΤΑ	L : 45 PE		S	
REFER	ENCE	:															
Chakro	borty ,	S.K. "\	/alues	s and	Ethics	s for c	organi	zatior	ns The	eory an	d prac	tice", C	Dxford				
Univers	sity Pre	ss ,Ne	w Del	hi													
COURS		тсом	ES														
Upon c				cours	se, sti	ıdent	s will	be a	ble to								
-	-																
CO1		Gain knowledge of self-development															
CO2	Learn the importance of Human values																
CO3	Deve	elop the	e over	all pe	rsona	lity th	rough	value	e educ	cation							
CO4	Over	come	the se	elf des	tructiv	/e hat	oits wi	ith val	ue ed	lucatio	n						
CO5	Inter	pret so	cial e	mpow	erme	nt with	n valu	ie edu	catior	า							
				N	IAPPI	NG O	F CO	s WI	ГН РС	)s ANI	D PSO	S					
									(20)				PROG	RAM SP	ECIFI	C	
COs			PROGRAM OUTCOMES (POs)											OUTCOMES (PSOs			
	P01	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO	3	
CO1	-	-	-	-	-	-	1	1	-	-	-	1	-	-	-		
CO2	-	-	-	-	-	-	1	1	1	-	-	1	-	-	-	_	
CO3	-	-	-	-	-	-	1	1	1	-	-	1	-	-	-		
CO4	-	-	-	-	-	-	1	1	-	-	-	1	-	-	-		
						l						l				-	

AD1003	PEDAGOGY STUDIES L T	Ρ	С
	2 0	0	0
OBJECTIVE	ES		
• Und	erstand the methodology of pedagogy.		
<ul> <li>Con</li> </ul>	npare pedagogical practices used by teachers in formal and informal classroo	oms	ir
deve	eloping countries.		
<ul> <li>Infe</li> </ul>	r how can teacher education (curriculum and practicum) and the school curriculu	ma	anc
•	lance materials best support effective pedagogy.		
<ul> <li>Illus</li> </ul>	trate the factors necessary for professional development.		
• Ider	tify the Research gaps in pedagogy.		
UNIT I	INTRODUCTION AND METHODOLOGY		9
Aime and re	ationale, Policy background, Conceptual framework and terminology - Theories of		_
	urriculum, Teacher education - Conceptual framework, Research questions –		01
•	methodology and Searching.		
	methodology and ocaroning.		
			9
UNIT II	THEMATIC OVERVIEW		9
			g
Pedagogica	I practices are being used by teachers in formal and informal classrooms in	c	
Pedagogica		c	9 02
Pedagogica developing o	I practices are being used by teachers in formal and informal classrooms in	с	02
Pedagogica developing o	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.	c	02
Pedagogica developing o <b>UNIT III</b>	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.	c	02
Pedagogica developing o <b>UNIT III</b> Methodology	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.	c	02
Pedagogica developing o <b>UNIT III</b> Methodology education (o	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.           EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES           y for the in depth stage: quality assessment of included studies - How can teacher		02
Pedagogica developing o <b>UNIT III</b> Methodology education (o support effe	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.           EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES           y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best		02
Pedagogica developing o <b>UNIT III</b> Methodology education (o support effe for effective	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.           EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES           y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best ctive pedagogy? - Theory of change - Strength and nature of the body of evidence		02
Pedagogica developing o <b>UNIT III</b> Methodology education (o support effe for effective	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.           EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES           y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best ctive pedagogy? - Theory of change - Strength and nature of the body of evidence e pedagogical practices - Pedagogic theory and pedagogical approaches -		O2 9 03
Pedagogica developing of <b>UNIT III</b> Methodology education (of support effe for effective Teachers' at <b>UNIT IV</b>	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.  EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES  y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best ctive pedagogy? - Theory of change - Strength and nature of the body of evidence e pedagogical practices - Pedagogic theory and pedagogical approaches - ttitudes and beliefs and Pedagogic strategies.  REINCARNATION THROUGH VALUE EDUCATION		O2 9 03
Pedagogica developing of <b>UNIT III</b> Methodology education (of support effe for effective Teachers' at <b>UNIT IV</b> Professiona	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.  EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES  y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best ctive pedagogy? - Theory of change - Strength and nature of the body of evidence e pedagogical practices - Pedagogic theory and pedagogical approaches - titudes and beliefs and Pedagogic strategies.  REINCARNATION THROUGH VALUE EDUCATION I development: alignment with classroom practices and follow up support – Peer	c	O2 9 03
Pedagogica developing of <b>UNIT III</b> Methodology education (of support effe for effective Teachers' at <b>UNIT IV</b> Professional support - Su	I practices are being used by teachers in formal and informal classrooms in countries - Curriculum, Teacher education.  EVIDENCE ON THE EFFECTIVENESS OF PEDAGOGICAL PRACTICES  y for the in depth stage: quality assessment of included studies - How can teacher curriculum and practicum) and the school curriculum and guidance materials best ctive pedagogy? - Theory of change - Strength and nature of the body of evidence e pedagogical practices - Pedagogic theory and pedagogical approaches - ttitudes and beliefs and Pedagogic strategies.  REINCARNATION THROUGH VALUE EDUCATION	c	

UNIT V		RESE	EARC	H GA	PS AI	ND FU	JTUR	E DIF	RECTI	ONS								
Resear Disserr		•				gogy	- Tea	acher	educa	ation -	Curric	ulum a	ind asse	essment ·	co			
DISSEI	ination		esean										τοτα	L : 45 PE				
REFER		•												L.4JFC				
			$n \in (2)$	2001)		room	intora	otion	in Kor		rimony	school	c Comr	oare, 31 (	$2) \cdot 24$			
261.	15 J, F	laiuma	II F (2	.001)	01855	100111	IIILEIA		iii kei	nyan p	mary	SCHOOL	s, comp	ale, ST (	Z). Z4			
-				icular	reform	n in s	chool	ls: Th	e imp	ortanc	e of ev	aluatio	n, Jourr	nal of Cu	rriculu			
Studies	•			) Too	obor	troinir	na in	Char		1000 it	00110	10 Muli	i cito to	ochor or	lucatio			
researc	•	•	•				•				Courr	t iviuit	li-Sile le	acher eo	lucalic			
	• •	•			•	•					roving	teachir	ng and I	earning o	of bas			
		•			Does	s tea	cher	prepa	ration	o coun	it? Inte	ernatio	nal Jour	rnal Edu	cation			
Develo		• • •			and	nehen	iouv.	Intern	ations	al com	narisol	ns in ni	rimary A	ducation.	Ovfo			
and Bo		•		unure	anu	peuag	jogy.	men	ationa		pansoi		innary e	uucation.	<b>U</b> XIU			
COUR	SE OU	тсом	ES															
Upon o	omple	etion o	f the	cours	e, sti	Ident	s will	be al	ole to									
CO1	Unde	erstand	the r	netho	dolog	y of p	edago	ogy										
CO2	Unde	erstand	l Peda	adodic	al pra	actices	sused	d by te	eache	rs in fo	ormal a	nd info	informal classrooms in					
002		loping							baono					001001110				
CO3					educa	tion (	curric	ulum :	and p	racticu	m) and	the sc	chool cur	riculum a	and			
		ance m							-		,		e school curriculum and					
CO4	•	w the fa			•	•		•		•	t.							
CO5		tify the				•				•								
000	laon		11000			-		•										
	Т			IV	IAPPI	NG C		os vvi	IHPC	)s ANI	J PSO	S		RAM SP				
COs				PRC	OGRA	MOL	ITCO	MES	(POs)					COMES (				
003	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO			
CO1	-	-	-	-	-	-	-	-	-	-	-	1	-	-	-			
	-	-	-	-	-	-	-	-	-	-	-	1	-	-	-			
CO2	1	_	-	-	-	-	-	-	-	-	-	1	-	-	-			
CO2 CO3	-	-						1	1	1	1	1						
	-	-	-	-	-	-	-	-	-	-	-	1	-	-	-			

AD1004	STRESS MANAGEMENT BY YOGA	Ρ	С					
	2 0	0	0					
OBJECTIVE	ES							
• Dev	elop healthy mind in a healthy body thus improving social health also improve efficie	ency	,					
• Inve	ent Do's and Don't's in life through Yam							
Cate	egorize Do's and Don't's in life through Niyam							
• Dev	elop a healthy mind and body through Yog Asans							
• Inve	ent breathing techniques through Pranayam							
-								
Definitions o	of Eight parts of yog.( Ashtanga )	С	;O					
	YAM							
Do`s and Do	on't's in life.Shaucha, santosh, tapa, swadhyay, ishwarpranidhan	С	:0					
UNIT III	NIYAM							
Do`s and Do	Do`s and Don't's in life. Ahinsa, satya, astheya, bramhacharya and aparigraha		:0;					
	ASAN							
support - Si	I development: alignment with classroom practices and follow up support – Peer upport from the head teacher and the community - Curriculum and assessment – earning: limited resources and large class sizes		:04					

UNIT V		RESE	EARC	H GA	PS A	ND F	UTUR	E DIF	RECTI	ONS					
Decer	ah daa	lan	Conto	wto	Dodo	acau	Тос	obor	oduo	otion	Currio			aamaat	COS
Dissemi						igogy	- 165	acher	eauca	auon -	Cume	uium a	inu asse	essment ·	
Disseim	Παιιοι		esean		Jaci.								τοτα	L : 45 PE	
REFER	FNCF														
			auerin	na the	Inter	nal Na	ature"	by S	wami	Viveka	nanda	Adva	ita Δshr	ama (Pul	licatio
Departn			•	ig the	men			by O	wann	VIVERO	inanaa	, / 0/0			moation
•				p Tari	ning-F	Part-l"	' : Jan	ardar	ı Swai	mi Yog	abhya	si Man	dal, Nag	pur	
														•	
Upon c	omple	etion o	f the	cours	se, sti	udent	s will	be al	ble to						
CO1	Deve	elop he	althy	mind	in a h	ealthy	/ body	thus	impro	ving so	ocial h	ealth a	lso impro	ove efficie	ency
CO2	Learn Do's and Don't's in life through Yam														
CO3	Learn Do's and Don't's in life through Niyam														
CO4	Develop a healthy mind and body through Yog Asans														
CO5	Learn breathing techniques through Pranayam														
	MAPPING OF COs WITH POS AND PSOs														
													PROG	RAM SP	FCIEIC
COs				PRC	DGRA	MOU	JTCO	MES	(POs)	)				COMES (	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3
CO1	-	-	-	-	-	-	1	1	-	-	-	1	-	-	
CO2	-	-	-	_	-	-	1	1	-	-	-	1	-	-	-
CO3	-					_	1	1	-			1			
		-	-		-				-	-	-		-	-	-
CO4	-	-	-	-	-	-	1	1	-	-	-	1	-	-	-
CO5	-	-	-	-	-	-	1	1	-	-	-	1	-	-	-

AD1005	PERSONALITY DEVELOPMENT THROUGH LIFE         L         T	Ρ	С
	ENLIGHTENMENT SKILLS		
	2 0	0	0
OBJECTIVE	S		
	elop basic personality skills holistically		
	elop deep personality skills holistically to achieve happy goals		
	rite the responsibilities		
	ame a person with stable mind		
UNIT I	NEETISATAKAM-HOLISTIC DEVELOPMENT OF PERSONALITY - I		9
			1
Verses- 19,2	20,21,22 (wisdom) - Verses- 29,31,32 (pride & heroism) - Verses- 26,28,63,65		:01
(virtue)			
UNIT II	NEETISATAKAM-HOLISTIC DEVELOPMENT OF PERSONALITY - II		9
Verses- 52.5	i3,59 (dont's) - Verses- 71,73,75,78 (do's)	С	:02
,.			
UNIT III	ORGANS OF GOVERNANCE		9
			1
Shrimad Bh	agwad Geeta: Chapter 2-Verses 41, 47,48 - Chapter 3-Verses 13, 21, 27, 35	C	:03
Chapter6-Ve	erses 5,13,17,23, 35 - Chapter 18-Verses 45, 46, 48		.00
	EMERGENCY PROVISIONS		9
UNIT IV			
Statements	of basic knowledge - Shrimad Bhagwad Geeta: Chapter2-Verses 56, 62, 68	С	:04
Statements	of basic knowledge - Shrimad Bhagwad Geeta: Chapter2-Verses 56, 62, 68 /erses 13, 14, 15, 16,17, 18	С	:04

UNIT V		LOCA	AL AC	<b>MINI</b>	STRA	TION										9	
Chapte Verses			, Cha	apter :	3-Ver	ses 3	6,37,4	42 - (	Chapt	er 4-V	erses	18, 38		pter18 -			
													ΤΟΤΑ	L : 45 PE	RIOD	S	
REFER																	
•		ashtriy	'a Sar	nskrit	Sanst	thana	m P,	Bhart	rihari':	s Thre	eSatał	am , N	viti-sring	arvairagy	/a, Ne	W	
Delhi,20																	
		-	ananc	la ,	Srim	ad B	haga	vad	Gita,	Advai	ta As	hram,F	Publicatio	on Depa	artmen	t,	
Kolkata																	
COURS	SE OU	тсом	ES														
Upon c	omple	etion o	f the	cours	e, stı	Ident	s will	be al	ole to								
CO1	To d	evelop	basic	perso	onality	/ skills	s holis	tically	/								
CO2	To develop deep personality skills holistically to achieve happy goals																
CO3	To re	ewrite t	he res	spons	ibilitie	S											
CO4	To re	eframe	a per	son w	ith sta	able m	nind, p	oleasii	ng pei	rsonali	ty and	determ	ermination				
CO5	To a	waken	wisdo	om in s	stude	nts											
				N	APPI	NG O	F CO	s WI	ГН РС	)s AN[	D PSO	S					
													PROG	RAM SP	ECIFIC	C	
COs				PRC	OGRA	MOU	JTCO	MES	(POs)				OUTC	OMES (	PSOs)	)	
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3	3	
CO1	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO2	-		-	-	-		_	_	1	-	_	1		_			
		-													-		
CO3	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO4	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
									-								

AD1006	UNNAT BHARAT ABHIYAN	L	Т	Ρ	C
		2	0	0	0
OBJECTIVE	ES I I I I I I I I I I I I I I I I I I I				
• To e	engage the students in understanding rural realities				
• Toi	dentify and select existing innovative technologies, enable customization o	of te	chn	olog	ies
or d	evise implementation method for innovative solutions, as per the local needs	s.			
• To	leverage the knowledge base of the institutions to devise processes	s fo	or e	ffec	tiv
impl	ementation of various government programmes				
• Τοι	inderstand causes for rural distress and poverty and explore solutions for th	e sa	ame		
• To	apply classroom knowledge of courses to field realities and thereby imp	rov	e qu	uality	уc
lear	ning		-		
	QUALITY OF RURAL LIFE IN VILLAGES AND UNNAT BHARAT ABHI			- <b>-</b>	
	to Unnat Bharat Abhiyan - concept, scope and objectives, rural life, rural		•		
•	ender relations, rural values with respect to community, nature and res				
	of "Soul of India lies in villages" – (Gandhi Ji), Rural infrastructure, prob	lem	s in	С	:0 <sup>,</sup>
rural area.					
Assignment	Prepare a map (Physical, visual and digital) of the village you visited and v	write	e an		
essay about	inter-family relation in that village.				
UNIT II	RURAL ECONOMY AND LIVELIHOOD				
Agriculture,	farming, land ownership pattern, water management, animal husbandry, n	on-	farm	l	
ivelihoods a	nd artisans, rural entrepreneurs, rural market.				
Assignment	Describe your analysis of rural household economy, it's challenges and p	200	aibla		:0:
•	address them. Group discussion in class- (4) Field visit 3.	005	SIDIC		
	RURAL INSTITUTIONS				
	ural Development, Traditional rural organizations, Self Help Groups, Gram	<u>Su</u>	<u>arai</u>		
•					
	Panchayat Raj Institutions (Gram Sabha, Gram Panchayat, Standing Com				
	ciety, local administration. Introduction to Constitution, Constitutional Amen	um	ents	์   C	:0
n Panchaya	ti Raj – Fundamental Rights and Directive Principles. Panchayati Raj institutions in villages? What would you suggest to impro		4h a :-		
Accianmant					

UNIT IV	RURAL DEVELOPMENT PROGRAMMES	9
National prog	rammes - Sarva Shiksha Abhiyan, Beti Bachao, Beti Padhao, Ayushman Bharat,	
Swatchh Bha	at, PM Awass Yojana, Skill India, Gram Panchayat Decentralised Planning,	
NRLM, MNRE	GA, etc.	_
	nment: Describe the benefits received and challenges faced in the delivery of one	CO4
of these prog	ammes in the rural community, give suggestions about improving implementation	
of the prograr	nme for the rural poor.	
UNIT V	FIELD WORK	9
Each student	selects one programme for field visit Field based practical activities:	
Interaction v	vith SHG women members, and study of their functions and challenges; planning	
for their skill b	uilding and livelihood activities	
• Visit MGNF	REGS project sites, interact with beneficiaries and interview functionaries at the	
work site		
• Field visit	to Swachh Bharat project sites, conduct analysis and initiate problem solving	
measures		
Conduct	Aission Antyodaya surveys to support under Gram Panchayat Development	
Plan(GPDP)		
Interactive c	ommunity exercise with local leaders, panchayat functionaries, grass-root officials	
and local insti	tutions regarding village development plan preparation and resource mobilization	
Visit Rural S	Schools I mid-day meal centres, study Academic and infrastructural resources and	
gaps		0.05
Participate i	n Gram Sabha meetings, and study community participation	CO5
Associate	with Social audit exercises at the Gram Panchayat level, and interact with	
programme b	eneficiaries	
Attend Pare	nt Teacher Association meetings, and interview school drop outs	
Visit local Ar	nganwadi Centre and observe the services being provided	
• Visit local N	GOs, civil society organisations and interact with their staff and beneficiaries.	
• Organize av	vareness programmes, health camps, Disability camps and cleanliness camps o	
Conduct soil I	nealth test, drinking water analysis, energy use and fuel efficiency surveys	
Raise under	standing of people's impacts of climate change, building up community's disaster	
preparedness		
Organise o	rientation programmes for farmers regarding organic cultivation, rational use of	
irrigation and	fertilizers and promotion of traditional species of crops and plants • Formation of	
committees fo	or common property resource management, village pond maintenance and fishing.	
	TOTAL : 45 PEF	RIODS
I		

Text Bo	ooks:														
1 Sin	igh, Ka	atar, R	ural D	Develo	pmer	nt Prir	nciples	s, Pol	icies	and M	anage	ment,	Sage Pu	ublication	s, New
Delhi, 2	015														
2.A Hai	nd boo	ok on ∖	∕illage	Pan	chaya	it Adn	ninistr	ation,	Rajiv	Gand	lhi Cha	air for	Panchay	ati Raj S	Studies,
2002															
3.United	d Natic	ons, Su	istaina	able D	evelo	pmen	t Goa	ıls, 20	15 un	.org/sc	lgs				
Referer	nce Bo	ooks:													
1.	M.P.B	oraian,	Best	Practi	ices ir	n Rura	al Dev	elopn	nent, S	Shanla	x Publ	ishers			
2.	Unnat	Bharat	t Abhi	yan W	/ebsit	e:ww	/w.un	natbh	aratat	bhiyan.	gov.in				
COURS										-	-				
Upon c	omple	tion o	f the	cours	e. sti	Ident	s will	be at	ole to						
CO1	•				•					oplition					
	Able to understand of rural life, culture and social realities Able to understand the concept of measurement by comparison or balance of parameters.														
CO2						•									ers.
CO3	Able	to dev	elop a	a sens	e of e	empat	hy an	d bon	ds of I	mutual	ity with	n local	commun	ity	
CO4	Able	to app	reciat	e sigr	nifican	t cont	ributio	ons of	local	comm	unities	to Ind	ian socie	ety and	
	econ	omy													
CO5	Lear	ned to	value	the lo	ocal kr	nowle	dge a	nd wi	sdom	of the	comm	unity			
	1			Μ	APPI	NG O	F CO	s WIT	Н РО	s ANC	PSO:	S			
									(DO-)				PROG	RAM SP	ECIFIC
COs				PRC	JGRA				(POs)				OUTC	OMES (	PSOs)
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
CO2	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
CO3	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
CO4	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

CO5

AD1007	ESSENCE OF INDIAN KNOWLEDGE TRADITION	-	Т	Ρ	C
	2	2	0	0	0
OBJECTIVE	S				
• Get a	a knowledge about Indian Culture				
• Knov	w Indian Languages and Literature religion and philosophy and the fine arts i	in In	idia		
• Expl	ore the Science and Scientists of Ancient, Medieval and Modern India				
• Unde	erstand education systems in India				
UNIT I	INTRODUCTION TO CULTURE				
	ization, culture and heritage, general characteristics of culture, importar man literature, Indian Culture, Ancient India, Medieval India, Modern India	nce	of	c	;0 <sup>,</sup>
UNIT II	INDIAN LANGUAGES AND LITERATURE			1	!
-	uages and Literature – I: Languages and Literature of South India, – and Literature – II: Northern Indian Languages & Literature	Ind	lian	С	:02
UNIT III	RELIGION AND PHILOSOPHY				
	ns practiced in India and Understanding their Philosophy – religious movem a (Selected movements only)	ent	s in	c	:0:
UNIT IV FINE ARTS IN INDIA (ART, TECHNOLOGY& ENGINEERING)			9		
music, Danc	ing, Indian handicrafts, Music, divisions of Indian classic music, modern e and Drama, Indian Architecture (ancient, medieval and modern), Science n India, development of science in ancient, medieval and modern India				:04

# UNIT V EDU

# EDUCATION SYSTEM IN INDIA

Education in ancient, medieval and modern India, aims of education, subjects, languages, Science and Scientists of Ancient India, Science and Scientists of Medieval India, Scientists of Modern India

**TOTAL : 45 PERIODS** 

9

# REFERENCE:

1. . Kapil Kapoor, "Text and Interpretation: The India Tradition", ISBN: 81246033375, 2005

2. "Science in Samskrit", Samskrita Bharti Publisher, ISBN 13: 978-8187276333, 2007

3. NCERT, "Position paper on Arts, Music, Dance and Theatre", ISBN 81-7450 494-X, 200

4. Narain, "Examinations in ancient India", Arya Book Depot, 1993

5. Satya Prakash, "Founders of Sciences in Ancient India", Vijay Kumar Publisher, 1989

6. M. Hiriyanna, "Essentials of Indian Philosophy", Motilal Banarsidass Publishers, ISBN 13: 978-8120810990, 2014

### **COURSE OUTCOMES**

CO5

### Upon completion of the course, students will be able to

CO1	Understand philosophy of Indian culture.
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CO2 Distinguish the Indian languages and literature.

CO3 Learn the philosophy of ancient, medieval and modern India.

CO4 Acquire the information about the fine arts in India.

### Know the contribution of scientists of different eras.

#### MAPPING OF COs WITH POS AND PSOs

COs	PROGRAM OUTCOMES (POs)													PROGRAM SPECIFIC OUTCOMES (PSOs)			
	PO1	PO2	PO3	PO4	PO5	PO6	P07	PO8	PO9	PO10	P011	PO12	PSO1	PSO2	PSO3		
CO1	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO2	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO3	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO4	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		
CO5	-	-	-	-	-	-	-	-	1	-	-	1	-	-	-		

AD1008	SANGA TAMIL LITERATURE APPRECIATION	٦	Т	Ρ	С
	2	C	)	0	0
OBJECTIVI	ES				
The main le	arning objective of this course is to make the students an appreciation for:				
• 1. Ir	ntroduction to Sanga Tamil Literature.				
• 2.'A	gathinai' and 'Purathinai' in SangaTamil Literature.				
• 3.'A	ttruppadai' in SangaTamil Literature.				
• 4.'P	uranaanuru' in SangaTamil Literature.				
• 5.'P	athitrupaththu' in SangaTamil Literature.				
	SANGA TAMIL LITERATURE – AN INTRODUCTION				9
_iterature-S	to Tamil Sangam–History of Tamil Three Sangams–Introduction to Tamil Sa Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra	•		с	; <b>O</b> 1
Literature–S Tamil Sanga	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra	•		c	•
Literature–S Tamil Sanga	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra	•		c	•
Literature–S Tamil Sanga <b>UNIT II</b>	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables. <b>'AGATHINAI'AND'PURATHINAI'</b>	mm	ar		:01 
Literature–S Tamil Sanga <b>UNIT II</b> Tholkappiya	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra	mm	ar		Ş
₋iterature–S Tamil Sanga <b>JNIT II</b> Tholkappiya Culture from	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables. (AGATHINAI'AND'PURATHINAI' r's Meaningful Verses-Three literature materials-Agathinai's message- Hist	mm	ar		:02
Literature–S Tamil Sanga UNIT II Tholkappiya Culture from UNIT III	pecial Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables.  (AGATHINAI'AND'PURATHINAI'  r's Meaningful Verses–Three literature materials–Agathinai's message- Hist Agathinai– Purathinai–Classification–Mesaage to Society from Purathinai.  (ATTRUPPADAI'.	ory	of	c	€ 202
Literature–S Tamil Sanga UNIT II Tholkappiya Culture from UNIT III	pecial Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables. <b>'AGATHINAI'AND'PURATHINAI'</b> r's Meaningful Verses–Three literature materials–Agathinai's message- Hist Agathinai– Purathinai–Classification–Mesaage to Society from Purathinai. <b>'ATTRUPPADAI'.</b> Literature–Attruppadaiin'Puranaanuru'-Attruppadaiin'Pathitrupaththu'-Attruppa	ory	of	c	•
∟iterature–S Tamil Sanga UNIT II Tholkappiya Culture from UNIT III Attruppadail Paththupaa	pecial Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables. <b>'AGATHINAI'AND'PURATHINAI'</b> r's Meaningful Verses–Three literature materials–Agathinai's message- Hist Agathinai– Purathinai–Classification–Mesaage to Society from Purathinai. <b>'ATTRUPPADAI'.</b> Literature–Attruppadaiin'Puranaanuru'-Attruppadaiin'Pathitrupaththu'-Attruppa	ory	of	c	€ 202
Literature–S Tamil Sanga UNIT II Tholkappiya Culture from UNIT III Attruppadail	Special Branches in Tamil Sangam Literature- Tamil Sangam Literature's Gra am Literature's parables.          'AGATHINAI'AND'PURATHINAI'         r's Meaningful Verses–Three literature materials–Agathinai's message- Hist of Agathinai– Purathinai–Classification–Mesaage to Society from Purathinai.         'ATTRUPPADAI'.         Literature–Attruppadaiin'Puranaanuru'-Attruppadaiin'Pathitrupaththu'-Attruppa ttu'.         'PURANAANURU'	ory	of	c	:02 :03

UNIT V		<b>'PATI</b>	HITRU	JPAT	HTHU	J'									
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													ΤΟΤΑ	L : 45 PE	
REFER															
1 Siva	araja P	illai, Th	ne Ch	ronolo	ogy of	theEa	rlyTa	mils,S	agwa	nPress	3,2018				
2. Hank	Heifet	z andG	eorge	eL. Ha	art, Th	e Pur	ananı	uru,Pe	enguir	n Book	s,2002				
3. Kam	il Zvele	bil, Th	e Smi	le of I	Murug	jan: O	nTarr	nil Lite	rature	e of So	uth Inc	lia, Bril	I Acaden	nic Pub,1	997.
4. Geo	rgeL. I	Hart, P	oetsc	of the	Tamil	Anth	ologie	es: Ar	cient	Poems	ofLove	andW	/ar, Prin	ceton Ur	niversit
Press,2	2015.														
5. Xavi	erS.Th	ani Na	iyagai	m, La	ndsca	ape a	nd po	etry:	a stu	dy of r	nature	in clas	sical Ta	imil poet	ry, Asi
Pub.Ho	ouse, 19	967.													
COURS	SE OU	ГСОМ	ES												
Upon c	omple	tion o	fthe	cours	e, stu	udent	s will	be a	ole to						
CO1	Appr	eciate	and a	pply t	he me	essag	es in l	Sanga	a Tam	il Liter	ature i	n their	life.		
CO2	Diffe	rentiate	e 'Aga	thina	' and	'Pura	thinai	' in the	eir per	sonal	and so	cietal I	ife.		
CO3	Appr	eciate	and a	pply t	he me	essag	es in'	Attru	opada	i' in the	eir pers	sonal a	nd socie	tal life.	
	Appreciate and apply the messages in' Attruppadai' in their personal and societal life.           Appreciate and apply the messages in' Puranaanuru' in their personal and societal life.												and soc	ietal life.	
CO4	1 YPP	coluto			h a 1994	essag	es in'	Pathi	trupat	hthu' ii	n their	person	al and s	ocietal lif	۵
CO4 CO5			and a	pply t	ne me										<b>.</b>
			and a			NG C	F CO	s Wl	ГН РС	)s ANI	D PSO	s			0.
			and a	N	IAPPI						D PSO	S	PROG	RAM SP	
			and a	N	IAPPI				TH PC (POs)		D PSO	S		RAM SP COMES (	ECIFI
CO5			and a	N	IAPPI						PSO PO11	S PO12			ECIFI
CO5	Appr	eciate		PRC	IAPPI OGRA	MOL	лсо	MES	(POs)			1	Ουτα	OMES (	ECIFI( PSOs)
CO5	P01	eciate	PO3	PRC PRC	IAPPI OGRA P05	M OU P06	JTCO PO7	MES PO8	(POs) P09	PO10	P011	P012	OUTC PSO1	PSO2	ECIFIC PSOs) PSO3
CO5 COs CO1	P01	eciate	P03 -	PRC PRC	IAPPI OGRA P05	PO6 -	JTCO P07 -	MES P08 -	(POs) PO9 -	<b>PO10</b>	P011 -	PO12	OUTC PSO1	PSO2	ECIFIC PSOs) PSO3
CO5 COs CO1 CO2	Appr           P01           -           -           -	PO2 -	P03 - -	PRC PRC	IAPPI OGRA P05	M OL PO6 - -	<b>JTCO</b> P07 -	MES P08 -	(POs) PO9 - -	<b>PO10</b> 1 1	P011 - -	PO12 1 1	OUTC PSO1 - -	<b>PSO2</b> - -	ECIFIC PSOs) PSO3 -
CO5 COs CO1 CO2 CO3	Appr           P01           -           -           -	PO2 - - -	PO3 - -	PRC PO4 - -	IAPPI DGRA PO5 - - -	M OL PO6 - - -	P07 - - -	MES P08	(POs) PO9 - - -	PO10 1 1 1	P011 - -	PO12 1 1 1	OUTC PS01 - - -	COMES ( PSO2 - - -	ECIFIC PSOs) PSO3 - - -